

# **Numerical study of a normally hyperbolic cylinder in the RTBP**

**Jacques Féjoz, Marcel Guardia, Pablo Roldán, Vadim Kaloshin**

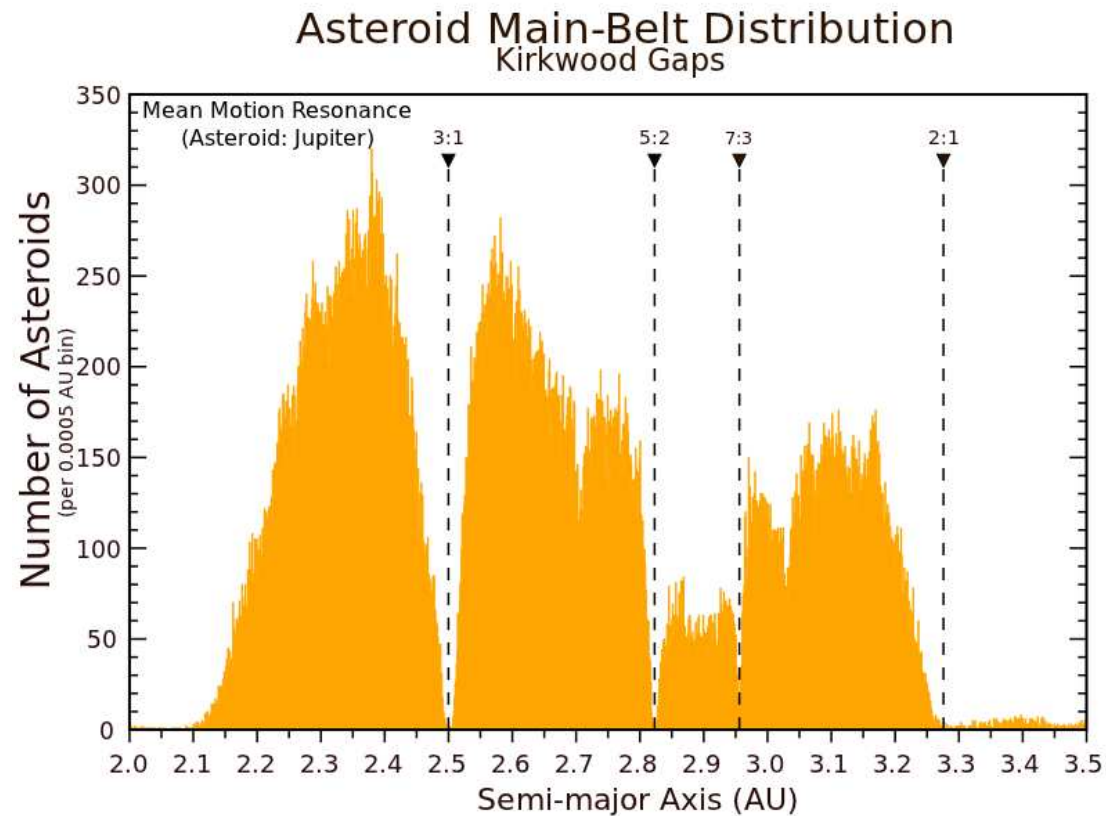
## Mechanism of Instability

- Consider the three-body problem consisting of the Sun, Jupiter, and an Asteroid which moves on (approximate) ellipses.
- A possible source of instabilities are *orbital resonances* between the frequencies of Jupiter and the Asteroid.
- Jupiter and the Asteroid are regularly in the same relative position. Over a long time interval, Jupiter's influence piles up and modifies the eccentricity of the Asteroid.
- According to Kepler's third law, resonances take place when the semi-major axis  $a$  satisfies

$$a^{3/2} \approx \frac{\omega_J}{\omega_A} \in \mathbb{Q}.$$

## Kirkwood Gaps

- The Asteroid Belt is located between the orbits of Mars and Jupiter. The distribution of asteroids presents several gaps precisely at the resonances.



## Kirkwood Gaps

- It is believed that these gaps are due to instability mechanisms.
- This motivates us to study the 3:1 resonance

$$a^{3/2} \approx \frac{\omega_J}{\omega_A} = \frac{1}{3}.$$

**Theorem 1 (FGKR, 2011)** *Consider the elliptic RTBP with mass ratio  $\mu = 10^{-3}$  and eccentricity of Jupiter  $e_0 > 0$ .*

*For  $e_0$  small enough, there exist  $T > 0$  and a trajectory whose eccentricity  $e(t)$  satisfies*

$$e(0) < 0.55 \quad \text{and} \quad e(T) > 0.85,$$

*while its semi-major axis stays almost constant*

$$a(t) \approx 3^{-2/3}.$$

## Summary of Proof

1. Prove the existence of a normally hyperbolic invariant cylinder  $\Lambda$ , which exists near the resonance.
2. Establish transversality of its stable and unstable invariant manifolds.
3. Compare inner and outer dynamics on  $\Lambda$ , and check that they do not have invariant circles.
4. Construct diffusing orbits by shadowing a composition of outer and inner maps.

- When  $\mu > 0$ , all known analytical techniques fail to estimate the splitting of separatrices (even for  $e_0 = 0$ ).
- We set  $\mu = 10^{-3}$ , and we show numerically that the splitting is not too small.
- Since the splitting varies smoothly with respect to  $e_0$ , it suffices to estimate the splitting for  $e_0 = 0$  (i.e. for the *circular* problem)!!

**Ansatz 1** Consider the circular RTBP with mass ratio  $\mu = 10^{-3}$  and Hamiltonian  $H$ .

In each energy level  $H \in [H_-, H_+]$  there exists a hyperbolic periodic orbit  $\lambda_H(t)$  which satisfies

$$|L_H(t) - 3^{-1/3}| < 50\mu \quad \text{for all } t \in \mathbb{R}.$$

Each  $\lambda_H$  has two branches of stable and unstable invariant manifolds  $W^{s,j}(\lambda_H)$  and  $W^{u,j}(\lambda_H)$  for  $j = 1, 2$ . For each  $H \in [H_-, H_+]$  either

$$W^{s,1}(\lambda_H) \cap W^{u,1}(\lambda_H) \text{ transversally}$$

or

$$W^{s,2}(\lambda_H) \cap W^{u,2}(\lambda_H) \text{ transversally.}$$



## Comments

- We verify the Ansatz numerically.
- Numerical analysis has several sources of error:
  - roundoff errors in computer arithmetic,
  - numerical approximation of ideal objects.

We evaluate such errors and check that they are appropriately small.

- Goal: to keep our numerics simple and convincing.
- Roldán and Zgliczynski are working towards a fully rigorous Computer-Assisted proof.

## Choice of Coordinates

- Circular RTBP in rotating Cartesian coordinates

$$H(x, y, p_x, p_y) = \frac{1}{2}(p_x^2 + p_y^2) + yp_x - xp_y - \frac{\mu_1}{r_1} - \frac{\mu_2}{r_2},$$

$$r_1^2 = (x - \mu_2)^2 + y^2,$$

$$r_2^2 = (x + \mu_1)^2 + y^2.$$

- Sun is located to the left of the origin:  $\mu_1 = \mu$  is the small mass and  $\mu_2 = 1 - \mu$  is the large mass.

## Symmetries of the System

- The system is reversible with respect to the involution

$$R(x, y, p_x, p_y) = (x, -y, -p_x, p_y).$$

- Thus, a solution is symmetric if and only if it intersects the *symmetry plane*

$$\{y = 0, p_x = 0\} \equiv \{y = 0, \dot{x} = 0\}.$$

## Conservation of Energy

- The circular problem has a conserved quantity, the Jacobi constant  $C$ .
- When the Hamiltonian is constant  $H = H_0$ , we have

$$H_0 = -\frac{C - \mu_1\mu_2}{2}.$$

- We will refer to  $H_0$  as the *energy* of the system.
- It is natural to fix  $H = H_0$  and perform our analysis for  $H_0$ . Then, we let  $H$  vary and repeat our computations for  $H \in [H_-, H_+]$ .

## Computation of Periodic Orbits

- Fix  $H = H_0$ , and look for an (almost) resonant periodic orbit  $\lambda_H(t)$  in this level of energy.
- As a first approximation, consider the 2BP and look for the resonant periodic orbit  $\tilde{\lambda}_H(t)$  in the level of energy  $H_{2BP} = H_0$ .
- To simplify numerics, we choose a *symmetric* periodic orbit.
- Refine  $\tilde{\lambda}_H(t)$  into  $\lambda_H(t)$  in the R3BP using a Newton method.

## Poincaré Map

- Consider the RTBP in Cartesian coordinates.
- Define the *Poincaré section*

$$\Sigma_+ = \{y = 0, \dot{y} > 0\}$$

with *Poincaré map*

$$P : \Sigma_+ \rightarrow \Sigma_+.$$

- On the section, the variable  $p_y$  can be eliminated. We can recover it from the energy condition

$$H(x, y, p_x; p_y) = H_0,$$

since  $\partial_{p_y} H = \dot{y} \neq 0$ .

- Hence, at each energy level,  $P = P(x, p_x)$  is a 2-dimensional symplectic map.

## Fixed Point Equation

- In the rotating frame, a 3:1 resonant periodic orbit makes 2 turns around the origin.
- One can look for a periodic point  $a = (x, p_x)$  of the Poincaré map

$$a = P^2(a),$$

or equivalently, a fixed point of the *iterated Poincaré map*  $\mathcal{P}$

$$a = \mathcal{P}(a).$$

- However, we want a *symmetric* periodic orbit. Thus, after half a period, it must intersect the symmetry plane  $\{y = 0, p_x = 0\}$ :

$$\Pi_{p_x} \circ P(a) = 0.$$

- Solve this 1-d equation using a Newton method.

## Family of Periodic Orbits

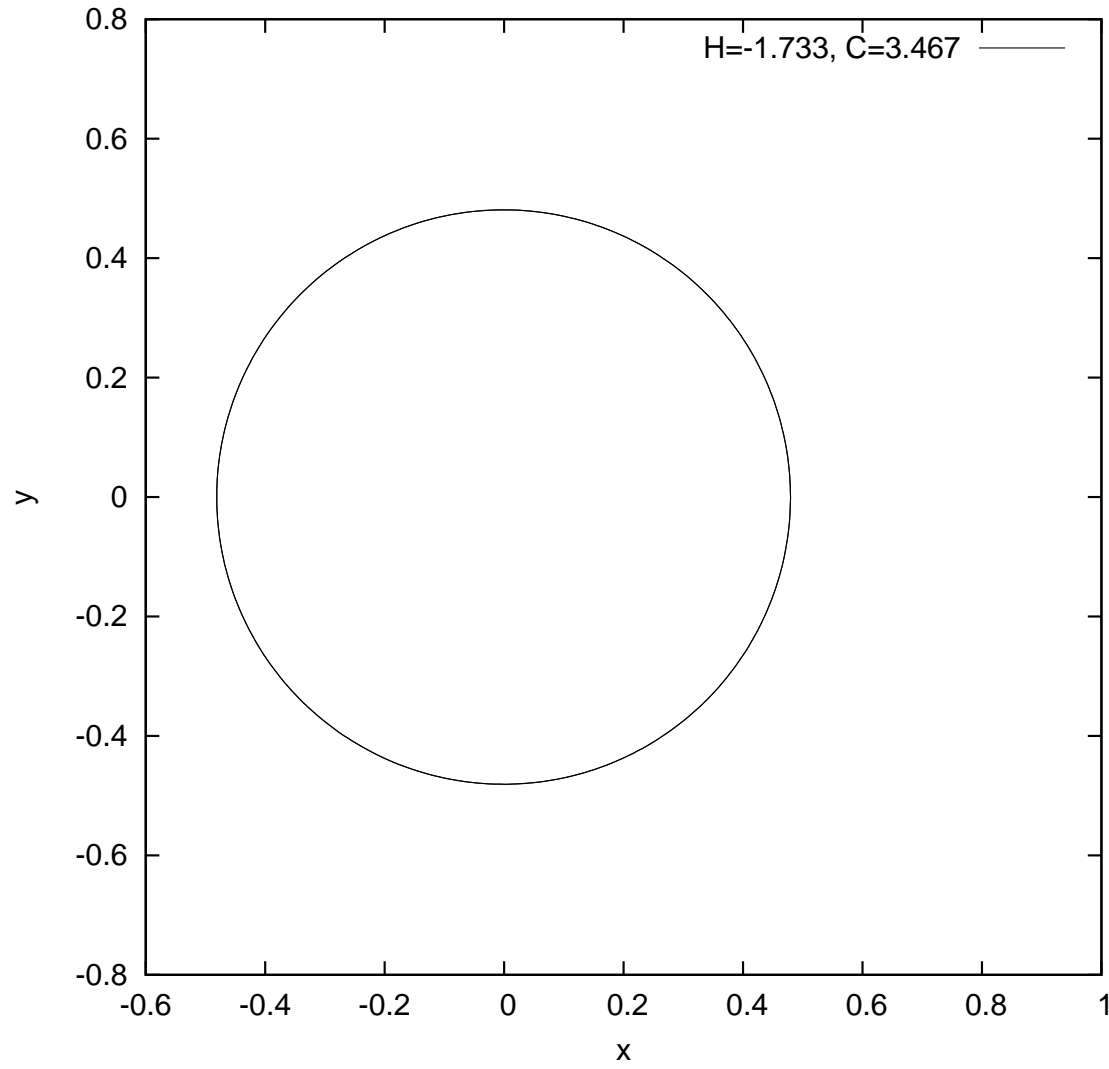
- Finally, let  $H$  vary in the range  $[H_-, H_+] = [-1.733, -1.405]$  to obtain the family of (almost) resonant periodic orbits

$$\Lambda_0 = \bigcup_{H \in [H_-, H_+]} \lambda_H.$$

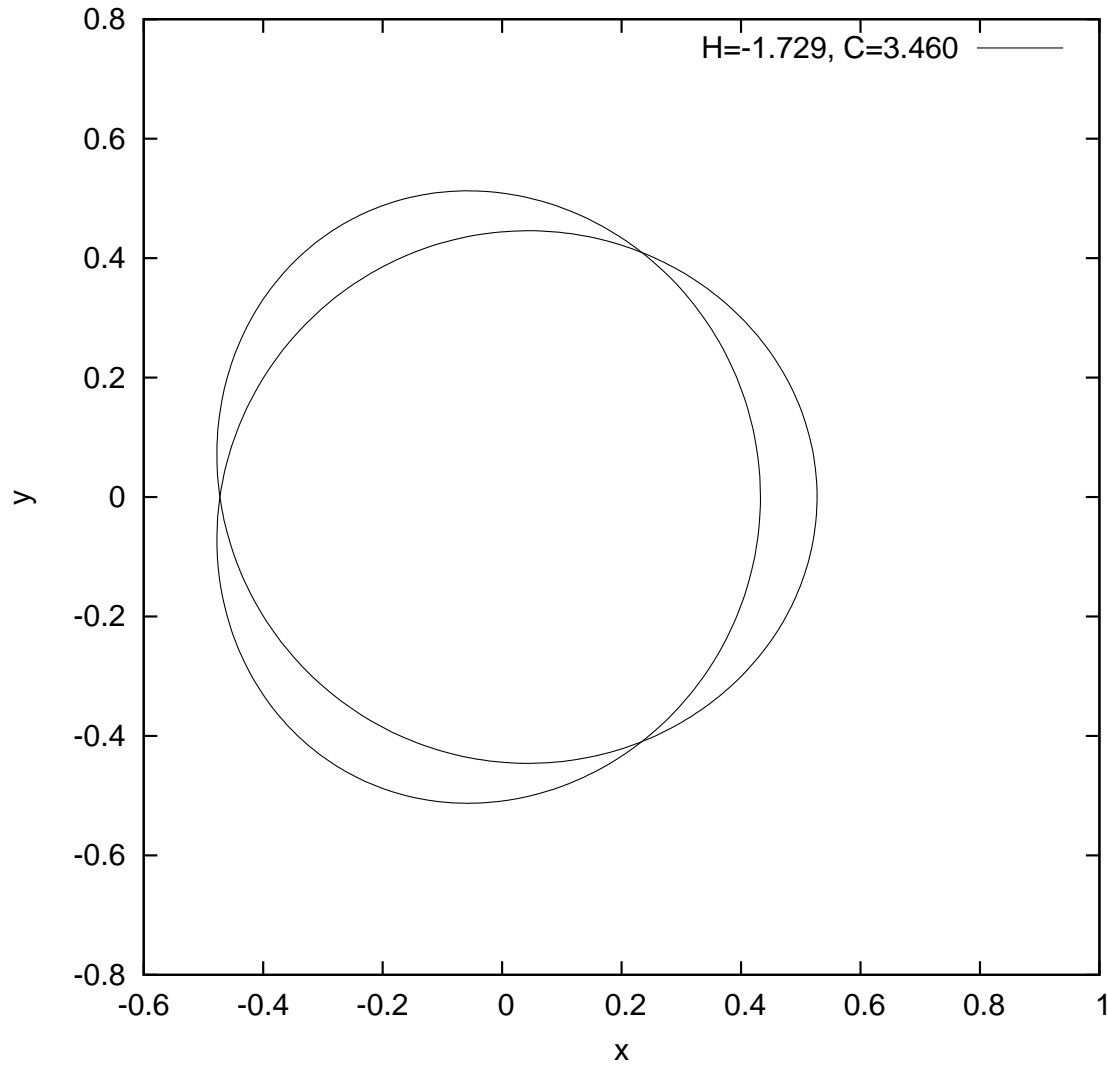
- $\Lambda_0$  is a family of symmetric periodic orbits around the Sun.
- Accuracy in the computation of periodic orbits:  $10^{-14}$ .



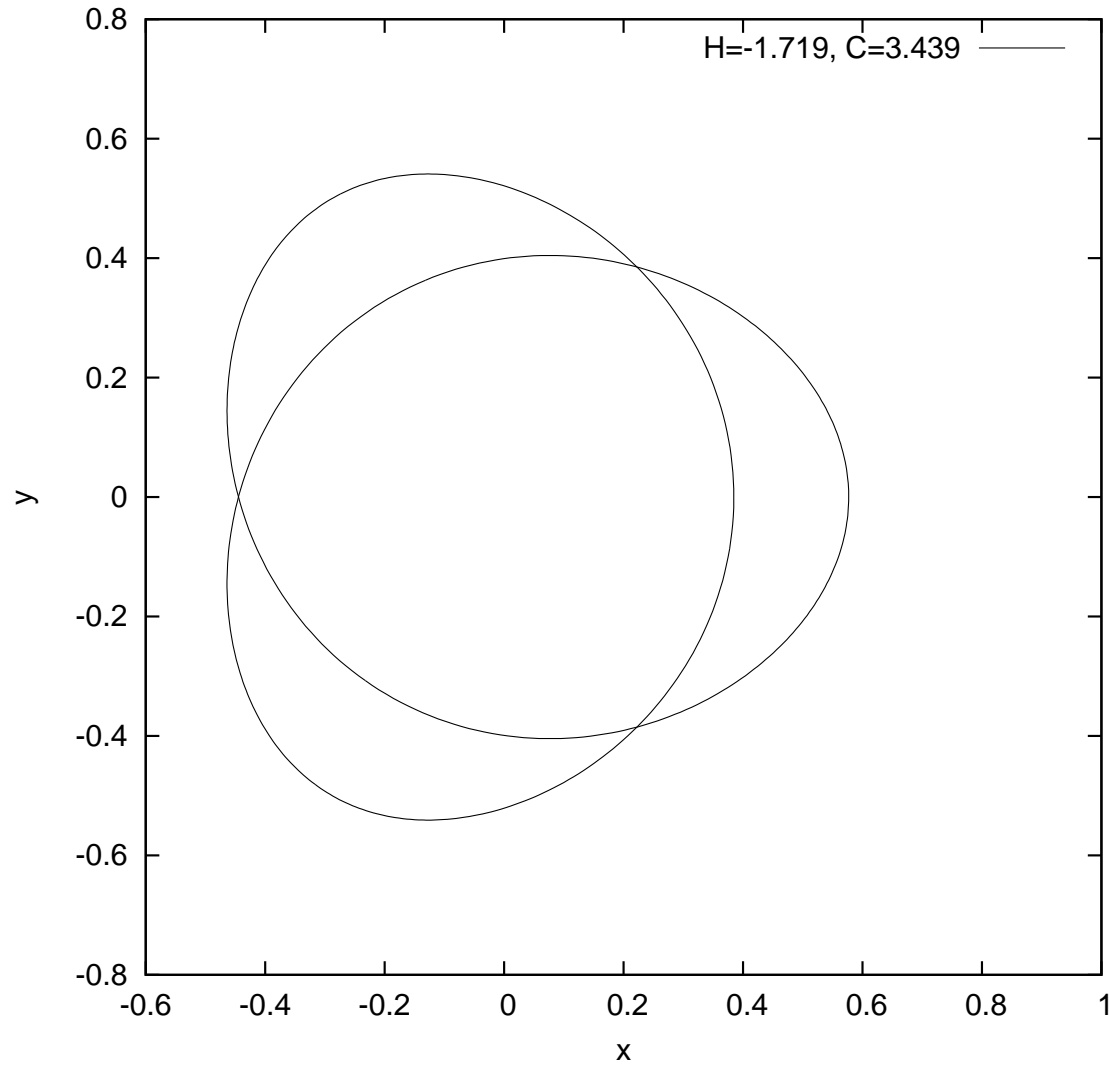
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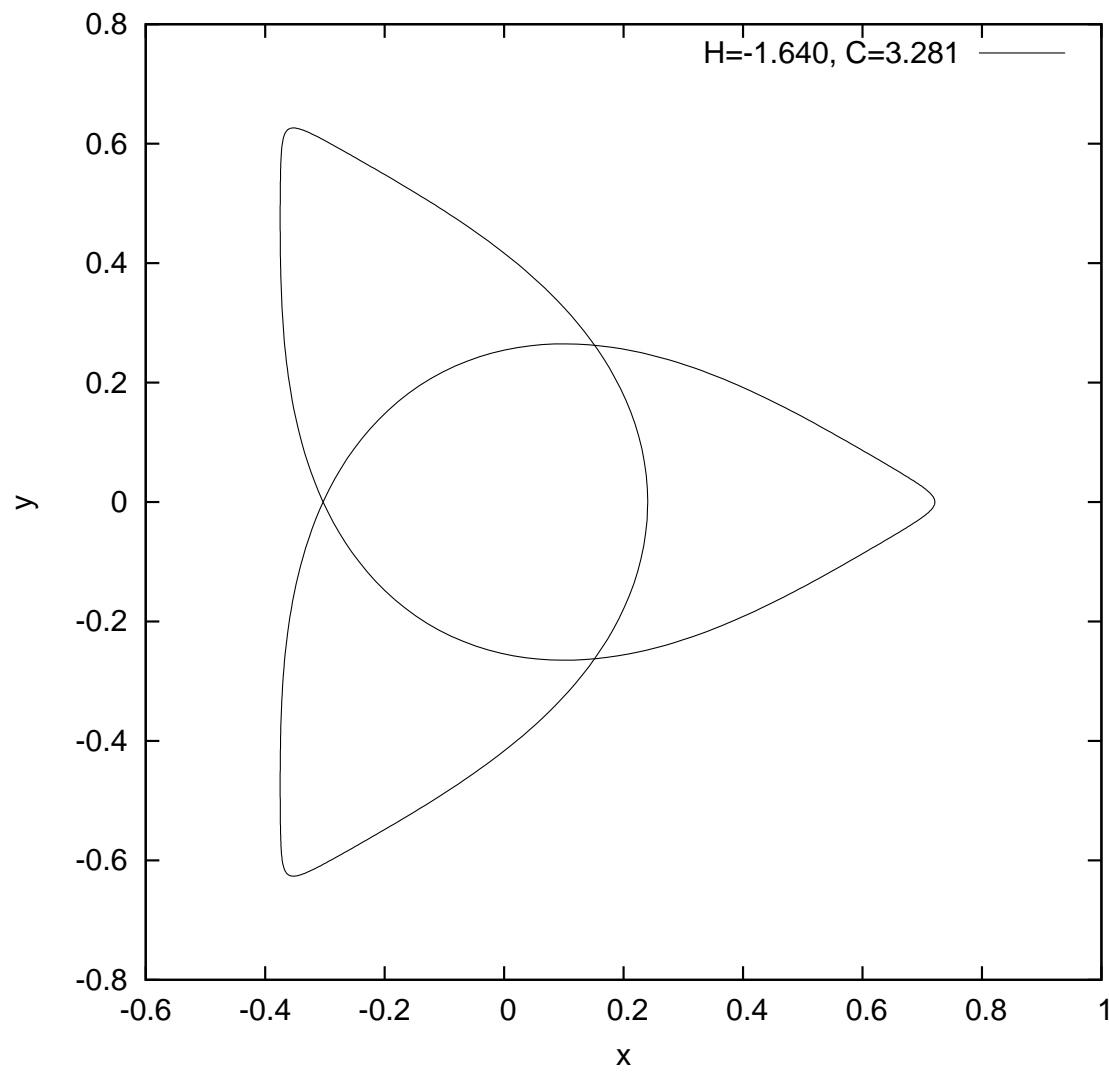
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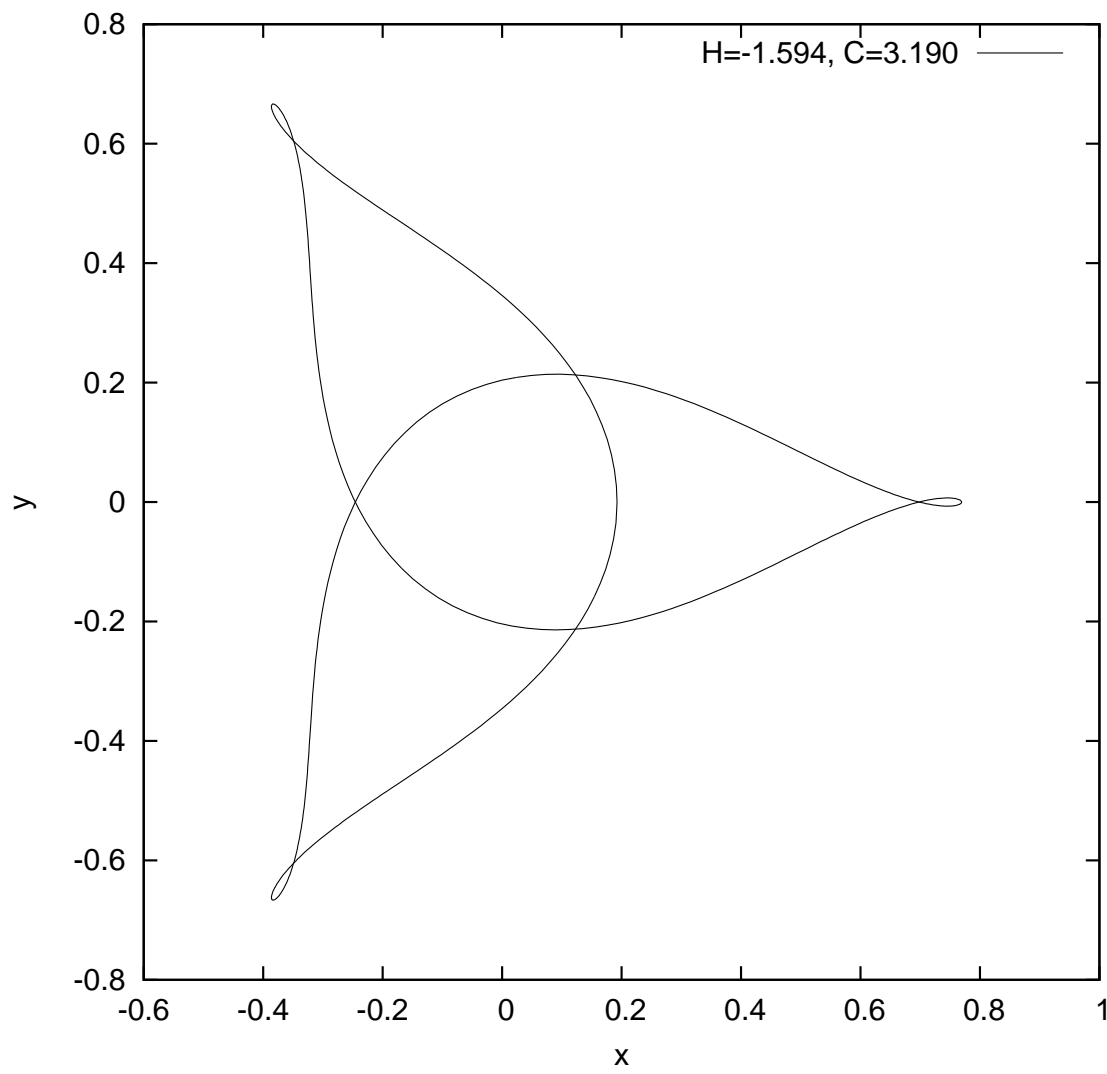
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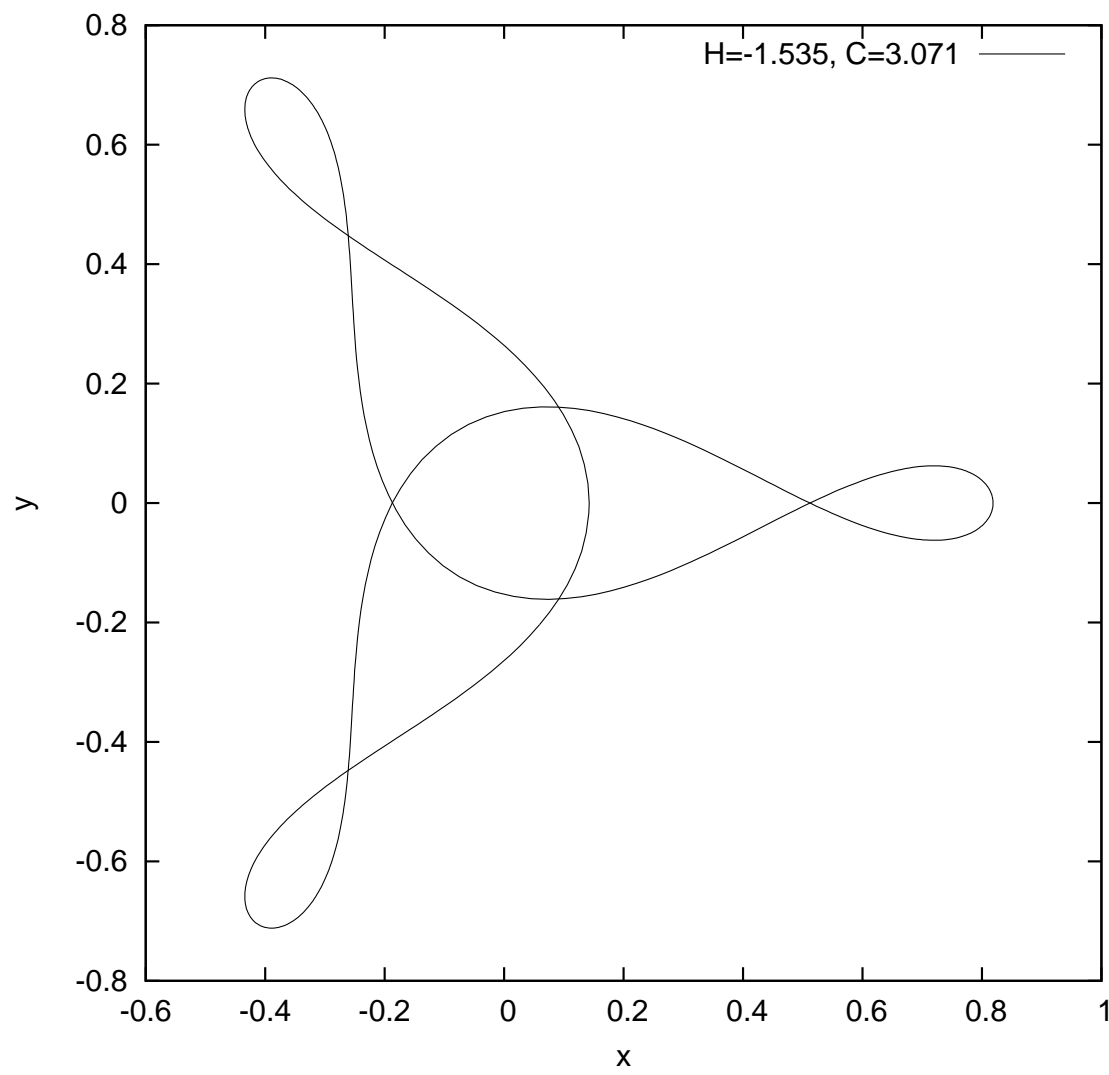
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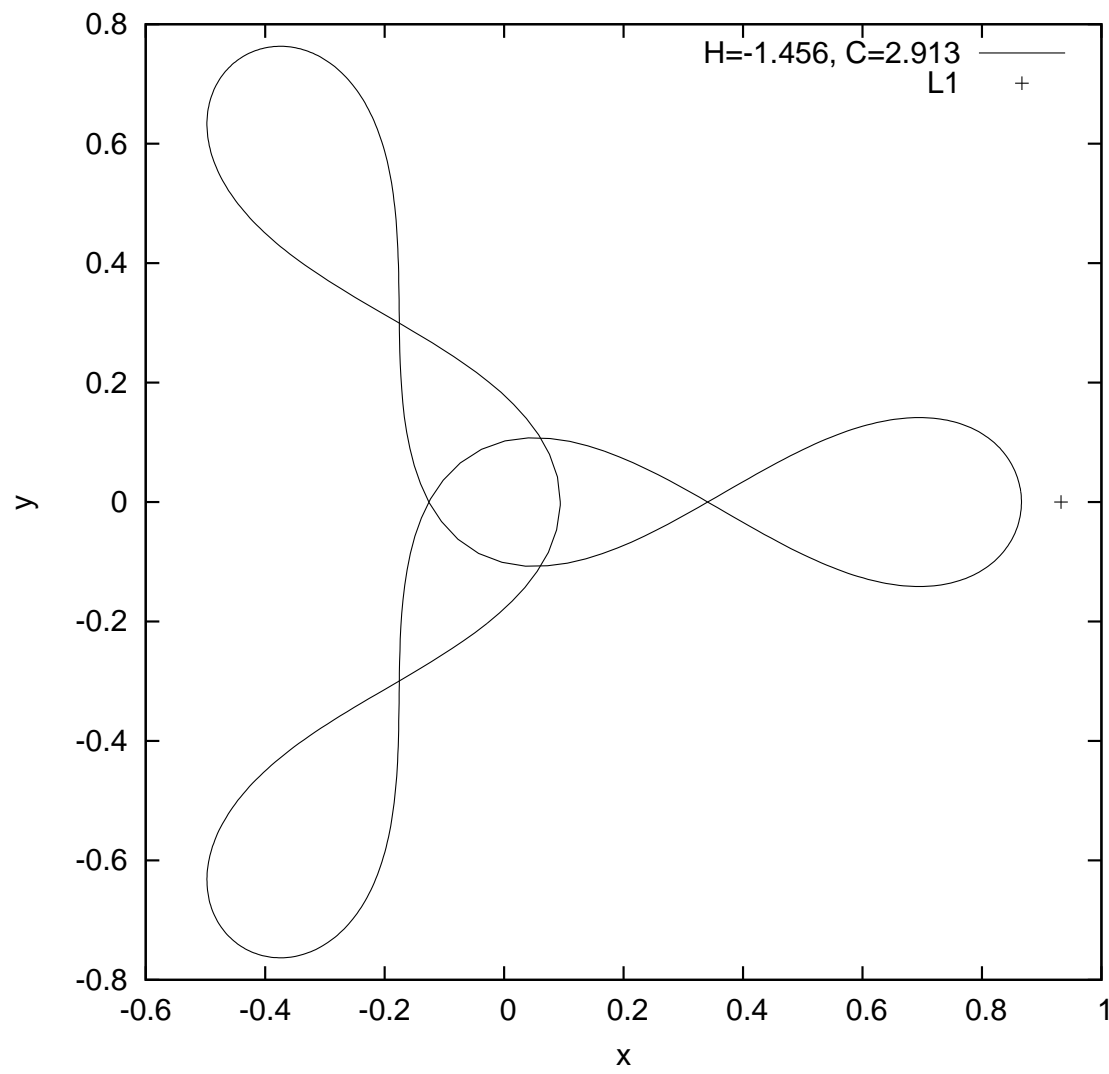
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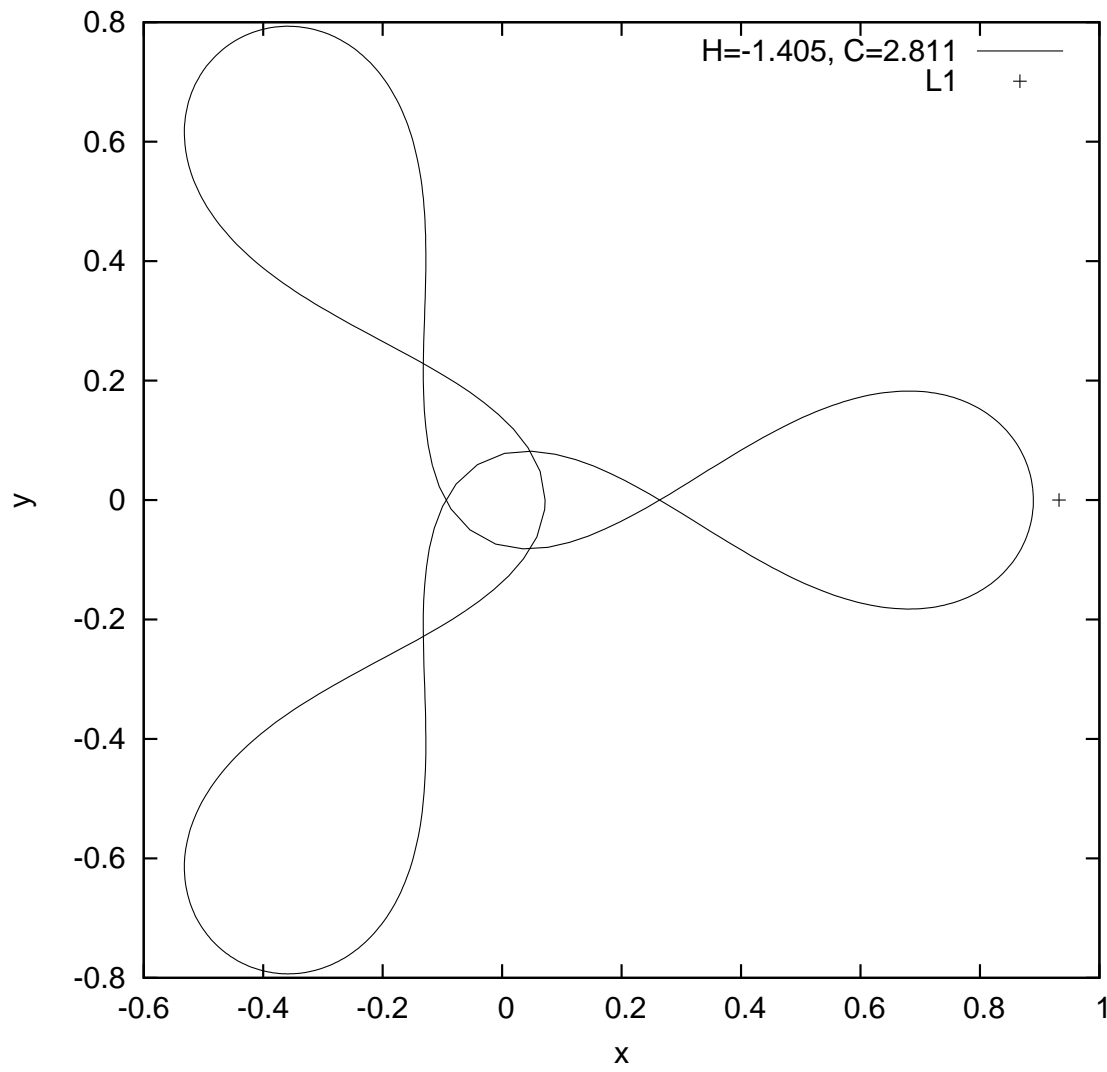
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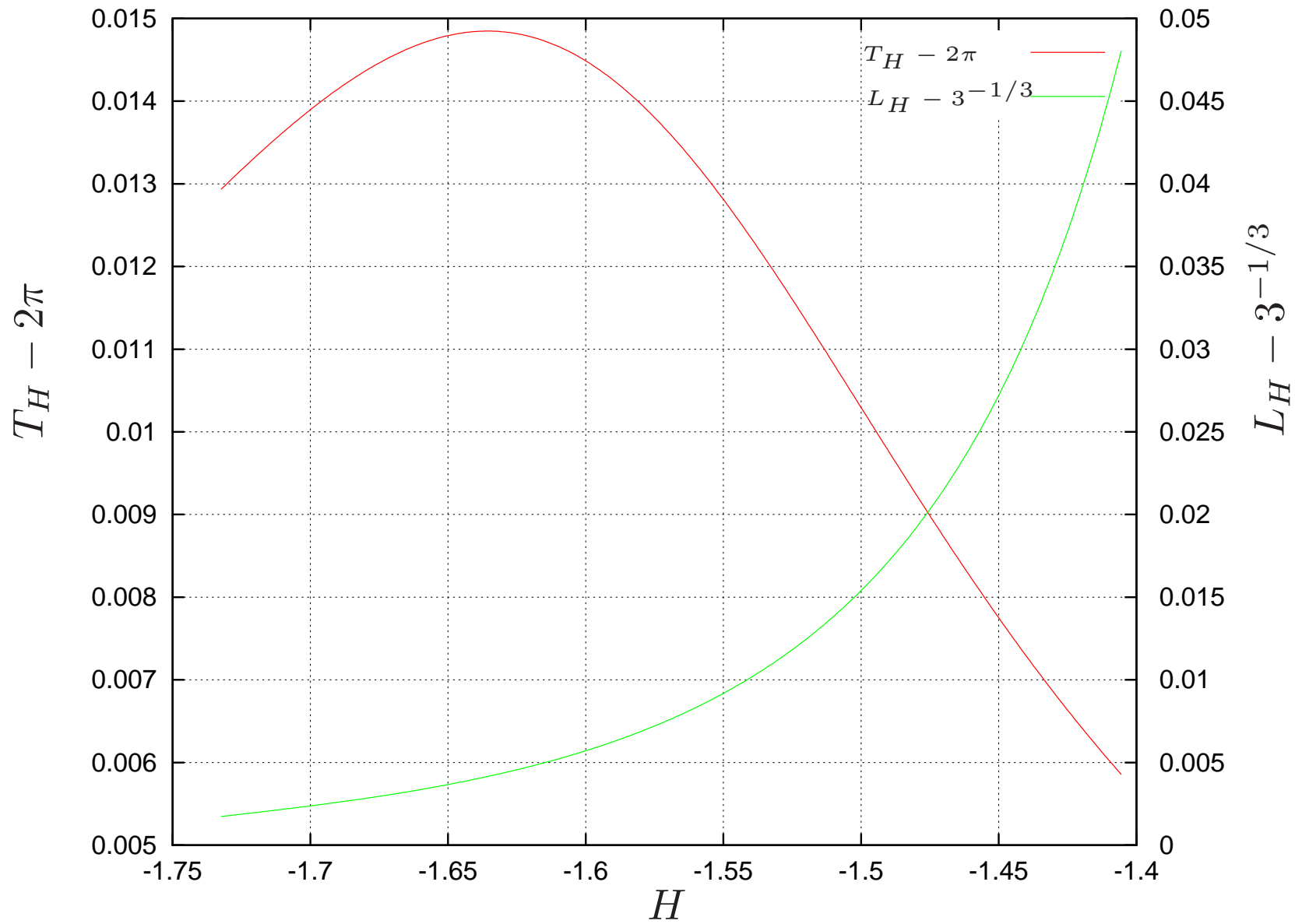


## In the Loop

- When  $H \approx -1.6$ , the periodic orbit develops loops. The reason is the following:
- Near the apohelion, the sidereal velocity of Asteroid becomes smaller than the velocity of rotating frame  $\implies$  relative velocity is negative, and orbit is direct.
- At other parts of the orbit, the sidereal velocity of Asteroid is larger than the velocity of rotating frame  $\implies$  relative velocity is positive, and orbit is retrograde.
- Loops are inherent to this resonant family of periodic orbits in the rotating system, even for the 2BP.

## In the Loop

- When the loops appear, there is one more iterate of the Poincaré map. However, the family is continuous with respect to the period  $T_H$ .
- This is an artifact produced by rotating coordinates. One can get rid of this technical problem by redefining the Poincaré map in a suitable way.



## Numerical Bounds

- The period stays close to the resonant period of the unperturbed system

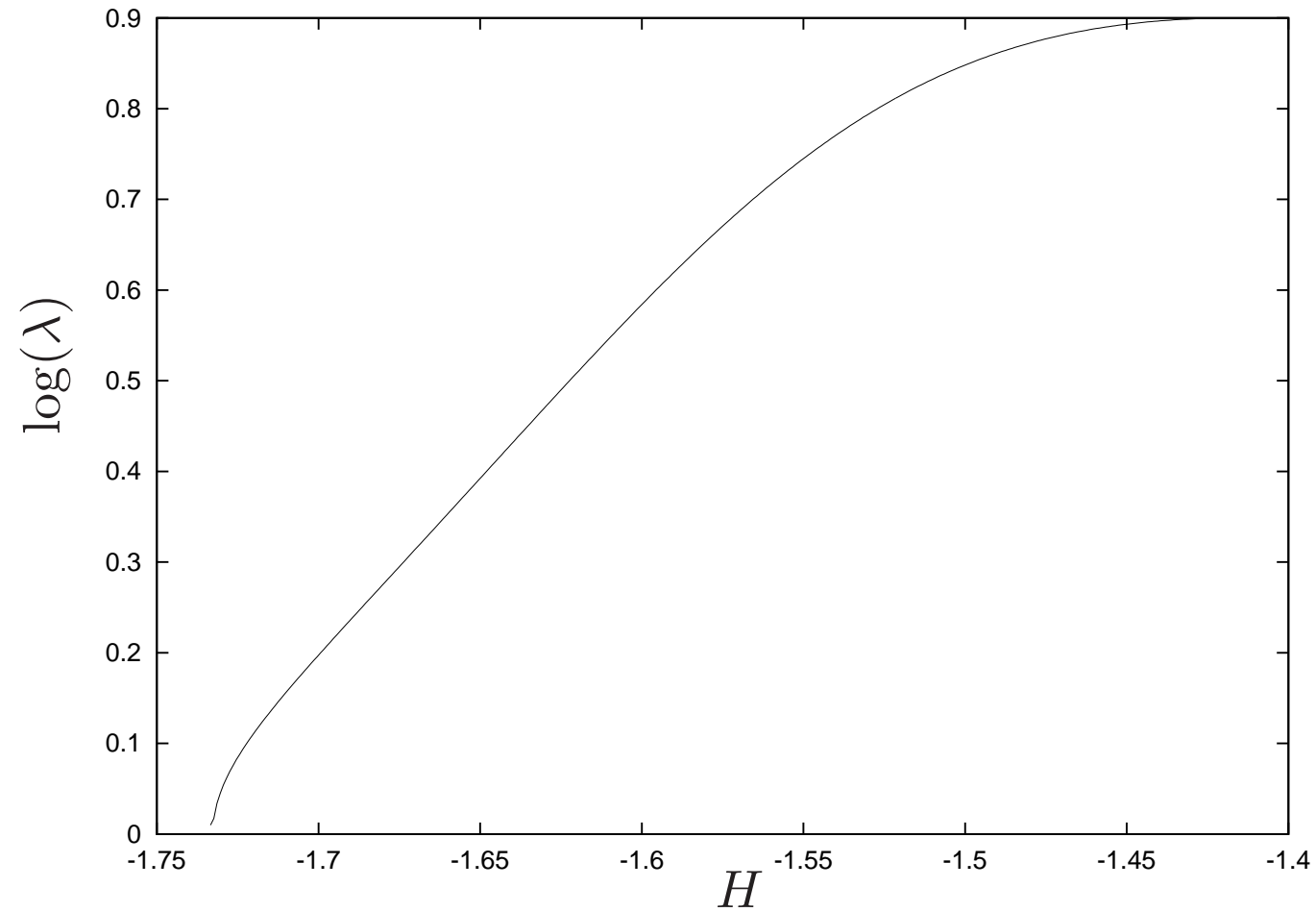
$$|T_H - 2\pi| < 15\mu.$$

- $L_H(t)$  stays close to the resonant value  $3^{-1/3}$ :

$$\max_{t \in [0, T_H]} |L_H(t) - 3^{-1/3}| < 50\mu.$$

## Stability of Periodic Orbits

- Compute eigenvalues  $\lambda, \lambda^{-1}$  of  $D\mathcal{P}(a)$ .



## Stability of Periodic Orbits

- The family of periodic orbits is
  - less hyperbolic when  $H \rightarrow H_-$ , or equivalently  $e \rightarrow 0$ .
  - more hyperbolic when  $H \rightarrow H_+$ , or equivalently  $e \rightarrow 1$ .
- Since the system is close to integrable ( $\mu$  is small), one expects eigenvalues  $\lambda, \lambda^{-1}$  close to unity.
- Nevertheless, non-integrability is noticeable in the picture. This is due to the effect of the perturbing body (Jupiter) on the Asteroid.

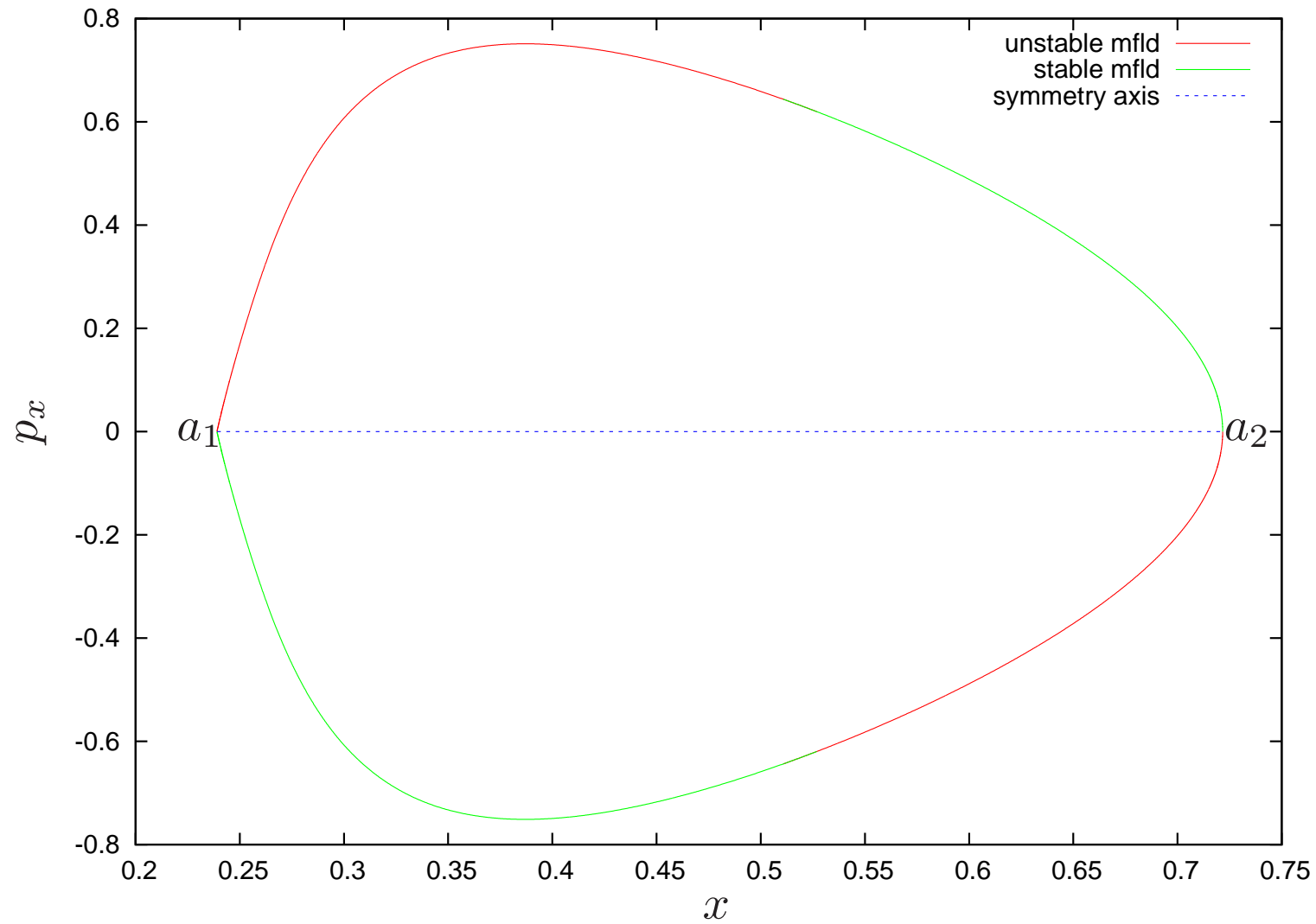
## Computation of Invariant Manifolds

- Fix  $H = H_0$ , and look for the (1-d) invariant manifolds  $W^u(a), W^s(a)$  of the hyperbolic fixed point  $a$  in this level of energy.
- Approximate the local invariant manifolds using a linear segment. The error committed in the linear approximation is controlled:

$$err(\eta) = \|\mathcal{P}(a + \eta v) - (a + \lambda\eta v)\| \in \mathcal{O}(\eta^2).$$

- Globalize the manifolds using the Poincaré map.
- Choose a displacement  $\eta$  such that  $err(\eta) < 10^{-8}$  uniformly in  $H$ .

## Invariant Manifolds for $H = -1.733$





## New Poincaré Section

- Notice that the fixed points  $a_1, a_2$  are in the symmetry plane by construction.
- Unfortunately, the homoclinic points are *not* in the symmetry plane.
- Consider the new Poincaré section

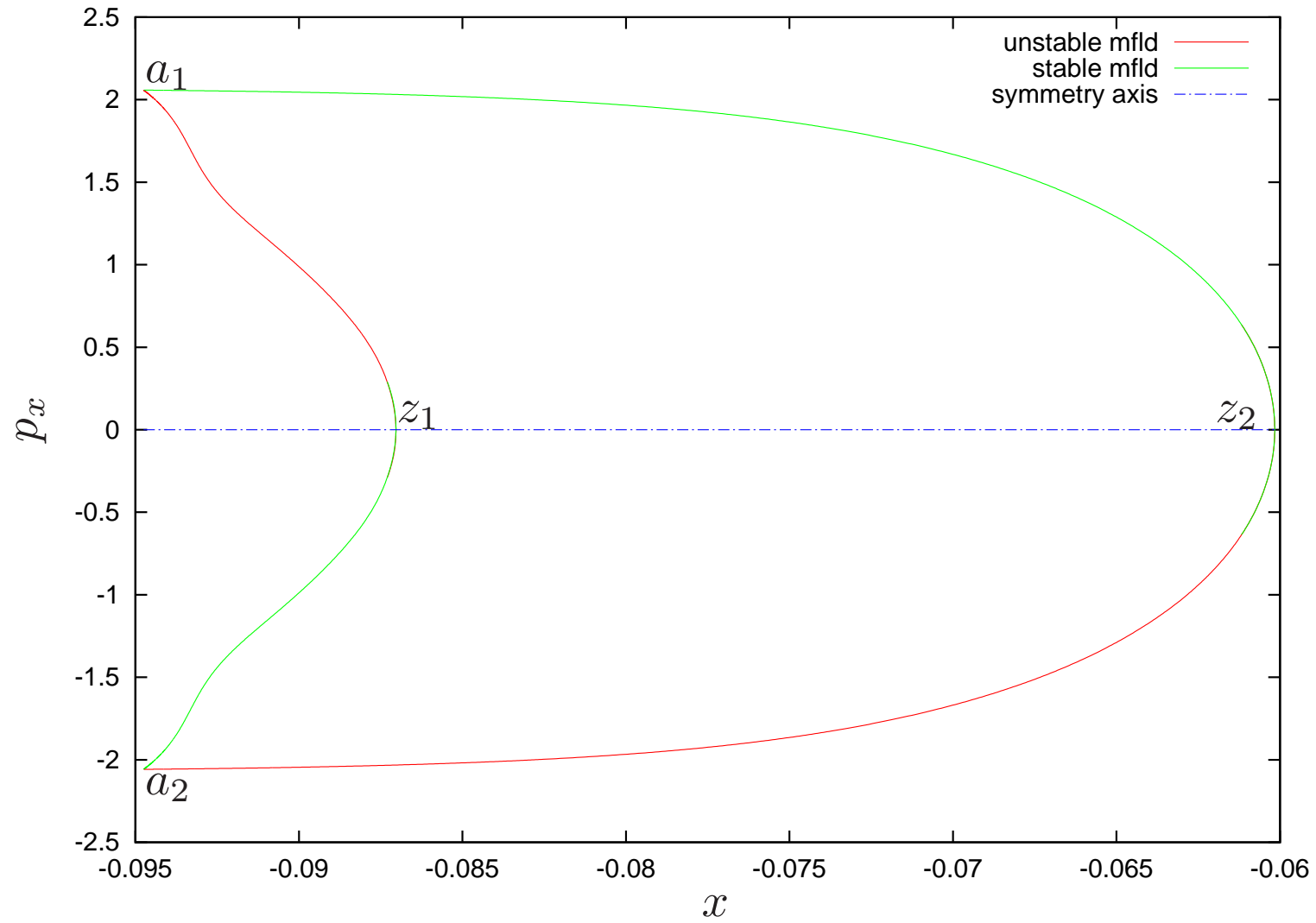
$$\Sigma_- = \{y = 0, \dot{y} < 0\}.$$

- In the new section  $\Sigma_-$ , the fixed points  $a_1, a_2$  are reversible:

$$R(a_1) = a_2.$$

Hence, the homoclinic points are now in the symmetry plane.

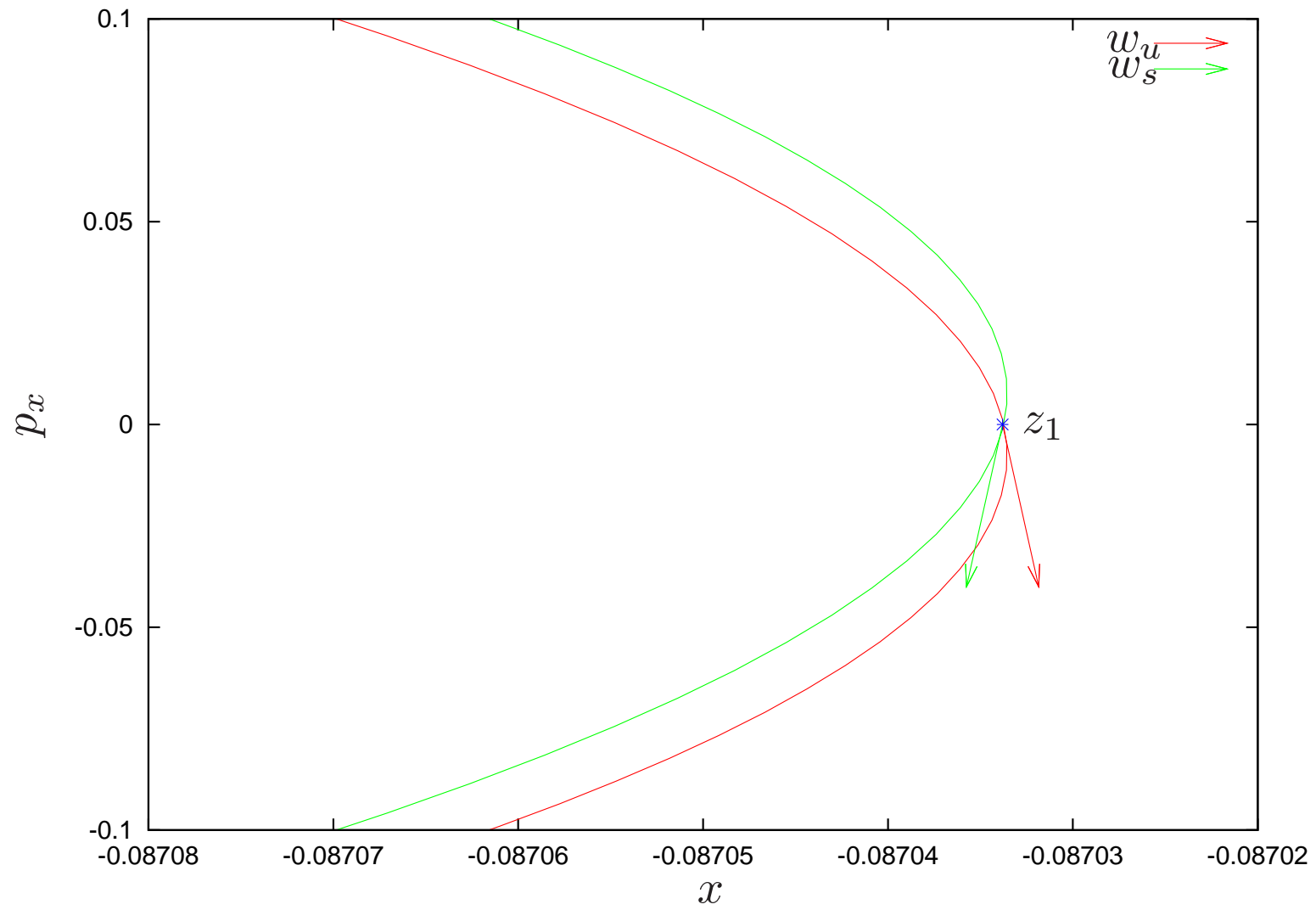
## Invariant Manifolds on the section $\Sigma_-$



## Homoclinic Points

- Thanks to reversibility, the intersection of the manifolds with the symmetry axis  $p_x = 0$  is a homoclinic point.
- We consider two homoclinic points:
  - $z_1$  corresponds to the “inner” splitting,
  - $z_2$  corresponds to the “outer” splitting.
- Compute  $z_1, z_2$  using a standard bisection method.
- We verify that  $z_1, z_2$  lie on the symmetry axis with tolerance  $10^{-10}$  uniformly in  $H$ .

# Inner Splitting for $H = -1.405$



## Computation of Splitting Angle

- Look for the tangent vectors  $w_u$  and  $w_s$  to the manifolds at  $z$ . The *splitting angle* is the oriented angle between them.
- We use two different methods to compute the tangent vectors at  $z$ . This way we can validate the numerical accuracy of the splitting angle.

## First Method

- Let  $p_0 \in W_{\text{loc}}^u(a)$  be the preimage of the homoclinic point  $z$  in the local manifold

$$\mathcal{P}^n(p_0) = z.$$

- Let  $v_0$  be the tangent vector to the manifold at  $p_0$  (i.e. the eigenvector).
- Transport  $v_0$  by the Jacobian  $D\mathcal{P}$  at the successive iterates of  $p_0$

$$w_u = \prod_{i=0}^{n-1} D\mathcal{P}(p_i)v_0.$$

## Second Method

- Let  $z = (x^*, 0)$  be the homoclinic point.
- Look at the manifold  $W^u(a)$  as a graph over the vertical line  $x = x^*$ .
- Sample the manifold  $W^u(a)$  at different values of  $p_x$ :

$$p_x = \frac{j}{10^5}, \quad j \in (-2, -1, 1, 2).$$

- Apply numerical differentiation to these values, using central differences centered at  $p_x = 0$ :

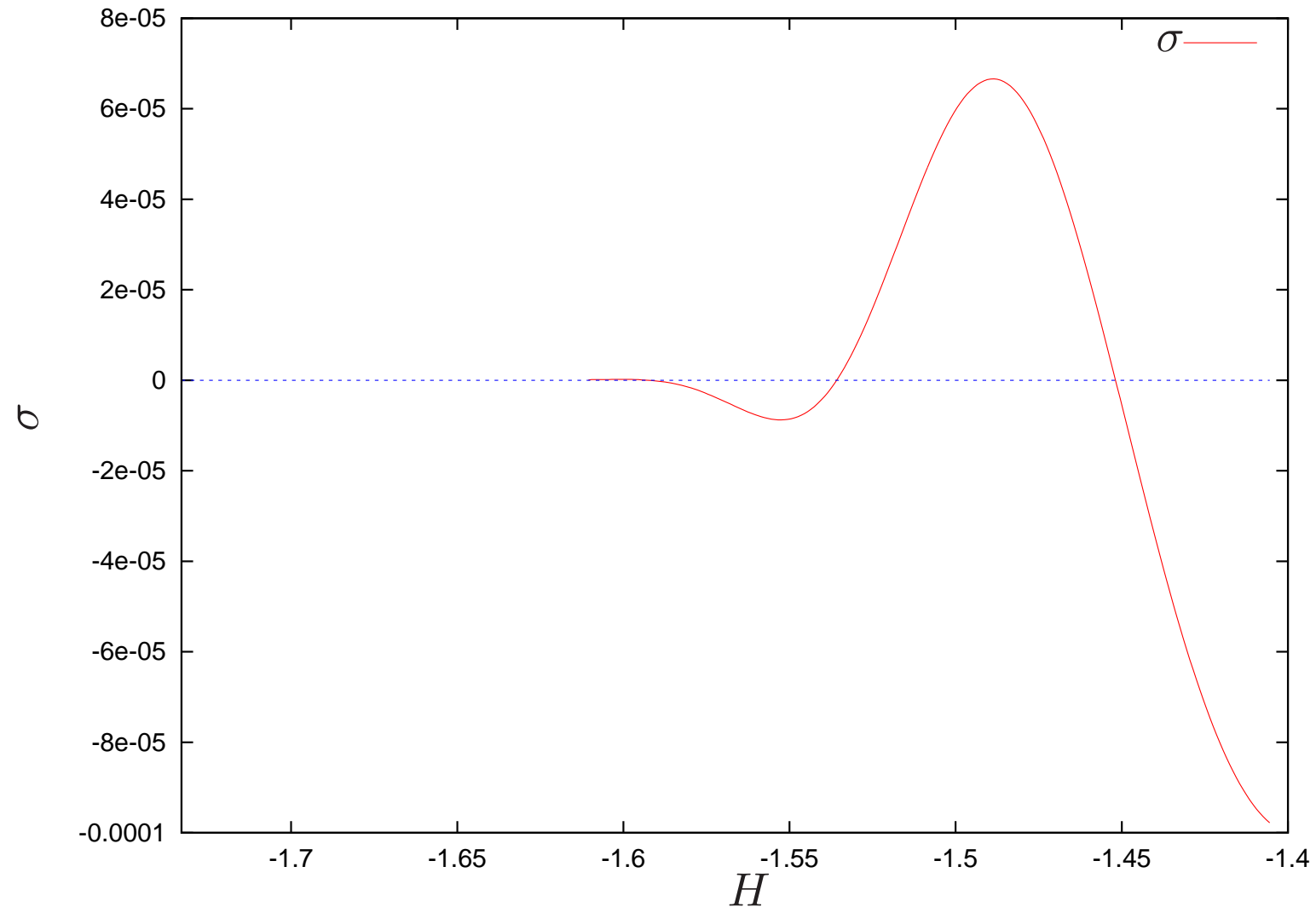
$$d_1 = \frac{x(0.00001) - x(-0.00001)}{0.00002},$$

$$d_2 = \frac{x(0.00002) - x(-0.00002)}{0.00004}.$$

- Use Richardson extrapolation to improve the precision of derivative:

$$d = \frac{4d_1 - d_2}{3}.$$

## Splitting Angle (Inner Splitting)





## Accuracy of Computations

- Let  $H = H_0 = -1.405$ , for example.
- According to the first method, the splitting angle is  $\sigma^{(1)} = -9.780327341442923e - 05$ .
- According to the second method,

$p_x$	$x^u$
-0.00002	$-8.703373796876306e - 02$
-0.00001	$-8.703373845681261e - 02$
0.00001	$-8.703373943484494e - 02$
0.00002	$-8.703373992482412e - 02$

$$\begin{aligned}
 d_1 &= -4.890161608983589e - 05 \\
 d_2 &= -4.890152657810453e - 05 \\
 d &= -4.890164592707968e - 05 \\
 \sigma^{(2)} &= -9.780329177619804e - 05
 \end{aligned}
 \tag{1}$$

- Compare the splitting angle computed using the two methods:

$$\begin{aligned}
 \sigma^{(1)} &= -9.780327341442923e - 05, \\
 \sigma^{(2)} &= -9.780329177619804e - 05.
 \end{aligned}
 \tag{2}$$

They differ by less than  $10^{-10}$  (total numerical error).

## Validation of Splitting Angle

- The splitting angle is several orders of magnitude larger than the total numerical error for a large range of energies  $H \approx [-1.6, -1.4]$ .

