# The forward－backward scheme for the minimizing total variation flow in $H^{-s}$ 

Work in the collaboration with
Yoshikazu Giga
University of Tokyo
and
Piotr Rybka
University of Warsaw

Monika Muszkieta
Wroclaw University of Science and Technology

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## Total variation flow in $H^{-s}$

We consider the nonlinear, singular, $(2 s+2)$-order diffusion equation

$$
\begin{equation*}
\frac{\partial u}{\partial t}=\left(-\Delta_{\mathrm{av}}\right)^{s}\left[\operatorname{div}\left(\frac{\nabla u}{|\nabla u|}\right)\right] \quad \text { in } \mathbb{T}^{d} \times(0, \infty) \tag{1}
\end{equation*}
$$

with periodic boundary conditions and the initial data $u_{0} \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$.
Here $\mathbb{T}^{d}:=\prod_{i=1}^{d} \mathbb{R} \backslash \mathbb{Z}$ denotes the $d$-dimensional torus and $s$ is the index in $[0,1]$.
For $s \in(0,1]$, we define by $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$, the space dual of

$$
H_{\mathrm{av}}^{s}\left(\mathbb{T}^{d}\right):=\left\{u \in H^{s}\left(\mathbb{T}^{d}\right): \int_{\mathbb{T}^{d}} u d x=0\right\}
$$

where $H^{s}\left(\mathbb{T}^{d}\right)$ is the standard fractional Sobolev space.
The inner product in $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ is defined by

$$
(u, v)_{H_{\mathrm{av}}^{-s}}:=\int_{\mathbb{T}^{d}}\left(-\Delta_{\mathrm{av}}\right)^{-s} u v d x \quad \text { for all } u, v \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)
$$

## Total variation flow in $H^{-s}$

The rigorous interpretation of the equation (1) is

$$
\begin{cases}\frac{d u}{d t}(t) \in-\partial_{H_{\mathrm{av}}^{-s}} \Phi(u(t)) & \text { in } H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right) \text { for a.e. } t \in(0, \infty) \\ u(0)=u_{0} & \text { in } H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)\end{cases}
$$

where the functional $\Phi$ is defined on $L^{2}\left(\mathbb{T}^{d}\right)$ by

$$
\Phi(u):=\left\{\begin{array}{cl}
\int_{\mathbb{T}^{d}}|\nabla u| & \text { if } u \in B V\left(\mathbb{T}^{d}\right) \cap H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right) \\
+\infty & \text { otherwise },
\end{array}\right.
$$

and $\partial_{H_{\mathrm{av}}^{-s}} \Phi$ denotes the subdifferential of $\Phi$ with respect to $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$-topology.
The total variation of the function $u$ is defined by

$$
\int_{\mathbb{T}^{d}}|\nabla u|:=\sup _{z}\left(\int_{\mathbb{T}^{d}} u \operatorname{div} z d x: z \in C_{0}^{1}\left(\mathbb{T}^{d}, \mathbb{R}^{d}\right),\|z\|_{\infty} \leq 1\right)
$$

where for a vector field $z(x)$, the norm $\|\cdot\|_{\infty}$ is defined by $\|z\|_{\infty}:=\sup _{x}|z(x)|$, and $|\cdot|$ is the standard Euclidean norm.

## Characterization of subdifferential

## Theorem 1

Assume that $u \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ is such that $\Phi(u)<+\infty$. Then $v \in \partial_{H_{\mathrm{av}}^{-s}} \Phi(u)$ if and only if there exists $z \in X\left(\mathbb{T}^{d}\right):=\left\{z \in L^{\infty}\left(\mathbb{T}^{d}, \mathbb{R}^{d}\right): \operatorname{div} z \in H_{\mathrm{av}}^{s}\left(\mathbb{T}^{d}\right)\right\}$, such that

$$
\left\{\begin{array}{l}
v=-\left(-\Delta_{\mathrm{av}}\right)^{s} \operatorname{div} z \\
\|z\|_{\infty} \leq 1 \\
\left(u,-\left(-\Delta_{\mathrm{av}}\right)^{s} \operatorname{div} z\right)_{H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)}=\int_{\mathbb{T}^{d}}|\nabla u|,
\end{array}\right.
$$

where $\partial_{H_{\mathrm{av}}^{-s}} \Phi$ is the subdifferential of $\Phi$ with respect to $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$-topology.

- F. Andreu, C. Ballester, V. Caselles, J. M. Mazón, Minimizing total variation flow, Diff. and Int. Eq., 2001.
- Y. Giga, H. Kuroda, H. Matsuoka, Fourth-order total variation flow with Dirichlet condition: characterization of evolution and extinction time estimates, Adv. Math. Sci. App., 2014.


## Existence and uniqueness

The existence and uniqueness of a solution to the system

$$
\begin{cases}\frac{d u}{d t}(t) \in-\partial_{H_{\mathrm{av}}^{-s}} \Phi(u(t)) & \text { in } H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right) \text { for a.e. } t \in(0, \infty) \\ u(0)=u_{0} & \text { in } H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)\end{cases}
$$

guarantees the theorem:

## Theorem 2

Let $\mathcal{A}(u):=\partial_{H_{\mathrm{av}}^{-s}} \Phi(u)$ and suppose that $u_{0} \in D(\mathcal{A})$. Then, there exists a unique function $u:[0, \infty) \rightarrow H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ such that:
(1) for all $t>0$ we have that $u(t) \in D(\mathcal{A})$,
(2) $\frac{d u}{d t} \in L^{\infty}\left(0, \infty, H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)\right)$ and $\left\|\frac{d u}{d t}\right\|_{H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)} \leq\left\|\mathcal{A}^{0}\left(u_{0}\right)\right\|_{H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)}$,
(3) $\frac{d u}{d t} \in-\mathcal{A}(u(t))$ a.e. on $(0, \infty)$,
(4) $u(0)=u_{0}$.

- H. Brézis, Opérateurs maximaux monotones et semi-groupes de contractions dans les espaces de Hilbert, North Holland Publishing Company, Amsterdam, 1973.


## Semi-discretization

We consider the finite set of $n+1$ equidistant points

$$
\left\{t_{i}=i \tau: i=0, \ldots, n \text { and } \tau=t / n\right\}
$$

in the interval $[0, t]$.
We set $u_{\tau}(0)=u_{0}$. For $i=1, \ldots, n$, we define recursively by $u_{\tau}\left(t_{i}\right)$ a solution of

$$
\begin{equation*}
\frac{u_{\tau}\left(t_{i}\right)-u_{\tau}\left(t_{i-1}\right)}{\tau} \in-\partial_{H_{\mathrm{av}}^{-s}} \Phi\left(u_{\tau}\left(t_{i}\right)\right) \tag{2}
\end{equation*}
$$

Let $\mathcal{A}:=\partial_{H_{\mathrm{av}}^{-s}} \Phi$, then we can write

$$
u_{\tau}\left(t_{i}\right)=(I+\tau \mathcal{A})^{-i} u_{0}
$$

It is well known that if $\mathcal{A}$ is monotone, then the resolvent $(I+\tau \mathcal{A})^{-1}$ is non-expansive, which implies that the above implicit scheme is stable.

We observe that the equation (2) for $u_{\tau}\left(t_{i}\right)$ is the optimality condition for the minimization problem

$$
\inf _{u \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)}\left\{\frac{1}{2 \tau}\left\|u-u_{\tau}\left(t_{i-1}\right)\right\|_{H_{\mathrm{av}}^{-s}}^{2}+\Phi(u)\right\}
$$

- M. G. Crandall, T. M. Liggett, Generation of semi-groups of nonlinear transformations on general Banach spaces, Amer. J. Math., 1971.


## Dual problem

Let $f \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ be a given function. To derive the dual problem to

$$
\inf _{u \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)}\left\{\frac{1}{2 \tau}\|u-f\|_{H_{\mathrm{av}}^{-s}}^{2}+\Phi(u)\right\}
$$

we need the following two results:

## Lemma 1

Let the functional $\Phi$ be convex, proper and lower-semicontinuous, then we have $v \in \partial_{H_{\mathrm{av}}^{-s}} \Phi(u)$ if and only if $u \in \partial_{H_{\mathrm{av}}^{-s}} \Phi^{*}(v)$.

## Lemma 2

For $u \in B V\left(\mathbb{T}^{d}\right) \cap H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$, we have that the convex conjugate of the functional $\Phi$ in $H_{\mathrm{av}}^{-s}$ is given by $\Phi^{*}(v)=\chi_{K}(v)$, where $K$ is the closure of the set

$$
\left\{v \in \mathcal{D}^{\prime}\left(\mathbb{T}^{d}\right): v=-\left(-\Delta_{\mathrm{av}}\right)^{s} \operatorname{div} z, z \in \mathcal{D}\left(\mathbb{T}^{d}\right),\|z\|_{\infty} \leq 1\right\}
$$

with respect to the $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$-topology.

## Dual problem

## Theorem 4

Let $f \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ be a given function, then the problem

$$
\begin{equation*}
\inf _{v \in K}\left\{\frac{1}{2 \tau}\|\tau v-f\|_{H_{\mathrm{av}}^{-s}}^{2}\right\} \tag{3}
\end{equation*}
$$

is dual to

$$
\begin{equation*}
\inf _{u \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)}\left\{\frac{1}{2 \tau}\|u-f\|_{H_{\mathrm{av}}^{-s}}^{2}+\Phi(u)\right\} \tag{4}
\end{equation*}
$$

Moreover, the solution $u$ of (4) is associated with the solution $v$ of (3) by the relation

$$
u=f-\tau v .
$$

## Corollary 1

The solution of the problem (4) satisfies $u=f-\tau P_{K}^{H_{\mathrm{av}}^{-s}}(f / \tau)$, where $P_{K}^{H_{\mathrm{av}}^{-s}}$ denotes the orthogonal projection on the set $K$ with respect to the inner product in $H_{\mathrm{av}}^{-s}$.

## Forward-backward splitting scheme

Let define the functional $J$ on $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ by

$$
J(v):=\frac{1}{2 \tau}\|\tau v-f\|_{H_{\mathrm{av}}^{-s}}^{2} .
$$

Then the dual problem can be written as

$$
\inf _{v \in H_{\mathrm{av}^{-s}\left(\mathbb{T}^{d}\right)}}\left\{J(v)+\Phi^{*}(v)\right\}
$$

To find $v^{*} \in K$ such that $0 \in \partial_{H_{\mathrm{av}}^{-s}}\left(J\left(v^{*}\right)+\Phi^{*}\left(v^{*}\right)\right)$ we consider the forward-backward splitting scheme given by

$$
\left\{\begin{array}{l}
u^{k} \in-\partial_{H_{\mathrm{av}}^{-s}} J\left(v^{k}\right)  \tag{5}\\
v^{k+1}=\left(I+\lambda \partial_{H_{\mathrm{av}}^{-s}} \Phi^{*}\right)^{-1}\left(v^{k}+\lambda u^{k}\right)
\end{array}\right.
$$

## Remark 1

The above scheme requires that $\partial_{H_{\mathrm{av}}^{-s}}\left(J(v)+\Phi^{*}(v)\right)=\partial_{H_{\mathrm{av}}^{-s}} J(v)+\partial_{H_{\mathrm{av}}^{-s} \Phi^{*}}(v)$, which holds since $\operatorname{int}\left(D\left(\Phi^{*}\right)\right) \cap D(J) \neq \emptyset$.

- P. L. Lions, B. Mercier, Splitting algorithms for the sum of two nonlinear operators, SIAM J. Num. Anal., 1979.
- P. L. Combettes, V. R. Wajs, Signal recovery by proximal forward-backward splitting. SIAM: MMS, 2005.


## Convergence

## Theorem 5

Let $\left\{u^{k}\right\}$ and $\left\{v^{k}\right\}$ be sequences generated by the scheme

$$
\left\{\begin{array}{l}
u^{k} \in-\partial_{H_{\mathrm{av}}^{-s}} J\left(v^{k}\right) \\
v^{k+1}=\left(I+\lambda \partial_{H_{\mathrm{av}}^{-s}} \Phi^{*}\right)^{-1}\left(v^{k}+\lambda u^{k}\right)
\end{array}\right.
$$

Moreover assume that $0<\lambda \tau<2$. Then we have that $v^{k} \rightharpoonup v^{*}$ and $u^{k} \rightharpoonup u^{*}$ in $H_{a v}^{-s}$ as $k \rightarrow \infty$, where $v^{*} \in K$ is such that $v^{*} \in \partial_{H_{\mathrm{av}}^{-s}} \Phi\left(u^{*}\right)$ and $u^{*}=f-\tau v^{*}$.

## Equivalent scheme

Let $v \in H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$, then by Moreau's identity

$$
v=\left(I+\lambda \partial_{H_{\mathrm{av}}^{-s}} \Phi^{*}\right)^{-1}(v)+\lambda\left(I+1 / \lambda \partial_{H_{\mathrm{av}}^{-s}} \Phi\right)^{-1}(v / \lambda),
$$

we obtain that the forward-backward splitting scheme

$$
\left\{\begin{array}{l}
u^{k} \in-\partial_{H_{\mathrm{av}}^{-s}} J\left(v^{k}\right) \\
v^{k+1}=\left(I+\lambda \partial_{H_{\mathrm{av}}^{-s}} \Phi^{*}\right)^{-1}\left(v^{k}+\lambda u^{k}\right)
\end{array}\right.
$$

is equivalent to

$$
\left\{\begin{array}{l}
u^{k} \in-\partial_{H_{\mathrm{av}}^{-s}} J\left(v^{k}\right) \\
v^{k+1}=H_{1 / \lambda}\left(v^{k} / \lambda+u^{k}\right)
\end{array}\right.
$$

where $H_{1 / \lambda}$ denotes the Yosida approximation of the operator $\mathcal{A}:=\partial_{H_{\mathrm{av}}^{-s}} \Phi$, i.e.

$$
H_{1 / \lambda}(v):=\lambda\left(v-(I+1 / \lambda \mathcal{A})^{-1} v\right)
$$

It is well known that $H_{1 / \lambda}$ converges as $\lambda \rightarrow \infty$ to the minimal selection $\mathcal{A}_{0}$ of $\mathcal{A}$.

## Dual problem

Using the characterization of $v \in \partial_{H_{\text {av }}^{-s}} \Phi(u)$, we can rewrite the dual problem to

$$
\inf _{z \in Z}\left\{\frac{1}{2 \tau}\left\|\tau\left(-\Delta_{\mathrm{av}}\right)^{s} \operatorname{div} z+f\right\|_{H_{\mathrm{av}}^{-s}}^{2}\right\}
$$

where $Z$ is the closure of the set

$$
\left\{z \in \mathcal{D}\left(\mathbb{T}^{d}\right):\left(-\Delta_{\mathrm{av}}\right)^{-s} \operatorname{div} z \in \mathcal{D}^{\prime}\left(\mathbb{T}^{d}\right),\|z\|_{\infty} \leq 1\right\}
$$

with respect to the $L^{2}\left(\mathbb{T}^{d}\right)$-topology.
Let define functionals $F$ and $G$ on $L^{2}\left(\mathbb{T}^{d}, \mathbb{R}^{d}\right)$ by

$$
F(z):=\frac{1}{2 \tau}\left\|\tau\left(-\Delta_{\mathrm{av}}\right)^{s} \operatorname{div} z+f\right\|_{H_{\mathrm{av}}^{-s}}^{2}
$$

and

$$
G(z):= \begin{cases}0 & \text { if } z \in Z \\ +\infty & \text { otherwise }\end{cases}
$$

Then the dual problem can be written as

$$
\inf _{z \in L^{2}\left(\mathbb{T}^{d}, \mathbb{R}^{d}\right)}\{F(z)+G(z)\}
$$

## Forward-backward splitting scheme

To find $z^{*} \in Z$ such that $0 \in \partial_{L^{2}}\left(F\left(z^{*}\right)+G\left(z^{*}\right)\right)$ we consider the forward-backward splitting scheme given by

$$
\left\{\begin{array}{l}
w^{k} \in \partial_{L^{2}} F\left(z^{k}\right)  \tag{6}\\
z^{k+1}=\left(I+\lambda \partial_{L^{2}} G\right)^{-1}\left(z^{k}-\lambda w^{k}\right)
\end{array}\right.
$$

The explicit form of the scheme (6) is given by

$$
\left\{\begin{array}{l}
w^{k}=-\nabla\left(f+\tau\left(-\Delta_{\mathrm{av}}\right)^{s} \operatorname{div} z^{k}\right) \\
z^{k+1}=\frac{z^{k}-\lambda w^{k}}{\left|z^{k}-\lambda w^{k}\right| \vee 1}
\end{array}\right.
$$

## Convergence in discrete setting

We denote by $X$ the Euclidean space $\mathbb{R}^{N}$.
The scalar product of two elements $u, v \in X$ is defined by $\langle u, v\rangle:=\sum_{i=1}^{N} u_{i} v_{i}$ and the norm $\|u\|:=\sqrt{\langle u, u\rangle}$.
Here $\nabla$ denotes the discrete gradient operator satisfying periodic boundary conditions. Then $\operatorname{div}:=\nabla^{T}$ and $\Delta:=\operatorname{div} \nabla$.

For the convenience, we also define $(u, v)_{-s}:=\left\langle(-\Delta)^{-s} u, v\right\rangle$ for all $u, v \in X$ and $\|u\|_{-s}:=\sqrt{(u, u)_{-s}}$.

We denote by $Z:=\left\{z \in X:\|z\|_{\infty} \leq 1\right\}$, where $\|z\|_{\infty}:=\max _{i}\left|z_{i}\right|$.
For $f \in X$ we define functionals $F$ and $G$ on $X$ by

$$
F(z):=\frac{1}{2 \tau}\left\|\tau(-\Delta)^{s} \operatorname{div} z+f\right\|_{-s}^{2}
$$

and

$$
G(z):= \begin{cases}0 & \text { if } z \in Z \\ +\infty & \text { otherwise }\end{cases}
$$

Then the discrete version of the dual problem for $z$ is

$$
\min _{z \in X}\{F(z)+G(z)\}
$$

## Convergence in discrete setting

## Lemma 6

For $z \in X$, there exists a constant $C>0$, such that

$$
\left\|(-\Delta)^{s} \operatorname{div} z\right\|_{-s}^{2} \leq C\|z\|^{2} .
$$

Moreover, $C=\mu_{\max }^{s+1}$, where $\mu_{\max }$ denotes the largest eigenvalue of the discrete Laplace operator.

## Theorem 6

Assume that $0<C \lambda \tau<2$, where the constant $C>0$ is as in Lemma 6. Then, the sequence $\left\{z_{k}\right\}$ given by the scheme

$$
\left\{\begin{array}{l}
w^{k}=-\nabla\left(f+\tau\left(-\Delta_{\mathrm{av}}\right)^{s} \operatorname{div} z^{k}\right) \\
z^{k+1}=\frac{z^{k}-\lambda w^{k}}{\left|z^{k}-\lambda w^{k}\right| \vee 1}
\end{array}\right.
$$

is such that $z^{k} \rightharpoonup z^{*}$ in $X$ as $k \rightarrow \infty$, where $z^{*} \in Z$ is such that

$$
0 \in \partial_{X}\left(F\left(z^{*}\right)+G\left(z^{*}\right)\right) .
$$

## Ergodic convergence

From Theorem 5 we have that if $0<\lambda \tau<2$, then the sequence $\left\{v^{k}\right\}$ converges weakly in $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ to $v^{*} \in K$, where $v^{*}$ is a unique solution of the dual problem.

Then, Mazur's lemma implies existence of the sequence $\left\{\bar{v}^{n}\right\}$ given by

$$
\bar{v}^{n}=\sum_{k=0}^{n} \alpha_{k} v^{k},
$$

where $\left\{\alpha_{k}\right\}$ is such that $\sum_{k=0}^{n} \alpha_{k}=1$, which converges strongly in $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ to $v^{*}$ as $n \rightarrow \infty$.

We aim to construct a sequence $\left\{\alpha_{k}\right\}$ such that $\bar{v}^{n} \rightarrow v^{*}$ as $n \rightarrow \infty$, and next, to use this result in order to prove that the sequence $\left\{\bar{z}^{n}\right\}$ given by

$$
\bar{z}^{n}=\sum_{k=0}^{n} \alpha_{k} z^{k}
$$

converges weakly in $Q L^{2}\left(\mathbb{T}^{d}\right)$ to $z^{*} \in Z$ as $n \rightarrow \infty$, where $Q$ is the orthogonal projection onto the space of gradient fields.

## Ergodic convergence

Theorem 6
Let $\left\{v^{k}\right\}$ be a weakly convergent sequence generated by the scheme (5) and let $\left\{\beta_{k}\right\}$ be a sequence of positive real numbers such that $\left\{\beta_{k}\right\} \in l^{2} \backslash l^{1}$. Then, for

$$
\alpha_{k}=\frac{1}{\sum_{j=1}^{n} \beta_{j}} \beta_{k}
$$

the sequence $\left\{\bar{v}^{n}\right\}$ given by

$$
\bar{v}^{n}=\sum_{k=0}^{n} \alpha_{k} v^{k},
$$

converges strongly in $H_{\mathrm{av}}^{-s}\left(\mathbb{T}^{d}\right)$ to $v^{*} \in K$ as $n \rightarrow \infty$. Moreover, the sequence $\left\{\bar{z}^{n}\right\}$ given by

$$
\bar{z}^{n}=\sum_{k=0}^{n} \alpha_{k} z^{k}
$$

where $\left\{z^{k}\right\}$ is generated by the scheme (6), converges weakly in $Q L^{2}\left(\mathbb{T}^{d}\right)$ to $z^{*} \in Z$ as $n \rightarrow \infty$.

## Evolution in 1d

For experiments, we were considering initial data $f, g:[-10,10] \rightarrow \mathbb{R}$, given by explicit formulas

$$
f(x)=\left\{\begin{array}{cl}
20 & \text { if }|x| \leq 2 \\
50|x|^{-1}-5 & \text { otherwise }
\end{array}, \quad g(x)=\left\{\begin{array}{cl}
20 & \text { if }|x| \leq 2 \\
0 & \text { otherwise }
\end{array}\right.\right.
$$




Figure: Graphs of functions $f$ and $g$ considered in experiments as initial data.

## Evolution in 1d

$$
s=0
$$

$s=0.5$

$$
s=1
$$







Figure: Evolution of solutions to the $H^{-s}$ total variation flow with periodic boundary conditions and initial data $f$ and $g$.

