

# What portion of the Americans relied on others' satisfaction when deciding to take the COVID-19 vaccination?

Azadeh Aghaeeyan

Department of  
Mathematics and Statistics  
Brock University

Supervisors:  
Pouria Ramazi & Mark Lewis

# Introduction

# Vaccination coverage

- Vaccination is a key to achieve a desired public health status.
- Achieving **timely high enough vaccination coverage** is important.
- High vaccination coverage requires high vaccine acceptance.
- Vaccine acceptance is the collective outcome of the individuals' decision-making processes.

# Vaccination coverage

- Vaccination is a key to achieve a desired public health status.
- Achieving **timely high enough vaccination coverage** is important.
- High vaccination coverage requires high vaccine acceptance.
- Vaccine acceptance is the collective outcome of the individuals' decision-making processes.

**When it came to COVID-19 vaccination, how did people decide whether to get immunized?**

# Success-based learners & myopic rationalists

- In some contexts<sup>1,2</sup>, people are assumed/reported to be mainly one of the followings:
- **Success-based learners (imitators)**: who follow the decisions of the perceived most satisfied (successful) individuals in the population;
- **Myopic rationalists (influentials)**: who take the action that maximizes their instant perceived payoff.

<sup>1</sup>Van den Bulte, C., & Joshi, Y. V. (2007). New product diffusion with influentials and imitators. *Marketing science*, 26(3), 400-421.

<sup>2</sup>Molleman, L., Van den Berg, P., & Weissing, F. J. (2014). Consistent individual differences in human social learning strategies. *Nature Communications*, 5(1), 3570.

# Success-based learners & myopic rationalists

- In some contexts<sup>1,2</sup>, people are assumed/reported to be mainly one of the followings:
- **Success-based learners (imitators)**: who follow the decisions of the perceived most satisfied (successful) individuals in the population;
- **Myopic rationalists (influentials)**: who take the action that maximizes their instant perceived payoff.
- In the context of vaccination, a large body of studies assumed either of these two types of decision-makers<sup>3</sup>.

<sup>1</sup>Van den Bulte, C., & Joshi, Y. V. (2007). New product diffusion with influentials and imitators. *Marketing science*, 26(3), 400-421.

<sup>2</sup>Molleman, L., Van den Berg, P., & Weissing, F. J. (2014). Consistent individual differences in human social learning strategies. *Nature Communications*, 5(1), 3570.

# Success-based learners & myopic rationalists

- In some contexts<sup>1,2</sup>, people are assumed/reported to be mainly one of the followings:
- **Success-based learners (imitators)**: who follow the decisions of the perceived most satisfied (successful) individuals in the population;
- **Myopic rationalists (influentials)**: who take the action that maximizes their instant perceived payoff.
- In the context of vaccination, a large body of studies assumed either of these two types of decision-makers<sup>3</sup>.

---

<sup>1</sup>Van den Bulte, C., & Joshi, Y. V. (2007). New product diffusion with influentials and imitators. *Marketing science*, 26(3), 400-421.

<sup>2</sup>Molleman, L., Van den Berg, P., & Weissing, F. J. (2014). Consistent individual differences in human social learning strategies. *Nature Communications*, 5(1), 3570.

<sup>3</sup>Bauch, C. T., & Bhattacharyya, S. (2012). Evolutionary game theory and social learning can determine how vaccine scares unfold. *PLoS computational biology*, 8(4), e1002452.

# Success-based learners & myopic rationalists

- The two types of decision makers also differ in the type of information they attend to<sup>4</sup>.

---

<sup>4</sup>van den Berg, P., Molleman, L., & Weissing, F. J. (2015). Focus on the success of others leads to selfish behavior. *PNAS*, 112(9), 2912-2917.



# Success-based learners & myopic rationalists

- The two types of decision makers also differ in the type of information they attend to<sup>4</sup>.
- Myopic rationalists seek information that shapes their payoffs<sup>5</sup>.

---

<sup>4</sup>van den Berg, P., Molleman, L., & Weissing, F. J. (2015). Focus on the success of others leads to selfish behavior. *PNAS*, 112(9), 2912-2917.

<sup>5</sup>Van den Bulte, C., & Joshi, Y. V. (2007). New product diffusion with influentials and imitators. *Marketing science*, 26(3), 400-421.

# Success-based learners & myopic rationalists

- The two types of decision makers also differ in the type of information they attend to<sup>4</sup>.
- Myopic rationalists seek information that shapes their payoffs<sup>5</sup>.
- Success-based learners focus on the satisfaction achieved by others<sup>6</sup>.

---

<sup>4</sup>van den Berg, P., Molleman, L., & Weissing, F. J. (2015). Focus on the success of others leads to selfish behavior. *PNAS*, 112(9), 2912-2917.

<sup>5</sup>Van den Bulte, C., & Joshi, Y. V. (2007). New product diffusion with influentials and imitators. *Marketing science*, 26(3), 400-421.

<sup>6</sup>McElreath, R. et al. (2008). Beyond existence and aiming outside the laboratory: estimating frequency-dependent and pay-off-biased social learning strategies. *Philos. Trans. R. Soc., B, Biol. Sci*, 363(1509), 3515-3528.

# Success-based learners & myopic rationalists

- The two types of decision makers also differ in the type of information they attend to<sup>4</sup>.
- Myopic rationalists seek information that shapes their payoffs<sup>5</sup>.
- Success-based learners focus on the satisfaction achieved by others<sup>6</sup>.
- Hence, knowing the proportion of the two types may inform health management and media about more tailored vaccine promotion communication strategies.

---

<sup>4</sup>van den Berg, P., Molleman, L., & Weissing, F. J. (2015). Focus on the success of others leads to selfish behavior. *PNAS*, 112(9), 2912-2917.

<sup>5</sup>Van den Bulte, C., & Joshi, Y. V. (2007). New product diffusion with influentials and imitators. *Marketing science*, 26(3), 400-421.

<sup>6</sup>McElreath, R. et al. (2008). Beyond existence and aiming outside the laboratory: estimating frequency-dependent and pay-off-biased social learning strategies. *Philos. Trans. R. Soc., B, Biol. Sci*, 363(1509), 3515-3528.

# Success-based learners & myopic rationalists

- The two types of decision makers also differ in the type of information they attend to<sup>4</sup>.
- Myopic rationalists seek information that shapes their payoffs<sup>5</sup>.
- Success-based learners focus on the satisfaction achieved by others<sup>6</sup>.
- Hence, knowing the proportion of the two types may inform health management and media about more tailored vaccine promotion communication strategies.

**When it came to COVID-19 vaccination, what population proportion of people behaved as Myopic rationalists ( $\alpha$ )?**

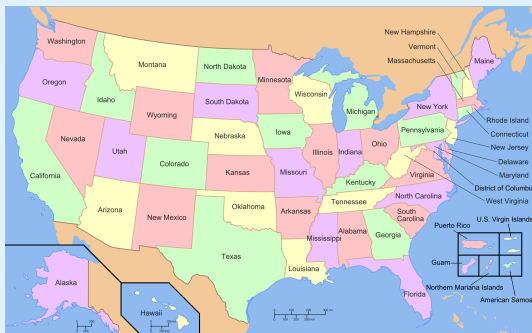
<sup>4</sup>van den Berg, P., Molleman, L., & Weissing, F. J. (2015). Focus on the success of others leads to selfish behavior. *PNAS*, 112(9), 2912-2917.

<sup>5</sup>Van den Bulte, C., & Joshi, Y. V. (2007). New product diffusion with influentials and imitators. *Marketing science*, 26(3), 400-421.

<sup>6</sup>McElreath, R. et al. (2008). Beyond existence and aiming outside the laboratory: estimating frequency-dependent and pay-off-biased social learning strategies. *Philos. Trans. R. Soc., B, Biol. Sci*, 363(1509), 3515-3528.

## Goal

To estimate the proportion of myopic rationalists in each US state, including D.C., when deciding whether to take the first dose of a COVID-19 vaccine



(Wikipedia)

# Model Formulation

## The excess payoff of vaccination

$$\Delta\pi(t) = \pi_v - \pi_{\bar{v}}$$

$\pi_{\bar{v}}$  (resp.  $\pi_v$ ): the perceived benefit of remaining unvaccinated (getting a dose of a COVID-19 vaccine),

## The excess payoff of vaccination

$$\Delta\pi(t) = \pi_v - \pi_{\bar{v}}$$

$\pi_{\bar{v}}$  (resp.  $\pi_v$ ): the perceived benefit of remaining unvaccinated (getting a dose of a COVID-19 vaccine),

## Population structure

- For each state, we have a large-enough, fixed-size, and well-mixed population,
- $N$ : Number of people aged 12 and above,
- $N_n : (N - VR)$ : Number of *non vaccine-refusers*,
- $\alpha_1 N_n$ : Number of Myopic rationalists,
- $(1 - \alpha_1) N_n$ : Number of Success-based learners.
- $\alpha : \alpha_1 \frac{N_n}{N}$



- $M(t)$  (resp.  $L(t)$ ): Number of vaccinated myopic rationalists (resp. success-based learners)

- $M(t)$  (resp.  $L(t)$ ): Number of vaccinated myopic rationalists (resp. success-based learners)
- $M_s(t)$  (resp.  $L_s(t)$ ): Number of unvaccinated myopic rationalists (resp. success-based learners) who are vaccine-seeker

$$M_s(t) = (\alpha_1 N_n - M(t))\mathbf{1}(\Delta\pi(t)),$$

$$M_s(t) = (\alpha_1 N_n - M(t)) \mathbf{1}(\Delta\pi(t)),$$

$$L_s(t) = ((1 - \alpha_1)N_n - L(t)) \frac{L(t) + M(t)}{N} \sigma \max\{0, \Delta\pi(t)\},$$

$$M_s(t) = (\alpha_1 N_n - M(t)) \mathbf{1}(\Delta\pi(t)),$$

$$L_s(t) = ((1 - \alpha_1)N_n - L(t)) \frac{L(t) + M(t)}{N} \sigma \max\{0, \Delta\pi(t)\},$$

$$\underbrace{\dot{i}(t)}_{\text{rate of change of vaccinated of class } i} = \kappa \underbrace{i_s(t) \min\left\{1, \frac{v(t) - L(t) - M(t)}{L_s(t) + M_s(t)}\right\}}_{\substack{\text{\# of vaccine-seekers} \\ \text{of class } i \text{ who} \\ \text{can get a vaccine}}}, \quad i = L, M.$$

$$\Delta\pi(t) = C_{\bar{v}} - C_v(t) + C_d \frac{D(t)}{N} + C_i \frac{I(t)}{N},$$

- $C_{\bar{v}}$  (resp.  $C_v$ ): the perceived risk of remaining unvaccinated (getting a dose of COVID-19 vaccine) in a disease-free situation,
- $C_i$  (resp.  $C_d$ ): the perceived cost reduction in morbidity (mortality) due to contracting COVID-19 obtained from a dose of a COVID-19 vaccine,
- $D(t)$  (resp.  $I(t)$ ): number of newly confirmed deaths due to COVID-19 (resp. cases of COVID-19 infection),
- $N$ : total population.

$$\Delta\pi(t) = C_{\bar{v}} - c_{v0}(t - t_0 + 1)^\lambda + 1 \frac{D(t)}{N} + C_i \frac{I(t)}{N}$$

$$M_s(t) = (\alpha_1 N_n - M(t)) \mathbf{1}(\Delta\pi(t)),$$

$$L_s(t) = ((1 - \alpha_1) N_n - L(t)) \frac{L(t) + M(t)}{N} \sigma \max\{0, \Delta\pi(t)\},$$

$$\dot{i}(t) = \kappa i_s(t) \min\left\{1, \frac{v(t) - L(t) - M(t)}{L_s(t) + M_s(t)}\right\}, \quad i = L, M.$$

- $\lambda < 0$  was estimated using the experimental Household Pulse Survey.
- $t_0$ : date of roll-out of COVID-19 vaccine.

## Fitting phase

optimization:  $\min_{\underline{\theta}} \sum_i (e(t_i))^2$

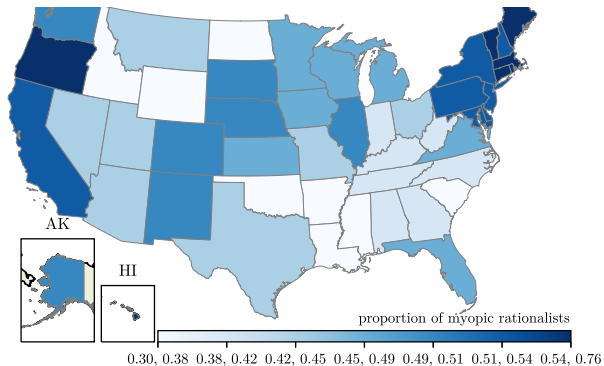
$$e(t_i) = \underbrace{\tilde{n}_v(t_i)}_{n_v(t_i) - n_v(t_{i-1})} - \underbrace{\tilde{n}_v(t_i, \underline{\theta})}_{\Delta M(t_i) + \Delta L(t_i)}, \quad (1)$$

where  $\underline{\theta} = (\kappa, \alpha_1, C_{\bar{v}}, c_{v0}, C_i, \sigma)$ .

- Optimization algorithm: Simulated Annealing approach



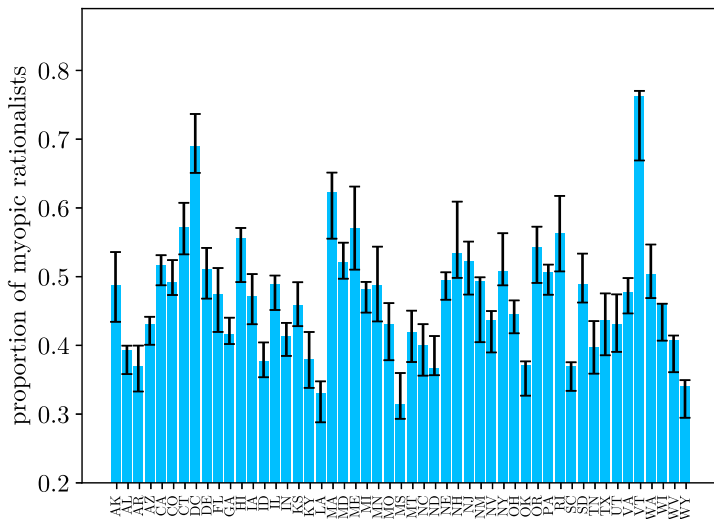
# Proportion of myopic rationalists, $\alpha = \alpha_1 N_n / N$



- Are we sure about the results?

- Are we sure about the results?
- What do we mean by “being sure”?

- Are we sure about the results?
- What do we mean by “being sure”?



- Are we sure about the results?
- What do we mean by “being sure”?
- Is it possible that the data could be fitted by other values of  $\alpha$ 's, equally well?

- Are we sure about the results?
- What do we mean by “being sure”?
- Is it possible that the data could be fitted by other values of  $\alpha$ 's, equally well?

→ **Identifiability**

# Identifiability

Consider the following reference state space model  $\Sigma_\theta$

$$\Sigma_\theta \begin{cases} \dot{x}(t) = f_\theta(x(t), u(t)), \\ y(t) = h_\theta(x(t), u(t)), \end{cases}$$

where

- $x(t) \in \mathcal{X} \subseteq \mathbf{R}^n$  is the state vector,
- $u(t) \in \mathcal{U} \subseteq \mathbf{R}^m$  is the input vector,
- $y(t) \in \mathcal{Y} \subseteq \mathbf{R}^p$  is the output vector,
- $\theta \in \Theta \subseteq \mathbf{R}^l$  is the parameter vector.



Consider the following reference state space model  $\Sigma_\theta$

$$\Sigma_\theta \begin{cases} \dot{x}(t) = f_\theta(x(t), u(t)), \\ y(t) = h_\theta(x(t), u(t)), \end{cases}$$

where

- $x(t) \in \mathcal{X} \subseteq \mathbf{R}^n$  is the state vector,
- $u(t) \in \mathcal{U} \subseteq \mathbf{R}^m$  is the input vector,
- $y(t) \in \mathcal{Y} \subseteq \mathbf{R}^p$  is the output vector,
- $\theta \in \Theta \subseteq \mathbf{R}^l$  is the parameter vector.

Now consider the emulated state space model  $\Sigma'_{\hat{\theta}}$

$$\Sigma'_{\hat{\theta}} \begin{cases} \dot{x}'(t) = f_{\hat{\theta}}(x'(t), u(t)), \\ y'(t) = h_{\hat{\theta}}(x'(t), u(t)). \end{cases}$$

Consider the following reference state space model  $\Sigma_\theta$

$$\Sigma_\theta \begin{cases} \dot{x}(t) = f_\theta(x(t), u(t)), \\ y(t) = h_\theta(x(t), u(t)), \end{cases}$$

where

- $x(t) \in \mathcal{X} \subseteq \mathbf{R}^n$  is the state vector,
- $u(t) \in \mathcal{U} \subseteq \mathbf{R}^m$  is the input vector,
- $y(t) \in \mathcal{Y} \subseteq \mathbf{R}^p$  is the output vector,
- $\theta \in \Theta \subseteq \mathbf{R}^l$  is the parameter vector.

Now consider the emulated state space model  $\Sigma'_{\hat{\theta}}$

$$\Sigma'_{\hat{\theta}} \begin{cases} \dot{x}'(t) = f_{\hat{\theta}}(x'(t), u(t)), \\ y'(t) = h_{\hat{\theta}}(x'(t), u(t)). \end{cases}$$

### Definition

The parameter  $\theta^i$  is *structurally globally identifiable* if for almost all  $\theta \in \Theta$

$$y(u(t), \theta) = y'(u(t), \hat{\theta}) \Rightarrow \hat{\theta}^i = \theta^i.$$

## Inputs and the outputs

$$\begin{aligned}
 M_s(t) &= (\alpha_1 N_n - x_2(t)) \mathbf{1}\left(\frac{1}{\sigma} \sum_{i=0}^{i=3} c_i u_i(t)\right), \\
 L_s(t) &= ((1 - \alpha_1) N_n - x_1(t)) \frac{x_1(t) + x_2(t)}{N} \max\left\{0, \sum_{i=0}^{i=3} c_i u_i(t)\right\}, \\
 \dot{x}_1(t) &= \kappa L_s(t) \min\left\{1, \frac{u_4(t) - x_1(t) - x_2(t)}{L_s(t) + M_s(t)}\right\}, \\
 \dot{x}_2(t) &= \kappa M_s(t) \min\left\{1, \frac{u_4(t) - x_1(t) - x_2(t)}{L_s(t) + M_s(t)}\right\}, \\
 y(t) &= x_1(t) + x_2(t)
 \end{aligned} \tag{2}$$

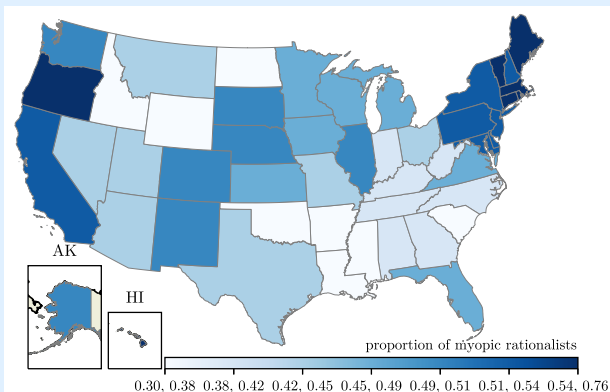
- $\Delta\pi(t) = \sum_{i=0}^{i=3} c_i u_i(t)$ , where
  - $c_0 = \sigma C_{\bar{v}}$ ,  $c_1 = \sigma c_{v0}$ ,  $c_2 = \sigma \frac{C_i}{N}$ ,  $c_3 = \frac{\sigma}{N}$ .
  - $u_0 = 1$ ,  $u_1(t) = (t - t_0 + 1)^\lambda$ ,  $u_3(t) = D(t)$ ,  $u_2(t) = I(t)$ .
- $u_4(t) = v(t)$ ;  $L(t)$  (resp.  $M(t)$ ) is denoted by  $x_1(t)$  (resp.  $x_2(t)$ ).

## Proposition

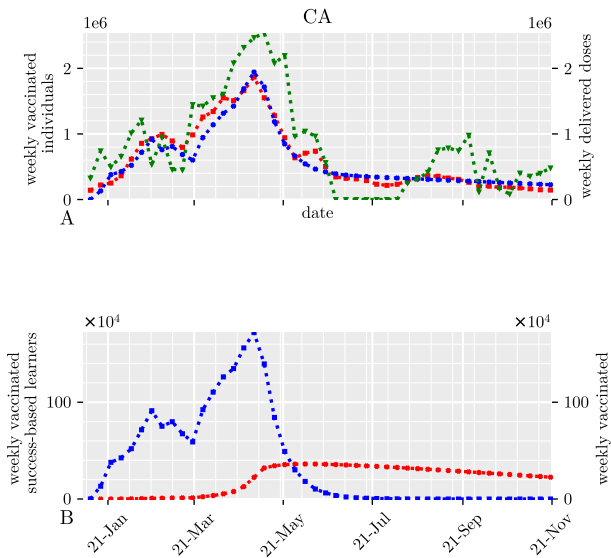
*The parameters  $\kappa, \alpha_1, C_i, C_{\bar{v}}, c_{v_0}, \sigma$  of the dynamical system (2) with single output  $y(t)$ , and five inputs,  $u_i, i = 0, \dots, 4$  are uniquely identifiable provided that some assumptions hold.*

# Results

## Proportion of myopic rationalists, $\alpha = \alpha_1 N_n / N$



- The nationwide estimated proportion of myopic rationalists was 47%.
- There was a high degree of variation across the 51 jurisdictions, i.e., 31% for Mississippi to 76% for Vermont.



**Table:** Linear correlation between explanatory variables and the estimated proportion of myopic rationalists.

<b>Predictor variable</b>	<b>Pearson-r</b>	<b>r-squared</b>
Vaccination coverage	0.87	0.76
Proportion of votes in favor of Democrats	0.82	0.68
Education score	0.74	0.54



# Conclusion

- We considered vaccination coverage as a collective outcome resulting from decisions of individuals where we assumed are mainly either myopic rationalists or success-based learners.

- We considered vaccination coverage as a collective outcome resulting from decisions of individuals where we assumed are mainly either myopic rationalists or success-based learners.
- We found that 47% of Americans behaved as myopic rationalists and 47% as success-based learners.

- We considered vaccination coverage as a collective outcome resulting from decisions of individuals where we assumed are mainly either myopic rationalists or success-based learners.
- We found that 47% of Americans behaved as myopic rationalists and 47% as success-based learners.
- We proved that the proportion of myopic rationalists is identifiable, and the obtained narrow confidence intervals supported the validity of the estimated values.

- We considered vaccination coverage as a collective outcome resulting from decisions of individuals where we assumed are mainly either myopic rationalists or success-based learners.
- We found that 47% of Americans behaved as myopic rationalists and 47% as success-based learners.
- We proved that the proportion of myopic rationalists is identifiable, and the obtained narrow confidence intervals supported the validity of the estimated values.
- Hopefully, the approach may be useful for health management and guide tailored communication towards promoting vaccination uptake.

# Acknowledgments



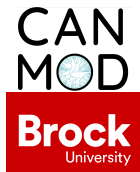
Pouria Ramazi

Department of Mathematics and Statistics  
Brock University



Mark Lewis

Department of Mathematical and Statistical Sciences  
Department of Biological Sciences  
University of Victoria



Thank you!