

# Worst Case Complexity of Solving (Structured) Linear Systems

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March 6, 2023

BIRS Workshop on Complexity of Matrix Computations

# Solving Systems of Linear Equations

- Input:
  - n-by-n matrix **A** with m non-zeros
  - vector **b**
- Output **x** such that **Ax = b**
- Goal: design an algorithm whose worst case complexity as function of size of **A** & output error tolerance is small

# Worst Case analysis

- Why? Linear solvers are often used as inner loops:
  - Preconditioning
  - Use in inner loop
  - Complexity-theoretic reductions

# Parameterizing the complexity of $\mathbf{Ax} = \mathbf{b}$

- Model: exact arithmetic, bit complexity, low memory, distributed
- Output: norm bound, entry-wise, eigenvector, determinant
- Representation of numbers: finite field, fractions, rounding

# Assumptions on $A$

- Symmetry
- Small condition number
- Low rank
- Low factor width: graph Laplacians, finite element methods
- Displacement structure: Toeplitz/Hankel, hierarchical
- Geometric correspondence

# Some rather strange worst-case complexities

- Krylov space methods: over finite fields/exact arithmetic, sparse linear systems can be solved in  $O(nm)$  time.
- Over finite fields & poly-conditioned floats, solving 1 linear system in  $\mathbf{A}$  is as expensive as solving  $n$  systems ( $\mathbf{AX} = \mathbf{B}$ ).
- [Storjohann '05]: bit-complexity of finding exact fractional solution to integer  $\mathbf{Ax} = \mathbf{b}$  is same as matrix multiplication over finite fields ( $O(n^\omega)$ ).
- Laplacian solvers: over fixed-point numbers, poly-conditioned factor width 2 systems can be solved in nearly-linear time.
- Dimensionality reduction/matrix concentration: in poly conditioned floats, can reduce problem size close to rank.
- [Kyng-Zhang '17] & subsequent: many well-studied classes of structured systems are complete for solving general linear systems.

# Combinations of Strange Complexities

- Does structure help for computing exact rational solutions?
- Exact rational solution of low-rank problems?
- Solving sequences of systems over low displacement matrices?
- Empirical comparisons of shifted 2-adics / Hensel lifting vs. floats?
- Complexity of solving Laplacians over floating point representation?
- Are there other (than Laplacians / low displacement) classes of systems that can be solved in sub-CG time in some model?