# A symbolic dynamics approach to Kirchberg algebras. 

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Universidad de Cádiz
BIRS Workshop "Graph algebras: Bridges between graph C*-algebras and Leavitt path algebras"

April 22, 2013

## Outline

(1) Why?
(2) Who?
(3) How?
(4) What give us?
(5) What's next?

Joint work with Ruy Exel (Departamento de Matemática, Universidade Federal de Santa Catarina, Florianópolis, Brazil),
R. Exel, E. Pardo, Representing Kirchberg algebras as inverse semigroup crossed products, arXiv:1303.6268v1 (2013),
submited to Indiana University Mathematical Journal.

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Problem: K-P Theorem needs a large amount of analytical technology.

A more combinatorial approach is possible on a restricted subclass:
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(ii) $\mathcal{O}_{2} \cong \mathcal{O}_{2_{-}}$(Analytic).

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Thus, classification of unital purely infinite simple LPAs is done, up to $L_{2} \cong L_{2-}$ problem. Also, the existence of a symbolic dynamical system associated to the algebra play a role in the abovementioned classification results.

HANDICAP: According to Rørdam's result, for any pair $\left(G_{0}, G_{1}\right)$ of countable abelian groups there exists a Kirchberg algebra $A$ such that $K_{i}(A) \cong G_{i}$ for $i=0,1$.

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The above results only cover a piece of a combinatorial, purely algebraic version of Kirchberg-Phillips Theorem.

We need a combinatorial model related to a symbolic DYNAMICAL SYSTEM!

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CANDIDATE: Katsura constructed a suitable combinatorial model for Kirchberg algebras.

## Definition

Let $N \in \mathbb{N} \cup\{\infty\}$, let $A \in M_{N}\left(\mathbb{Z}^{+}\right)$and $B \in M_{N}(\mathbb{Z})$ be row-finite matrices. Define a set $\Omega_{A}$ by
$\Omega_{A}:=\{(i, j) \in\{1,2, \ldots, N\} \times\{1,2, \ldots$


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\Omega_{A}:=\left\{(i, j) \in\{1,2, \ldots, N\} \times\{1,2, \ldots, N\} \mid A_{i, j} \geq 1\right\} .
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For each $i \in\{1,2, \ldots, N\}$, define a set $\Omega_{A}(i) \subset\{1,2$, by

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\Omega_{A}(i):=\left\{j \in\{1,2, \ldots, N\} \mid(i, j) \in \Omega_{A}\right\}
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\text { (0) } \Omega_{A}(i) \neq \emptyset \text { for all } i \text {, and } B_{i, j}=0 \text { for }(i, j) \notin \Omega_{A} \text {. }
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## Definition

Define $\mathcal{O}_{A, B}$ to be the universal $C^{*}$-algebra generated by mutually orthogonal projections $\left\{q_{i}\right\}_{i=1}^{N}$, partial unitaries $\left\{u_{i}\right\}_{i=1}^{N}$ with $u_{i} u_{i}^{*}=u_{i}^{*} u_{i}=q_{i}$, and partial isometries $\left\{s_{i, j, n}\right\}_{(i, j) \in \Omega_{A}, n \in \mathbb{Z}}$ satisfying the relations:

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(ii) $s_{i, j, n}^{*} s_{i, j, n}=q_{j}$ for all $(i, j) \in \Omega_{A}$ and $n \in \mathbb{Z}$.
(iii) $q_{i}=\sum_{j \in \Omega_{A}(i)} \sum_{n=1}^{A_{i, j}} s_{i, j, n} s_{i, j, n}^{*}$ for all $i$.

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(3) Every Kirchberg algebra can be represented, up to isomorphism, by an algebra $\mathcal{O}_{A, B}$ for matrices $A, B$ satisfying the conditions $(2)(a \& b)$.
(4) For any matrix $B, \mathcal{O}_{A} \hookrightarrow \mathcal{O}_{A, B}$.

THUS, IT SEEMS THAT THIS IS THE RIGHT CLASS.

The natural injective $*$-homomorphism $\mathcal{O}_{A} \hookrightarrow \mathcal{O}_{A, B}$, suggest to deal with graph moves, to get some sort of classification stuff.

Problem: Changes on $A$ cannot be independent of suitable changes on $B$. Moreover, results associated to classical moves on $A$ are unclear.

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We need an associated symbolic dynamical system!

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IDEA: Mimic Exel-Laca picture of $\mathcal{O}_{A} \cong C_{0}\left(X_{A}\right) \rtimes_{\alpha} \mathbb{F}$, where $X_{A}$ is the space of one-sided infinite paths on $E_{A}$, while $\alpha$ is a partial action of the free group (with generators the edges of $\left.E_{A}\right)$ on $C_{0}\left(X_{A}\right)$.

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(1) Fix $\mathbb{F}$, and pick $C_{\text {par }}^{*}(\mathbb{F}) \cong C_{0}\left(\Omega_{A}\right) \rtimes_{\alpha} \mathbb{F}$.
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(3) Thus:
(i) $\mathcal{O}_{A} \cong C_{\mathrm{par}}^{*}(\mathbb{F}) / J$.
(ii) $J=C_{0}\left(U_{A}\right) \rtimes_{\alpha} \mathbb{F}$ for an open subspace of $\Omega_{A}$ such that $X_{A}=\Omega_{A} \backslash U_{A}$.

PROBLEM: For $\mathcal{O}_{A, B}$, the group acting must be

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G=\mathbb{F} * \mathbb{F}^{\prime} / \mathcal{R}
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where $\mathbb{F}^{\prime}$ is the free group with generators the partial unitaries, and $\mathcal{R}$ the normal subgroup generated by the relations $(i)$ in $\mathcal{O}_{A, B}$ definition.

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We need a different strategy.

SOLUTION: We construct the symbolic dynamics system from scratch, using Exel's techniques.
(1) Use $A, B$ to define a semigroupoid $\Lambda_{A, B}$.
(2) Prove it satisfies the right properties:
(i) $\Lambda_{A, B}$ is left cancellative.
(ii) Every pair of intersecting elements have a unique lcm
(iii) $\Lambda_{A, B}$ has no springs and is categorical.
(3) Construct an associated inverse semigroup with zero $\mathcal{S}\left(\Lambda_{A, B}\right)$, whose semilatice of idempotents is denoted $E$.
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(3) $\mathcal{G}_{\Lambda_{A, B}}^{(0)}:=\widehat{E}_{\text {tight }}$ is homeomorphic to $X_{A}$ !

Under this identification we have
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The action $\alpha: \mathcal{S}\left(\Lambda_{A, B}\right) \rightarrow \widehat{E}_{\text {tight }}$ becomes the action
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## Corollary

The groupoid $G_{\Lambda_{A},}$ is étale with second countable unit space.

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The $C^{*}$-algebra $\mathcal{O}_{A, B}$ is isomorphic to the inverse semigroup crossed product $C_{0}\left(X_{A}\right) \rtimes_{\alpha} \mathcal{S}^{A, B}$.

Notice that, when $B=(0)$, the previous corollary recover the picture of the Exel-Laca algebra $\mathcal{O}_{A}$. Also, we get the desired picture of $\mathcal{O}_{A, B}$ in terms of symbolic dynamics.

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The addition of an extra condition on the matrix $B$ produces interesting consequences.

## Definition

We say that the matrix $B$ satisfies Condition (E) when $B_{i, j}=0$ if and only if $(i, j) \notin \Omega_{A}$.

## Lemma

$\Lambda_{A, B}$ is right cancellative if and only if $B$ satisfies Condition (E).

## Remark <br> If $\Lambda_{A, B}$ is right cancellative then $S\left(\Lambda_{A, B}\right)$ is a $E^{*}$-unitary inverse semigroup, whence $\mathcal{G}_{\Lambda_{A, B}}$ is Hausdorff.

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## Outline

## (1) Why?

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The dynamical approach lets us to deal with some questions in a more intuitive form. For example, when looking for characterize simplicity, we need to get ride of when $\mathcal{G}_{\Lambda_{A, B}}$ is minimal and essentially principal.

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With respect to minimal, we have

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A groupoid $\mathcal{G}$ is said to be minimal if the only invariant open subsets of $\mathcal{G}^{(0)}$ are the empty set and $\mathcal{G}^{(0)}$ itself.

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## Theorem

Given the action $\alpha$ of $\mathcal{S}^{A, B}$ on $X_{A}$, the following are equivalent:
(1) The matrix $A$ is irreducible.
(2) The space $X_{A}$ is irreducible.
(3) The groupoid $\mathcal{G}_{\Lambda_{A, B}}$ is minimal.

## With respect to essentially principal, we have

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Now, we have the following result, connecting both notions.

## Theorem

Let $S$ be an $E^{*}$-unitary inverse semigroup, let $\tau$ be an action of $S$ on a locally compact, Hausdorff space $X$, and let $\mathcal{G}$ be the corresponding groupoid of germs. Then $\mathcal{G}$ is essentially principal if and only if $\tau$ is topologically free.

Thus, we can deal with the problem from the point of view of topological freeness.

> We get Exel-Laca's result when we act with elements of $\mathcal{S}^{A}$ (the inverse semigroup of $\mathcal{O}_{A}$ generated by the $s_{i, j, n}$ 's).

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The action of partial unitaries give us

## Lemma

Given an element $\omega=s_{i_{1}, i_{2}, n_{1}} s_{i_{2}, i_{3}, n_{2}} \cdots s_{i_{k}, i_{k+1}, n_{k}} \cdots$ of $X_{A}$, the following are equivalent:
(1) $\omega$ is fixed under the action of $u_{i_{1}}^{l}(l \in \mathbb{Z})$.
(2) For every $j \geq 1$ the element $K_{j}:=l \cdot \prod_{t=1}^{j} \frac{B_{i, i_{t+1}}}{A_{i t}, i_{t+1}}$ belongs to $\mathbb{Z}$.

Thus, combining all the information we get

## Theorem

Let $\alpha$ be the action of $\mathcal{S}^{A, B}$ on $X_{A}$, and let $\mathcal{G}_{\Lambda_{A, B}}$ the associated groupoid. The following are equivalent:
(1) (i) The graph $E_{A}$ satisfies Condition (L).
(ii) The matrix $B$ satisfies Condition (E).
(iii) For any fixed point $\omega=s_{i_{1}, i_{2}, n_{1}} s_{i_{2}, i_{3}, n_{2}} \cdots s_{i_{k}, i_{k+1}, n_{k}} \cdots$ and every $n \geq 1$ there exist $m \geq n$ and $j_{m+1}$ with:
(a) $\left(i_{m}, j_{m+1}\right) \in \Omega_{A}$.
(b) $K_{m+1}=K_{m} \cdot \frac{B_{i_{m}, j_{m+1}}}{A_{i_{m}, j_{m+1}}} \notin \mathbb{Z}$.
(2) The groupoid $\mathcal{G}_{\Lambda_{A, B}}$ is essentially principal.

## And as a practical consequence:

## Proposition

Let $\alpha$ be the action of $\mathcal{S}^{A, B}$ on $X_{A}$, and let $\mathcal{G}_{\Lambda_{A, B}}$ the associated groupoid. If
(1) The graph $E_{A}$ satisfies Condition (L).
(2) The matrix $B$ satisfies Condition (E).
(3) For any fixed point $\omega=s_{i_{1}, i_{2}, n_{1}} s_{i_{2}, i_{3}, n_{2}} \cdots s_{i_{k}, i_{k+1}, n_{k}} \cdots$ and for every $n, r \geq 1$ there exist a sequence $j_{n+1}, j_{n+2}, \ldots, j_{n+r}$ with:
(i) $\left(j_{t}, j_{t+1}\right) \in \Omega_{A}$ for all $t$.
(ii) $\lim _{r \rightarrow \infty} \prod_{t=1}^{r}\left(\frac{B_{j_{n+t}, j_{n+t+1}}}{A_{j_{n+t}, j_{n+t+1}}}\right)=0$.
then the groupoid $\mathcal{G}_{\Lambda_{A, B}}$ is essentially principal.

Notice that this proposition includes Katsura's conditions for purely infinite simple. Now, we are ready to characterize simplicity, using a result of Clark et al. characterizing simplicity of groupoid $C^{*}$-algebras of Hausdorff groupoids.

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## Theorem

Consider the initial matrices $A$, $B$. If the matrix $B$ satisfies Condition (E), then the following are equivalent:
(1) (i) The matrix $A$ is irreducible.
(ii) The graph $E_{A}$ satisfies Condition (L).
(iii) For any fixed point $\omega=s_{i_{1}, i_{2}, n_{1}} s_{i_{2}, i_{3}, n_{2}} \cdots s_{i_{k}, i_{k+1}, n_{k}} \cdots$ and every $n \geq 1$ there exist $m \geq n$ and $j_{m+1}$ with:
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(2) $\mathcal{O}_{A, B}$ is simple.

## Corollary

Consider the initial matrices $A$, B. If they satisfy Katsura's conditions for purely infinite simple and $B$ satisfies Condition $(E)$, then $\mathcal{O}_{A, B}$ is simple.

We need an extra property -Condition (E)- to characterize simplicity of $\mathcal{O}_{A, B}$. But we describe simplicity of $\mathcal{O}_{A}$ broad collection of algebras, including the ones given by Katsura.

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Results are obtained in a more natural way, by linking this property to dynamical properties of $X_{A}$.

With respect to pure infiniteness, we use the notion of local contractiveness of groupoids, due to Anantharaman-Delaroche

## Definition

We say that a second countable étale groupoid $\mathcal{G}$ is locally contracting in for every nonempty open subset $U$ of $\mathcal{G}^{(0)}$ there exists an open subset $V$ in $U$ and an slice $S$ such that $\bar{V} \subset S^{-1} S$ and $S \bar{V} S^{-1}$ is properly contained in $V$.

Under our picture, what we obtain is

## Proposition

If every finite path in the graph $E_{A}$ can be enlarged to a cycle and $E_{A}$ satisfies Condition (L), then $\mathcal{G}_{\Lambda_{A, B}}$ is locally contracting.

## So, we can prove

## Theorem

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(1) The matrix $A$ is irreducible.
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(i) $\left(i_{m}, j_{m+1}\right) \in \Omega_{A}$.
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then $\mathcal{O}_{A, B}$ is purely infinite simple.

This result includes Katsura's case, when Condition (E) is satisfied. Also, since A irreducible plus Condition (L) implies Condition (K), the theorem becomes an extension of Exel-Laca results to the case of $B$ being a nonzero matrix.

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Finally, we will show that, under Condition (E), it is possible to show a partial version of Katsura's result.

Theorem
I et $G_{0}, G_{1}$ be finitely generated abelian groups. Then, there exist $N \in \mathbb{N}, A \in M_{N}\left(\mathbb{Z}^{+}\right), B \in M_{N}(\mathbb{Z})$ satisfying Condition $(E)$,
such that:
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(1) $\mathcal{O}_{A, B}$ is unital Kirchberg algebra.
(2) $K_{i}\left(\mathcal{O}_{A, B}\right) \cong G_{i}$ for $i=0,1$.

So, we can represent any unital Kirchberg algebra (up to isomorphism) with finitelly generated $K$-Theory as a Katsura algebra $\mathcal{O}_{A, B}$ such that the matrix $B$ satisfies Condition (E), and thus as the groupoid $C^{*}$-algebra of a minimal essentially principal locally contracting groupoid $\mathcal{G}_{\Lambda_{A, B}}$.

## Outline

## (1) Why?

(2) Who?
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We have some conclusion remarks, which could open new lines of research

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"classification" (i.e., moves preserving something) to advance in the classification problem.

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## Extend the strategy to LPAs world:

(1) Use Steinberg discret groupoid algebra construction for representing $\mathcal{O}_{A, B}{ }^{\mathrm{alg}}(K)$ as $K \mathcal{G}_{\Lambda_{A, B}}$

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# A symbolic dynamics approach to Kirchberg algebras. 

## Enrique Pardo

Universidad de Cádiz
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April 22, 2013

