Traces of Sobolev functions

Luboš Pick (Charles University, Prague)

BIRS, July 14, 2016

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• Andrea Cianchi

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Problem. Sketch the trace of $f(x, y) = 10 - 4x^2 - y^2$ for the plane x = 1.

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Problem. Sketch the trace of $f(x, y) = 10 - 4x^2 - y^2$ for the plane y = 2.

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Traces of Sobolev functions

Observation. In elementary calculus, trace means just **restriction** of a function to a certain subset.

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In the principle field of application for traces, however, this concept does not work.

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Application: boundary value problems

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Motivation: existence and uniqueness of solutions to partial differential equations with prescribed boundary conditions.

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The basic description

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Let Ω be a bounded open set in \mathbb{R}^n having the C^1 boundary $\partial \Omega$. Suppose that $u \in C^1(\overline{\Omega})$.

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However, if *u* is just a weak solution to a PDE, it only belongs to a Sobolev space.

Obstacle: such functions are defined only up to a set of measure 0, and $\partial\Omega$ **does** have measure 0 in \mathbb{R}^n . As a consequence, any such function can be **redefined** on $\partial\Omega$ in any way without changing it as an element of that space.

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However, if *u* is just a weak solution to a PDE, it only belongs to a Sobolev space.

Obstacle: such functions are defined only up to a set of measure 0, and $\partial\Omega$ **does** have measure 0 in \mathbb{R}^n . As a consequence, any such function can be **redefined** on $\partial\Omega$ in any way without changing it as an element of that space.

So, restriction is useless.

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The **Sobolev space** $W^{m,p}(\Omega)$ is defined as the set of all *m*-times weakly differentiable functions u in Ω such that $D^{\alpha}u \in L^{p}(\Omega)$ for every *n*-dimensional multiindex α satisfying $0 \leq |\alpha| \leq m$,

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$$D^{\alpha}u:=\frac{\partial^{|\alpha|}u}{\partial x_1^{\alpha_1}\dots\partial x_n^{\alpha_n}}.$$

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The norm in Sobolev space is given by

$$\|u\|_{W^{m,p}(\Omega)}=\sum_{|\alpha|\leq m}\|D^{\alpha}u\|_{L^{p}(\Omega)}.$$

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The norm in Sobolev space is given by

$$\|u\|_{W^{m,p}(\Omega)}=\sum_{|\alpha|\leq m}\|D^{\alpha}u\|_{L^p(\Omega)}.$$

We also denote by $W^{m,p}_0(\Omega)$ the closure of $C^\infty_0(\Omega)$ in $W^{m,p}(\Omega)$.

Trace operator

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Remark. The **trace operator** enables one to extend the notion of **restriction** of a function to the boundary to generalized functions in a Sobolev space.

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Consider the linear operator

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given by

Tr $u = u \mid_{\partial \Omega}$.

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Then the domain of Tr is a dense subset of the Sobolev space $W^{1,p}(\Omega)$.

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Then the domain of Tr is a dense subset of the Sobolev space $W^{1,p}(\Omega)$. It can be proved that

$$\|\operatorname{Tr} u\|_{L^p(\partial\Omega)} \leq C \|u\|_{W^{1,p}(\Omega)},$$

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Consider the linear operator

$$\mathsf{Tr}: C^1(\overline{\Omega}) o L^p(\partial\Omega)$$

given by

$${\sf \Gamma}{\sf r}\; u=u\mid_{\partial\Omega}$$
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Then the domain of Tr is a dense subset of the Sobolev space $W^{1,p}(\Omega)$. It can be proved that

$$\|\operatorname{\mathsf{Tr}} u\|_{L^p(\partial\Omega)} \leq C \|u\|_{W^{1,p}(\Omega)},$$

that is, \mathcal{T} admits a continuous extension

$$\operatorname{Tr}: W^{1,p}(\Omega) \to L^p(\partial\Omega).$$

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Then the domain of Tr is a dense subset of the Sobolev space $W^{1,p}(\Omega)$. It can be proved that

$$\|\operatorname{Tr} u\|_{L^p(\partial\Omega)} \leq C \|u\|_{W^{1,p}(\Omega)},$$

that is, T admits a continuous extension

$$\operatorname{Tr}: W^{1,p}(\Omega) \to L^p(\partial\Omega).$$

We call this (rather incorrectly) a trace embedding.

An application

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$$-\Delta u = f \text{ in } \Omega,$$
$$u \mid_{\partial \Omega} = 0.$$

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 $\begin{aligned} -\Delta u &= f \text{ in } \Omega, \\ u \mid_{\partial \Omega} &= 0. \end{aligned}$

With the help of the concept of the trace,

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$$-\Delta u = f \text{ in } \Omega$$
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With the help of the concept of the **trace**, the equation above can be given by the **weak** formulation

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and, using the Lax-Milgram theorem, one can prove the existence and uniqueness of a solution.

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Remark.

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Remark. Similar ideas can be used to prove existence and uniqueness of solutions to more complicated PDEs with Neumann boundary conditions,

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and, using the Lax-Milgram theorem, one can prove the existence and uniqueness of a solution.

Remark. Similar ideas can be used to prove existence and uniqueness of solutions to more complicated PDEs with Neumann boundary conditions, with traces playing a crucial role.

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The basic question: Given some data on u, what can we say about Tr u?

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Elementary observations

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For example, if *u* is *continuous* or *smooth* on Ω , then so will be Tr *u*.

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For example, if *u* is *continuous* or *smooth* on Ω , then so will be Tr *u*.

Our main interest concerns functions *u* in a **Sobolev space**.

Part 1: boundary traces

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Classical trace embeddings

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The standard Sobolev boundary-trace embedding

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The standard Sobolev boundary-trace embedding (Morrey, Adams, Maz'ya):

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The standard Sobolev boundary-trace embedding (Morrey, Adams, Maz'ya): if $1 \le m < n$ and $p < \frac{n}{m}$,

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The standard Sobolev boundary-trace embedding (Morrey, Adams, Maz'ya): if $1 \le m < n$ and $p < \frac{n}{m}$, then the *linear operator*

 $\operatorname{Tr} : u \mapsto \operatorname{Tr} u$

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The standard Sobolev boundary-trace embedding (Morrey, Adams, Maz'ya): if $1 \le m < n$ and $p < \frac{n}{m}$, then the *linear operator*

 $\operatorname{Tr}: u \mapsto \operatorname{Tr} u$

is well defined on $W^{m,p}(\Omega)$, and

$$Tr: W^{m,p}(\Omega) \to \begin{cases} L^{\frac{p(n-1)}{n-mp}}(\partial\Omega) & \text{ if } p < \frac{n}{m}, \\ L^{\infty}(\partial\Omega) & \text{ if } p > \frac{n}{m}. \end{cases}$$

Comparison with full (non-trace) Sobolev embeddings

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Let $1 \le p < \frac{n}{m}$. The full Sobolev embedding states that $W^{m,p}(\Omega) \hookrightarrow L^{\frac{np}{n-mp}}(\Omega),$

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Let $1 \le p < \frac{n}{m}$. The full Sobolev embedding states that $W^{m,p}(\Omega) \hookrightarrow L^{\frac{np}{n-mp}}(\Omega),$

while the Sobolev boundary-trace embedding states that

$$Tr: W^{m,p}(\Omega) \to L^{\frac{p(n-1)}{n-mp}}(\partial \Omega).$$

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Classical approach

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• local coordinates on $\partial \Omega$,

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- local coordinates on $\partial \Omega$,
- Sobolev inequalities in Ω ,

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- local coordinates on $\partial \Omega$,
- Sobolev inequalities in Ω,
- Lebesgue norms (heavily).

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The limiting case

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For the case $p = \frac{n}{m}$,

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For the case $p = \frac{n}{m}$, the classical approach gives only $Tr: W^{m,p}(\Omega) \to L^q(\partial \Omega)$ for every $q < \infty$,

which is quite unsatisfactory.

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The moral

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• a more general function space,

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- a more general function space,
- another approach to traces.

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- a more general function space,
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This can be achieved, for instance, via

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• an exponential-type Orlicz space,

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- a more general function space,
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This can be achieved, for instance, via

- an exponential-type Orlicz space,
- and a representation theorem in terms of Riesz potentials.

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This can be achieved, for instance, via

- an exponential-type Orlicz space,
- and a representation theorem in terms of Riesz potentials.

We get

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- a more general function space,
- another approach to traces.

This can be achieved, for instance, via

- an exponential-type Orlicz space,
- and a representation theorem in terms of Riesz potentials.

We get

$$Tr: W^{m,\frac{n}{m}}(\Omega) \to \exp L^{\frac{n}{n-m}}(\partial\Omega).$$

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A drawback

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Shortcoming:

Shortcoming: function spaces defined in terms of potentials

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Shortcoming: function spaces defined in terms of **potentials** are not always equivalent to corresponding ones defined by **derivatives**.

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Shortcoming: function spaces defined in terms of **potentials** are not always equivalent to corresponding ones defined by **derivatives**.

In fact, none of the available methods seems to cover the whole range of situations of interest in applications.

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The problem

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Hence the demand:

Hence the demand: Find a unified flexible approach to trace inequalities fitting sufficiently general class of function spaces.

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The approach

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An idea:

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An idea: Use symmetrization.

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An idea: Use symmetrization.

Symmetrization is a powerful principle based upon the **Pólya–Szegö principle** on decrease of gradient norms under radially non-increasing rearrangement.

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An idea: Use symmetrization.

Symmetrization is a powerful principle based upon the **Pólya–Szegö principle** on decrease of gradient norms under radially non-increasing rearrangement.

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Our approach

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• symmetrization,

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- symmetrization,
- rearrangement-techniques,

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- symmetrization,
- rearrangement-techniques,
- reduction to one-dimensional inequalities,

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- symmetrization,
- rearrangement-techniques,
- reduction to one-dimensional inequalities,
- interpolation,

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We developed a new method based on the combination of

- symmetrization,
- rearrangement-techniques,
- reduction to one-dimensional inequalities,
- interpolation,
- iteration.

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We developed a new method based on the combination of

- symmetrization,
- rearrangement-techniques,
- reduction to one-dimensional inequalities,
- interpolation,
- iteration.

Moreover, we work in a fairly general environment of rearrangement-invariant spaces.

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Function spaces involved

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We say that a functional $\|\cdot\|_{X(0,1)}$ is a *function norm*

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(P1) $||f||_{X(0,1)} = 0$ if and only if f = 0; $||\lambda f||_{X(0,1)} = \lambda ||f||_{X(0,1)}$;

(P1) $||f||_{X(0,1)} = 0$ if and only if f = 0; $||\lambda f||_{X(0,1)} = \lambda ||f||_{X(0,1)}$; $||f + g||_{X(0,1)} \le ||f||_{X(0,1)} + ||g||_{X(0,1)}$;

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(P1) $||f||_{X(0,1)} = 0$ if and only if f = 0; $||\lambda f||_{X(0,1)} = \lambda ||f||_{X(0,1)}$; $||f + g||_{X(0,1)} \le ||f||_{X(0,1)} + ||g||_{X(0,1)}$; (P2) $f \le g$ a.e. implies $||f||_{X(0,1)} \le ||g||_{X(0,1)}$; (P3) $f_j \nearrow f$ a.e. implies $||f_j||_{X(0,1)} \nearrow ||f||_{X(0,1)}$;

 $\begin{array}{ll} (\mathsf{P1}) & \|f\|_{X(0,1)} = 0 \text{ if and only if } f = 0; \ \|\lambda f\|_{X(0,1)} = \lambda \|f\|_{X(0,1)}; \\ & \|f + g\|_{X(0,1)} \leq \|f\|_{X(0,1)} + \|g\|_{X(0,1)}; \\ (\mathsf{P2}) & f \leq g \text{ a.e. implies } \|f\|_{X(0,1)} \leq \|g\|_{X(0,1)}; \\ (\mathsf{P3}) & f_j \nearrow f \text{ a.e. implies } \|f_j\|_{X(0,1)} \nearrow \|f\|_{X(0,1)}; \\ (\mathsf{P4}) & \|1\|_{X(0,1)} < \infty; \end{array}$

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(P1)
$$||f||_{X(0,1)} = 0$$
 if and only if $f = 0$; $||\lambda f||_{X(0,1)} = \lambda ||f||_{X(0,1)}$;
 $||f + g||_{X(0,1)} \le ||f||_{X(0,1)} + ||g||_{X(0,1)}$;
(P2) $f \le g$ a.e. implies $||f||_{X(0,1)} \le ||g||_{X(0,1)}$;
(P3) $f_j \nearrow f$ a.e. implies $||f_j||_{X(0,1)} \nearrow ||f||_{X(0,1)}$;
(P4) $||1||_{X(0,1)} < \infty$;
(P5) $\int_0^1 f(x) dx \le C ||f||_{X(0,1)}$ for some constant *C* independent of f .

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Rearrangement-invariant spaces

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If $\|\cdot\|_{X(0,1)}$ is a function norm and, in addition, (P6) $\|f\|_{X(0,1)} = \|g\|_{X(0,1)}$ whenever $f^* = g^*$, we say that $\|\cdot\|_{X(0,1)}$ is a *rearrangement-invariant function norm*.

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If $\|\cdot\|_{X(0,1)}$ is a function norm and, in addition, (P6) $\|f\|_{X(0,1)} = \|g\|_{X(0,1)}$ whenever $f^* = g^*$, we say that $\|\cdot\|_{X(0,1)}$ is a *rearrangement-invariant function norm*.

Here, f^* is the non-increasing rearrangement of f, defined as

 $f^*(s)=\sup\{\lambda\geq 0: \
u\left(\{t\in (0,1); \ |f(t)|>\lambda\}
ight)>s\}, \quad s\in (0,1).$

Associate norm

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If $\|\cdot\|_{X(0,1)}$ is a function norm, then the associate function norm $\|\cdot\|_{X'(0,1)}$ is defined by

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If $\|\cdot\|_{X(0,1)}$ is a function norm, then the associate function norm $\|\cdot\|_{X'(0,1)}$ is defined by

$$\|g\|_{X'(0,1)} = \sup_{\substack{f \ge 0 \\ \|f\|_{X(0,1)} \le 1}} \int_0^1 f(s)g(s) \, ds.$$

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Examples of rearrangement-invariant spaces

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What is a rearrangement-invariant space?

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What is a rearrangement-invariant space?

Everything that measures just the size of a function, for example

What is a rearrangement-invariant space?

Everything that measures just the size of a function, for example

- Lebesgue spaces
- Lorentz spaces
- Orlicz spaces
- Zygmund classes

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Examples of rearrangement-invariant spaces

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What is not a rearrangement-invariant space?

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What is **not** a rearrangement-invariant space?

Anything that measures continuity, smoothness, oscillation etc., for example

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What is **not** a rearrangement-invariant space?

Anything that measures continuity, smoothness, oscillation etc., for example

- Hölder continuity spaces
- Sobolev spaces
- Morrey spaces
- Campanato classes

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General Sobolev space

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Let Ω be a bounded open set in \mathbb{R}^n . Let $m \in \mathbb{N}$ and let $p \in [1, \infty]$.

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Let Ω be a bounded open set in \mathbb{R}^n . Let $m \in \mathbb{N}$ and let $p \in [1, \infty]$.

The **Sobolev space** $W^m X(\Omega)$ is defined as the set of all *m*-times weakly differentiable functions u in Ω such that $D^{\alpha}u \in X(\Omega)$ for all $0 \leq |\alpha| \leq m$,

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The **norm** in $W^m X$ is given as

$$\|u\|_{W^mX(\Omega)}=\sum_{|\alpha|\leq m}\|D^{\alpha}u\|_{X(\Omega)}.$$

The results - the reduction principle

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The results - the reduction principle

Theorem (Cianchi, Kerman, Pick – J. d' Anal. Math. 2008).

Let $1 \leq m < n$.

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Then the trace embedding

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holds if and only if

$$\left\|\int_{t^{n'}}^{1} f(s)s^{\frac{m}{n}-1} ds\right\|_{Y(0,1)} \leq C\|f\|_{X(0,1)}.$$

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The results - the optimal range partner space

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The results - the optimal range partner space

Theorem (Cianchi, Kerman, Pick – J. d' Anal. Math. 2008).

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where $f^{**}(t) = \frac{1}{t} \int_0^t f^*(s) \, ds$.

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For $p,q\in(0,\infty]$, define

$$||u||_{L^{p,q}(\Omega)} = ||u^*(t)t^{\frac{1}{p}-\frac{1}{q}}||_{L^q(0,1)}.$$

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Note: $L^{p,p} = L^p$, and, for $1 < q < r < \infty$,

$$L^{p,1} \subsetneq L^{p,q} \subsetneq L^{p,r} \subsetneq L^{p,\infty}.$$

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Example: Let \mathfrak{L} be the Laplace transform on (0, 1).

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Theorem (Cianchi, Kerman, Pick – J. d' Anal. Math. 2008).

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Then

$$Tr: W^{m,p}(\Omega) \to \begin{cases} L^{\frac{p(n-1)}{n-mp},p}(\partial\Omega) & \text{ if } p < \frac{n}{m}, \\ L^{\infty,\frac{n}{m};-1}(\partial\Omega) & \text{ if } p = \frac{n}{m}, \\ L^{\infty}(\partial\Omega) & \text{ if } p > \frac{n}{m}. \end{cases}$$

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$$\left(\int_0^1 \left(\frac{u^*(s)}{\log(\frac{2}{s})}\right)^{\frac{n}{m}} \frac{ds}{s}\right)^{\frac{m}{n}}$$

Part 2: traces on linear subspaces of smaller dimensions

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The affine subspace of lower dimension

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Let Ω be a bounded open set with the cone property in \mathbb{R}^n , $n \geq 2$.
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Let Ω be a bounded open set with the cone property in \mathbb{R}^n , $n \geq 2$.

Assume that $d \in \mathbb{N}$ is such that $1 \leq d \leq n$.

We denote by Ω_d be the (non empty) intersection of Ω with a *d*-dimensional affine subspace of \mathbb{R}^n .

The case of general d

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• well defined on Ω_d ,

- well defined on Ω_d ,
- measurable with respect to the *d*-dimensional measure,

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- well defined on Ω_d ,
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- measurable with respect to the *d*-dimensional measure,
- integrable to some power q depending on p, d, m, n.

Observation: increasing the values of m, p causes u to be more regular, hence allows smaller values of d and larger values of q.

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Boundary traces

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As we have seen, boundary traces constitute an important special case with d = n - 1.

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Warning

For a general d, even the very **existence** of a trace is a problem.

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The existence of a trace

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Standard trace theorem:

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The existence of a trace

Standard trace theorem: if

• either $d \ge n - m$ and $p \ge 1$

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Standard trace theorem: if

- either $d \ge n m$ and $p \ge 1$
- or d < n m and $p > \frac{n-d}{m}$,

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Standard trace theorem: if

- either $d \ge n m$ and $p \ge 1$
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then every function $u \in W^{m,p}(\Omega)$ has a trace on Ω_d .

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Moreover,

$$\mathsf{Tr}: W^{m,p}(\Omega) \to L^{rac{dp}{n-mp}}(\Omega_d).$$

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Moreover,

$$\mathsf{Tr}: W^{m,p}(\Omega) \to L^{\frac{dp}{n-mp}}(\Omega_d).$$

Note: The case $m \ge n$ is not interesting since then any function in $W^{m,p}(\Omega)$ is continuous.

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An important difference

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but for d < n - m and $p = \frac{n-d}{m} > 1$, the functions from $W^{m,\frac{n-d}{m}}(\Omega)$ need not admit a trace on Ω_d .

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Our first main aim:

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but for d < n - m and $p = \frac{n-d}{m} > 1$, the functions from $W^{m,\frac{n-d}{m}}(\Omega)$ need not admit a trace on Ω_d .

Our first main aim: to fill this gap.

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The existence of trace - the result

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Let $1 \le m < n, \ 1 \le d \le n - m$.

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Let $1 \le m < n, \ 1 \le d \le n - m$.

Then any function from $W^m L^{\frac{n-d}{m},1}(\Omega)$ admits a trace on Ω_d .

Let $1 \leq m < n$, $1 \leq d \leq n - m$.

Then any function from $W^m L^{\frac{n-d}{m},1}(\Omega)$ admits a trace on Ω_d .

Moreover, $L^{\frac{n-d}{m},1}(\Omega)$ is the largest rearrangement-invariant space with this property.

A working conjecture

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$$\mathsf{Tr}: W^m L^{rac{n-d}{m},1}(\Omega) o L^{rac{n-d}{m},1}(\Omega_d).$$

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$$\mathsf{Tr}: W^m L^{rac{n-d}{m},1}(\Omega) o L^{rac{n-d}{m},1}(\Omega_d).$$

The conjecture was based on our *experience* with other similar embeddings.

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$$\mathsf{Tr}: W^m L^{rac{n-d}{m},1}(\Omega) \to L^{rac{n-d}{m},1}(\Omega_d).$$

The conjecture was based on our *experience* with other similar embeddings.

It is a *lovely* result, but unfortunately *not true*.

A correction

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Let $m, n, d \in \mathbb{N}$, $p \in [1, \infty)$.

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Let $m, n, d \in \mathbb{N}$, $p \in [1, \infty)$. Assume

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Question: Are these results are sharp or can we improve them?

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Question: Are these results are sharp or can we improve them?

Our next aim: to answer this question.

Comment on the assumption

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• every function in $W^{m,1}(\Omega)$ has a trace on Ω_d ,

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$$d \geq n - m$$
?

Because this and only this assumption guarantees that

- every function in $W^{m,1}(\Omega)$ has a trace on Ω_d ,
- therefore every function in W^mX(Ω) has a trace on Ω_d for every rearrangement-invariant space X(Ω).

One more comment on the assumption

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How come that the condition

 $d \ge n - m$

did not jump on us in the case of *boundary* traces?

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$$d \ge n - m$$

did not jump on us in the case of *boundary* traces?

Because in the case d = n - 1 it is equivalent to $m \ge 1$, which is automatically satisfied.

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How come that the condition

$$d \ge n - m$$

did not jump on us in the case of *boundary* traces?

Because in the case d = n - 1 it is equivalent to $m \ge 1$, which is automatically satisfied.

Hence it was still there, but invisible.

The classical trace embeddings improved

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Let $m, n, d \in \mathbb{N}$, $m < n, p \in [1, \infty)$.

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The classical trace embeddings improved

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Then

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Let $m, n, d \in \mathbb{N}$, $m < n, p \in [1, \infty)$. Assume

$$d \ge n - m$$
.

Then

$$Tr: W^{m,p}(\Omega) \to \begin{cases} L^{\frac{pd}{n-mp},p}(\Omega_d) & \text{ if } p < \frac{n}{m}, \\ L^{\infty,\frac{n}{m};-1}(\Omega_d) & \text{ if } p = \frac{n}{m}, \\ L^{\infty}(\Omega_d) & \text{ if } p > \frac{n}{m}. \end{cases}$$

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The optimal trace target

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Given $n, m, d \in \mathbb{N}$ and a rearrangement-invariant space $X(\Omega)$.

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Given $n, m, d \in \mathbb{N}$ and a rearrangement-invariant space $X(\Omega)$. Assume $1 \leq m < n, d \geq n - m$.

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 $\operatorname{Tr}: W^m X(\Omega) \to X^m_{d,n}(\Omega_d),$

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Given $n, m, d \in \mathbb{N}$ and a rearrangement-invariant space $X(\Omega)$. Assume $1 \leq m < n, d \geq n - m$. Then

$$\operatorname{Tr}: W^m X(\Omega) \to X^m_{d,n}(\Omega_d),$$

where

$$\|g\|_{(X_{d,n}^m)'(\Omega_d)} = \left\| t^{-1+\frac{m}{n}} \int_0^{t^{\frac{d}{n}}} g^*(s) ds \right\|_{X'(0,|\Omega_d|)}$$

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Moreover, $X_{d,n}^m(\Omega_d)$ is the *smallest* rearrangement-invariant space with this property.

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Trace embedding into L^{∞}

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$$\begin{aligned} \mathsf{Tr}: W^m X(\Omega) \to L^\infty(\Omega_d) \\ \left\| t^{-1+\frac{m}{n}} \right\|_{X'(0,1)} < \infty. \end{aligned}$$

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The reduction principle

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With all the parameters as above,

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With all the parameters as above, the trace embedding

 $\operatorname{Tr}: W^m X(\Omega) \to Y(\Omega_d)$

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With all the parameters as above, the trace embedding

$$\operatorname{Tr}: W^m X(\Omega) \to Y(\Omega_d)$$

holds for some rearrangement-invariant space $Y(\Omega_d)$

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With all the parameters as above, the trace embedding

$$\operatorname{Tr}: W^m X(\Omega) \to Y(\Omega_d)$$

holds for some rearrangement-invariant space $Y(\Omega_d)$ if and only if

$$\left\|\int_{t^{\frac{n}{d}}}^{1} g(s)s^{-1+\frac{m}{n}} \, ds\right\|_{Y(0,1)} \leq C \|g\|_{X(0,1)}$$

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Comments on the reduction principle

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Reduction principles are by now classical for **full Sobolev embeddings**.

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- Talenti, Ann. Mat. Pura Appl. 1976,
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When functions do not vanish on $\partial\Omega$, but still m = 1, variants of the result are available, using relative isoperimetric inequality in Ω and a rearrangement inequality for the gradient, requiring some regularity on Ω , see e.g.

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- Cianchi, Edmunds, Gurka, Math. Nachr. 1996,
- Cianchi, Pick, Ark. Mat. 1998.

The situation of traces

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Note (important): None of this is applicable to traces,

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Our approach:

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This was respectively done in

• (a) Cianchi, Pick, Slavíková, Adv. Mat. 2015,

Our approach: a two-step iteration method, which relies on the characterization of

- (a) the optimal rearrangement-invariant target space for a full Sobolev embedding of any order,
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- (b) Cianchi, Kerman, Pick, J. Anal. Math. 2008.

The situation of traces

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Note: A remarkable feature of this approach is that any composition of Sobolev and trace embeddings with optimal targets ends up again having optimal target.

The stability theorem

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 $1 \leq d \leq l \leq n, \quad l \geq n-k, \quad d \geq l-h, \quad \Omega_d \subset \Omega_l.$

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$$1 \leq d \leq l \leq n, \quad l \geq n-k, \quad d \geq l-h, \quad \Omega_d \subset \Omega_l.$$

Let $X(\Omega)$ be a rearrangement-invariant space.

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$$1 \leq d \leq l \leq n, \quad l \geq n-k, \quad d \geq l-h, \quad \Omega_d \subset \Omega_l.$$

Let $X(\Omega)$ be a rearrangement-invariant space. Then

$$(X_{l,n}^k)_{d,l}^h(\Omega_d) = X_{d,n}^{k+h}(\Omega_d).$$

A comment on the preceding theorem

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The validity of the iteration principle in this generality is quite striking. Though it works in particular situations, see e.g.

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it is not true in general, as the following examples show.

An example

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Let $2 \leq d \leq n$.

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$$\mathsf{Tr}: \mathcal{W}^{n,1}(\Omega) o L^\infty(\Omega_d).$$

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$$\mathsf{Tr}: W^{n,1}(\Omega) \to L^{\infty}(\Omega_d).$$

However, iterating known *sharp embeddings in Orlicz spaces*, we get only

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$$\mathsf{Tr}: W^{n,1}(\Omega) \to L^{\infty}(\Omega_d).$$

However, iterating known *sharp embeddings in Orlicz spaces*, we get only

$$W^{n,1}(\Omega) \xrightarrow{\mathsf{Tr}} W^{1,d}(\Omega_d) \to \exp L^{\frac{d}{d-1}}(\Omega_d).$$

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Another example, even more enlightening

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Another example, even more enlightening

Let $n \geq 3$, m = 2.

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Another example, even more enlightening

Let $n \ge 3$, m = 2. Let $\max\{2, n - 2\} \le d \le n$.

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$$\operatorname{Tr}: W^{2, \frac{n}{2}}(\Omega) \to \exp L^{\frac{n}{n-2}}(\Omega_d).$$

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However, iterating known *sharp embeddings in Orlicz spaces*, we get either

$$W^{2,\frac{n}{2}}(\Omega) \xrightarrow{\mathsf{Tr}} W^{1,d}(\Omega_d) \hookrightarrow \exp L^{\frac{d}{d-1}}(\Omega_d)$$

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$$\operatorname{Tr}: W^{2, \frac{n}{2}}(\Omega) \to \exp L^{\frac{n}{n-2}}(\Omega_d).$$

However, iterating known *sharp embeddings in Orlicz spaces*, we get either

$$W^{2,\frac{n}{2}}(\Omega) \xrightarrow{\mathsf{Tr}} W^{1,d}(\Omega_d) \hookrightarrow \exp L^{\frac{d}{d-1}}(\Omega_d)$$

or

$$W^{2,\frac{n}{2}}(\Omega) \hookrightarrow W^{1,n}(\Omega) \xrightarrow{\mathsf{Tr}} \exp L^{\frac{n}{n-1}}(\Omega_d).$$

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Comments on the preceding example

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$$\exp L^{\frac{n}{n-2}}(\Omega_d) \hookrightarrow \exp L^{\frac{d}{d-1}}(\Omega_d) \hookrightarrow \exp L^{\frac{n}{n-1}}(\Omega_d),$$

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$$\exp L^{\frac{n}{n-2}}(\Omega_d) \hookrightarrow \exp L^{\frac{d}{d-1}}(\Omega_d) \hookrightarrow \exp L^{\frac{n}{n-1}}(\Omega_d),$$

first embedding being strict when $[n, d] \neq [4, 2]$,

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$$\exp L^{\frac{n}{n-2}}(\Omega_d) \hookrightarrow \exp L^{\frac{d}{d-1}}(\Omega_d) \hookrightarrow \exp L^{\frac{n}{n-1}}(\Omega_d),$$

first embedding being strict when $[n, d] \neq [4, 2]$, and second being strict when d < n.

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Thank you for your attention, this is all.

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