

"Stochastic homogenization of nonconvex viscous HJ equations in 1D"

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Random Growth Models and KPZ universality

(Timo - Fest)

BIRS

May 30, 2023

$$\frac{\partial u}{\partial t} = \underbrace{\operatorname{tr} \left(a(x) D^2 u \right)}_{d} + H(\underline{D} u, x), \quad (t, x) \in (0, +\infty) \times \mathbb{R}^d, \quad d \geq 1.$$

$$\sum_{i,j=1}^d a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j} \quad \left(\frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_d} \right)$$

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Geometrical optics - Hamilton (1828)
 Classical mechanics - Jacobi (1884) } } Hamilton - Jacobi equation

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Two-person differential games: $a \equiv 0$. H is general.

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Suppose $a(x) = a(x, \omega)$ and $H(p, x) = H(p, x, \omega)$ are random.

(Ω, \mathcal{F}, P) probability space, $\omega \in \Omega$.

$x \mapsto a(x, \omega)$ and $x \mapsto H(p, x, \omega)$ are stationary & ergodic.

Let's zoom out:

$$(HJ_\varepsilon) \quad \frac{\partial u^\varepsilon}{\partial t} = \varepsilon \operatorname{tr} \left(a \left(\frac{x}{\varepsilon}, \omega \right) D^2 u^\varepsilon \right) + H(Du^\varepsilon, \frac{x}{\varepsilon}, \omega), \quad (t, x) \in (0, +\infty) \times \mathbb{R}^d.$$

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Questions:

- ① As $\varepsilon \rightarrow 0$, does this HJ equation effectively become

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- ② If so, then $\underbrace{\overline{H}(p)}_{\text{formula?}} = ?$ "Effective Hamiltonian" (deterministic).
 $\underbrace{\text{properties?}}$

Precisely: For every $g \in UC(\mathbb{R}^d)$, let u_g^ε and \bar{u}_g be the unique **viscosity solutions** of these HJ equations with $u_g^\varepsilon(0, x) = \bar{u}_g(0, x) = g(x), \quad x \in \mathbb{R}^d$.

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We want to show: $\forall g \in UC(\mathbb{R}^d)$ and P -a.e. ω ,

$u_g^\varepsilon(\cdot, \cdot, \omega) \xrightarrow{\varepsilon \rightarrow 0} \bar{u}_g(\cdot, \cdot)$ locally uniformly on $[0, +\infty) \times \mathbb{R}^d$.

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"Qualitative homogenization" (vs. "quantitative homogenization")

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Suppose that, for every $p \in \mathbb{R}^d$, there exist $\lambda = \lambda(p) \in \mathbb{R}$ and $F(\cdot, \omega)$ that solves (SHJ) and $\lim_{|x| \rightarrow +\infty} \frac{F(x, \omega)}{|x|} = 0$.

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Then, $u^\varepsilon(t, x, \omega) = \lambda(p)t + p \cdot x + \underbrace{\varepsilon F\left(\frac{x}{\varepsilon}, \omega\right)}_{\text{"correcting"}}$ solves (HJ_ε) .

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One then generalizes this to uniformly continuous initial data.

This strategy works when $(a(x), H(p, x))$ is periodic in each x_i .

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Suppose not periodic. Then what ?

① If $p \mapsto H(p, x, \omega)$ is convex, then (HJ_ϵ) homogenizes.

- $a \equiv 0$: Souganidis (1999)
Rezakhanlou - T�ver (2000)
- $a \neq 0$: Lions - Souganidis (2005)
Kosygina - Rezakhanlou - Varadhan (2006)

(Stochastic) optimal control representations.

Subadditive ergodic theorem / large deviations techniques.

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Special case: $H(p, x, \omega) = \frac{1}{2} |p|^2 + b(x, \omega) \cdot p + V(x, \omega)$.

- Quenched large deviations of diffusions in random environment.
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Sublinear correctors correspond to Busemann functions.

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- there are some positive results in $d \geq 2$, e.g.
 - + Armstrong - Saganidis (2013) : $a \equiv 0$, H is quasiconvex;
 - + Armstrong - Tran - Yu (2015) : $a \equiv 0$, H is rotation invariant;
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- there are **counterexamples** to homogenization in $d \geq 2$.
 - Ziliotto (2017); Feldman - Saganidis (2017) : $a \equiv 0$;
 - Feldman - Fermanian - Ziliotto (2020) : $a \neq 0$.

Two-person (stochastic) differential game, H has a saddle point.

From now on: $d = 1$, no periodicity or convexity assumption.

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$\sqrt{a(\cdot, \omega)}$ and $V(\cdot, \omega)$ are Lipschitz.

$$\beta > 0.$$

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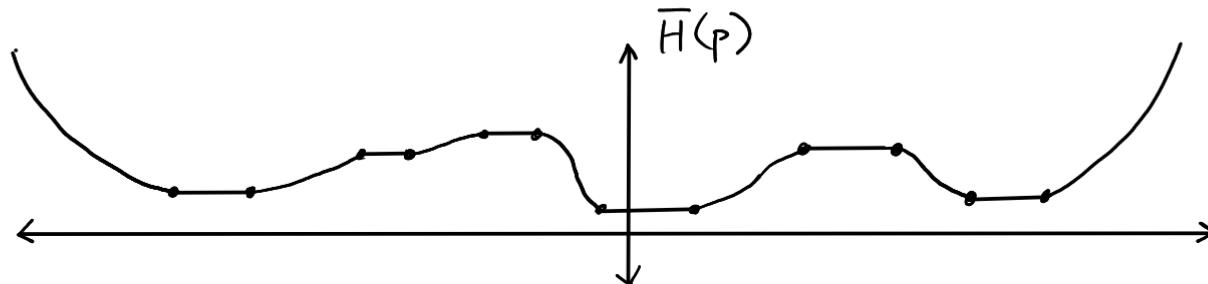
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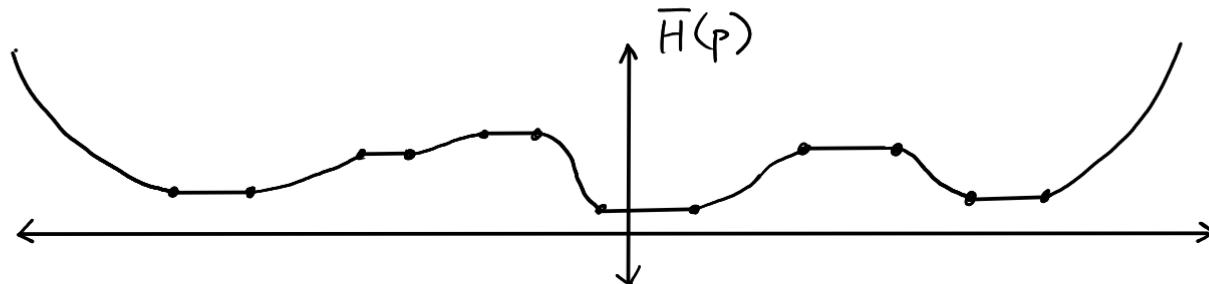
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Generalized to nonseparated $H(p, \alpha, w)$ by Gao (2016).

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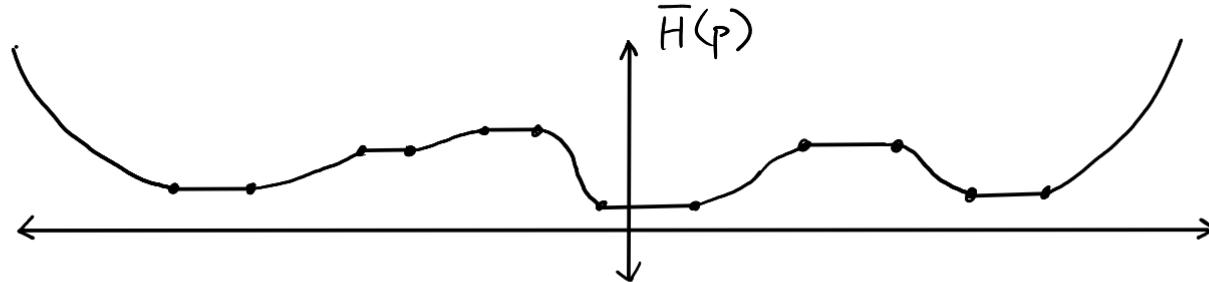
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Regular hill and valley condition: For every $h \in (0, 1)$ and $y > 0$,

$$P(v(\cdot, \omega) \geq h \text{ on } [0, y]) > 0 \quad (\text{hill}).$$

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By ergodicity, for every $h \in (0,1)$, $y > 0$ and P -a.e. ω ,

$$\exists l \in \mathbb{R} \text{ s.t. } v(\cdot, \omega) \geq h \text{ on } [l, l+y] \quad (\text{hill}).$$

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Scaled hill and valley condition: For every $h \in (0,1)$, $y > 0$ and P -a.e. w ,

$$\exists l_1 < l_2 \text{ s.t. } \left\{ \begin{array}{l} \frac{dx}{a(x,w)} \geq y \text{ and} \\ l_1 \end{array} \right. \quad \text{scale}$$

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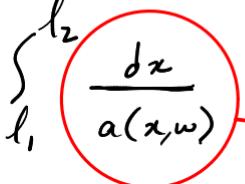
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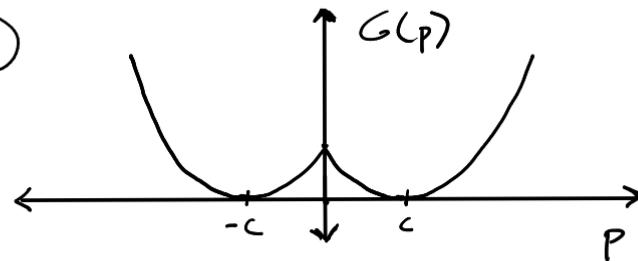
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When $a \equiv 0$, the scaled hill and valley condition is trivially satisfied.



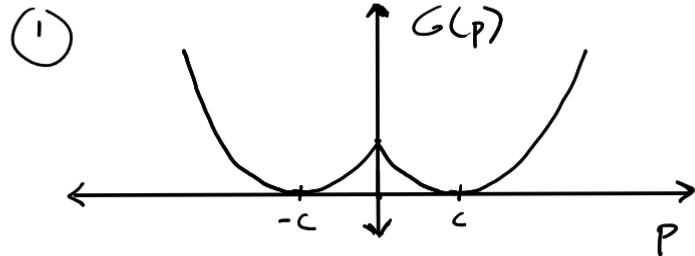
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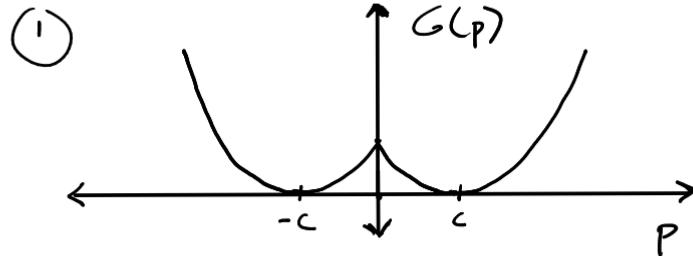


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Risk-sensitive stochastic optimal control in a random potential.

- Y.-Zeitouni (2019): random walk
- Kosygina - Y.-Zeitouni (2020): Brownian motion

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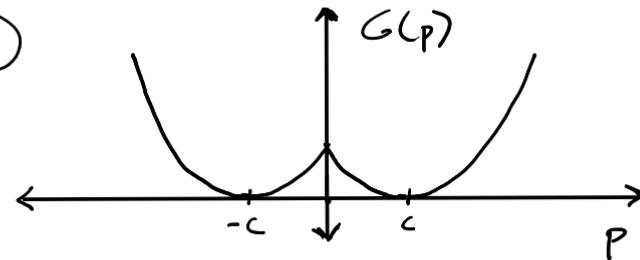
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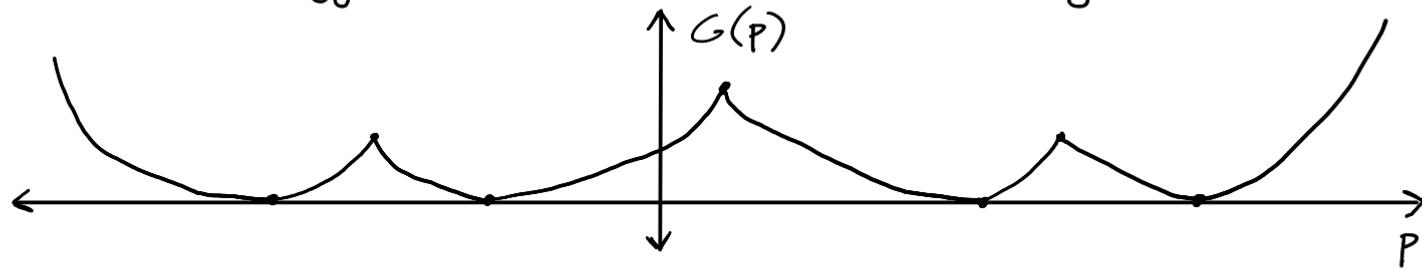
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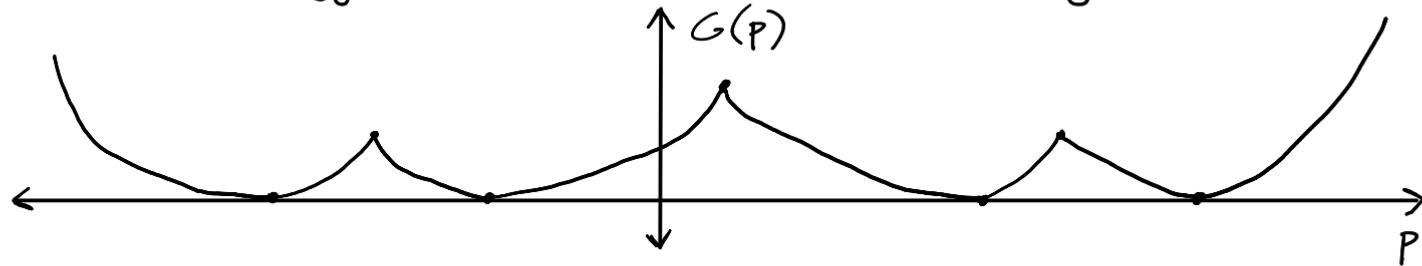
Sublinear correctors have explicit control representations.

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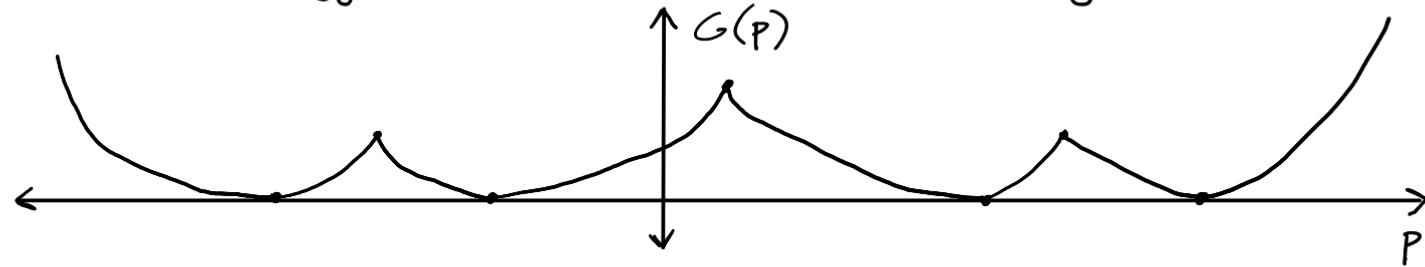
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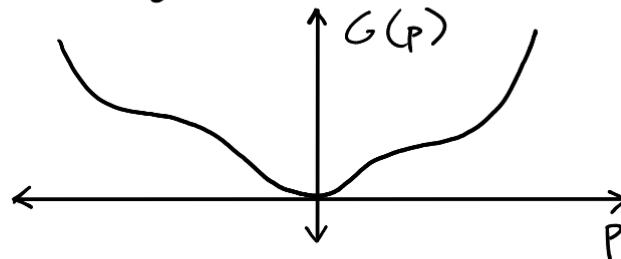
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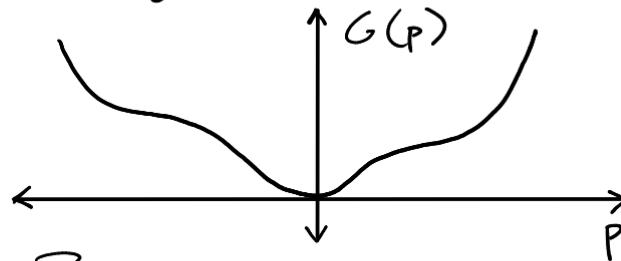


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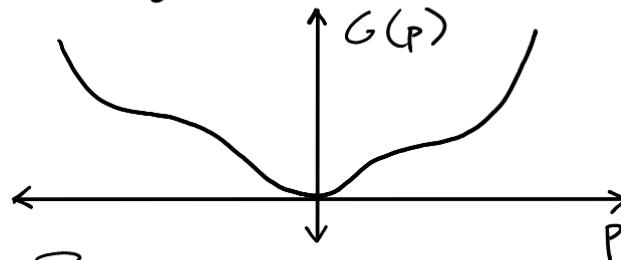


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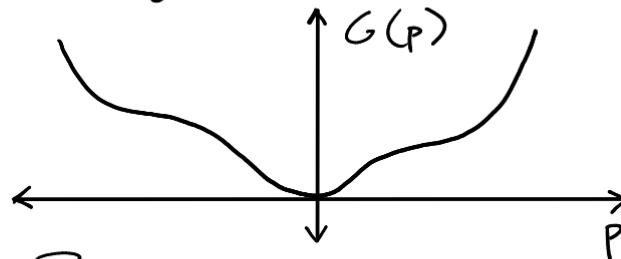
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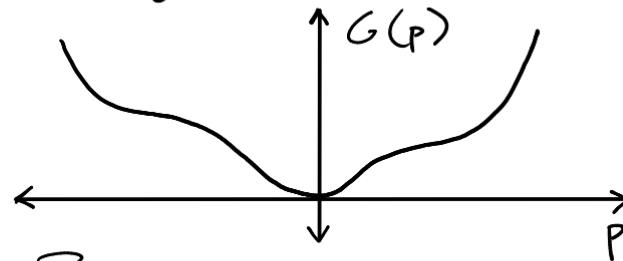
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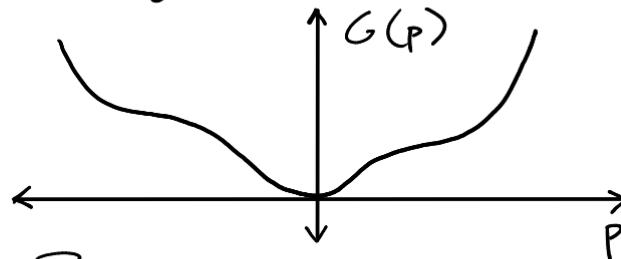
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Restate the classical strategy: Suppose that, for every $p \in R$, there exist $\lambda = \lambda(p)$ and an $f(\cdot, \omega)$ s.t.

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Relaxed strategy: Suppose that, for every $p \in \mathbb{R}$, there exist $\lambda = \lambda(p)$ and stationary & ergodic $\underline{f}(\cdot, \omega)$, $\bar{f}(\cdot, \omega)$ (not necessarily distinct) that solve (ODE),

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\bar{H} is constant on $\left[\underbrace{\mathbb{E}[\underline{f}(0, \omega)]}_{\text{distinct if } \underline{f}(\cdot, \omega) < \bar{f}(\cdot, \omega)}, \underbrace{\mathbb{E}[\bar{f}(0, \omega)]} \right]$.

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This is where the scaled hill and valley condition is used.



Cheers,
Timo!