# Geometric analysis on Finsler manifolds

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# **§Outline of the talk**

<u>Aim</u>: Geometric analysis on various curved spaces (*comparison theorems*).

# Today

- Develop "nonlinear Γ-calculus" on Finsler mfds using the Bochner inequality (by O.–Sturm 2014).
- Show some functional inequalities.
- §1 Finsler manifolds
- §2 Weighted Ricci curvature
- §3 Nonlinear Γ-calculus

§1 Finsler manifolds

# **§1 Finsler manifolds**

# §1 Finsler manifolds

- §2 Weighted Ricci curvature
- §3 Nonlinear  $\Gamma$ -calculus

# **Finsler manifolds**

A Finsler manifold will be an *n*-dimensional connected  $C^{\infty}$ -manifold *M* equipped with  $F : TM \longrightarrow [0, \infty)$  s.t.

(1) 
$$F \in C^{\infty}(TM \setminus \{0\});$$
  
(2)  $F(cv) = cF(v) \ \forall v \in TM, c > 0$  (positive homog.);  
(3)  $\forall v \in T_xM \setminus \{0\}$ , the  $n \times n$ -symmetric matrix  
 $g_{ij}(v) := \frac{1}{2} \frac{\partial^2 [F^2]}{\partial v^i \partial v^j}(v), \quad \text{where } v = \sum_{i=1}^n v^i \frac{\partial}{\partial x^i}\Big|_x,$   
is positive-definite (*strong convexity*).

<u>Note</u>:  $F(-v) \neq F(v)$  is allowed.

# **Riemannian approximation** $g_{\nu}$

For each  $v \in T_x M \setminus \{0\}$ ,  $g_{ij}(v)$  defines an inner product  $g_v$  of  $T_x M$  (fundamental tensor) by

$$g_{\nu}\left(\sum_{i=1}^{n}a_{i}\frac{\partial}{\partial x^{i}},\sum_{j=1}^{n}b_{j}\frac{\partial}{\partial x^{j}}\right):=\sum_{i,j=1}^{n}a_{i}b_{j}g_{ij}(\nu).$$

This is an approximation of  $F|_{T_xM}$  in the direction v (up to the second order).

## **Ricci curvature**

Instead of the precise definition, we explain a useful interpretation of the Ricci curvature (or Ricci scalar) Ric(v) of  $v \in T_x M \setminus \{0\}$ :

#### "Riemannian characterization"

- (1) Extend v to a  $C^{\infty}$ -vector field V on a neighborhood U of x such that every integral curve is geodesic.
- (2) Consider the Riem. str.  $g_V$  on U induced from V.
- (3) Then  $\operatorname{Ric}(v)$  coincides with the Ricci curvature of v w.r.t.  $g_V$  (indep. of the choice of V).

#### **Measure?**

To develop analysis on Finsler manifolds, we would like to equip a Finsler manifold with a measure. However, there is no unique canonical measure like the Riemannian volume measure.

Thus we start with an arbitrary measure m on M and modify the Ricci curvature according to m, inspired by the weighted Ricci curvature for Riemannian manifolds equipped with measures.

# §2 Weighted Ricci curvature

- §1 Finsler manifolds
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- §3 Nonlinear Γ-calculus

# Weighted Ricci curvature

We fix an arbitrary positive  $C^{\infty}$ -measure m on M and take  $v \in T_x M \setminus \{0\}$  and V as above.

Decompose m as  $m = e^{-\psi} \operatorname{vol}_{g_V}$  and let  $\eta$  be the geodesic with  $\dot{\eta}(0) = v$ .

For 
$$N \in (-\infty, 0] \cup (n, \infty)$$
  $(n = \dim M)$ , define  
 $\operatorname{Ric}_{N}(v) := \operatorname{Ric}(v) + (\psi \circ \eta)''(0) - \frac{(\psi \circ \eta)'(0)^{2}}{N-n}$ ,  
 $\operatorname{Ric}_{\infty}(v) := \operatorname{Ric}(v) + (\psi \circ \eta)''(0)$ ,  $\operatorname{Ric}_{n}(v) := \lim_{N \downarrow n} \operatorname{Ric}_{N}(v)$ .

#### **Remarks**

- Monotonicity: For  $N \in (n, \infty)$  and  $N' \leq 0$ , Ric<sub>n</sub>  $\leq$  Ric<sub>N</sub>  $\leq$  Ric<sub>m</sub>  $\leq$  Ric<sub>N'</sub>.
- $\operatorname{Ric}_N \ge K$  (i.e.,  $\operatorname{Ric}_N(v) \ge KF^2(v) \ \forall v \in TM$ ) is equivalent to the curvature-dimension condition  $\operatorname{CD}(K, N)$  à la Lott–Sturm–Villani (O. 2009, 2016).
- A typical example satisfying  $Ric_{\infty} \ge 0$  is a normed space endowed with a log-concave measure.

We are interested in  $(M, F, \mathfrak{m})$  with  $\operatorname{Ric}_N \geq K$ .

#### Three useful techniques

- The curvature-dimension condition CD(*K*, *N*) via the *L*<sup>2</sup>-optimal transport theory.
- The Γ-calculus based on the Bochner inequality (O.–Sturm 2014). → this talk
- The localization (a.k.a. needle decomposition) via the *L*<sup>1</sup>- & *L*<sup>2</sup>-optimal transport theory (O. 2018).

§3 Nonlinear Γ-calculus

# §3 Nonlinear Γ-calculus

- §1 Finsler manifolds
- §2 Weighted Ricci curvature
- §3 Nonlinear Γ-calculus

# **Nonlinear Laplacian**

• For  $u: M \longrightarrow \mathbb{R}$  differentiable at  $x \in M$ , define

 $\nabla u(x) :=$  the Legendre transform of du(x),

i.e., 
$$F^*(du) = F(\nabla u)$$
 and  $du[\nabla u] = F^*(du)^2$ .

<u>Note</u>: The Legendre transf.  $T_x^*M \longrightarrow T_xM$  is linear only when  $F|_{T_xM}$  comes from an inner product.

• For  $u \in H^1_{loc}(M)$ , define the nonlinear Laplacian  $\Delta u := \operatorname{div}_{\mathfrak{m}}(\nabla u)$  in the weak sense that

$$\int_{M} \phi \Delta u \, d\mathfrak{m} = - \int_{M} d\phi(\nabla u) \, d\mathfrak{m} \quad \forall \phi \in C^{\infty}_{c}(M).$$

# Nonlinear heat semigroup

 $\Delta$  is nonlinear but locally uniformly elliptic (by the strong convexity of *F*), this helps us to analyze the nonlinear heat equation  $\partial_t u_t = \Delta u_t$  as follows.

# Existence & regularity (Ge–Shen 2001, O.–Sturm 2009)

 $\forall f \in H_0^1(M)$ ,  $\exists$ a unique solution  $(u_t)_{t\geq 0}$  to  $\partial_t u_t = \Delta u_t$ with  $u_0 = f$ , which is  $H_{loc}^2$  in x and  $C^{1,\alpha}$  in t & x. And  $\Delta u_t \in H_0^1(M)$  if M is compact (or *unif. smooth*).

# <u>Note</u>: The $C^{1,\alpha}$ -regularity cannot be improved.

# The heart of the $\Gamma$ -calculus:

Bochner inequality (O.–Sturm 2014)

For  $u \in C^{\infty}(M)$  and  $N \in (-\infty, 0) \cup [n, \infty]$ , we have

$$\Delta^{\nabla u} \left( \frac{F(\nabla u)^2}{2} \right) - d(\Delta u)(\nabla u) \ge \operatorname{Ric}_N(\nabla u) + \frac{(\Delta u)^2}{N}$$

point-wise on  $\{\nabla u \neq 0\}$  and in the weak sense on *M*.

Here  $\Delta^{\nabla u}$  is the linearized Laplacian (w.r.t.  $g_{\nabla u}$ ):

$$\Delta^{\nabla u} f := \operatorname{div}_{\mathfrak{m}}(\nabla^{\nabla u} f), \quad \nabla^{\nabla u} f := \sum_{i,j=1}^{n} g^{ij}(\nabla u) \frac{\partial f}{\partial x^{i}} \frac{\partial}{\partial x^{j}}.$$

<u>Note</u>: This is *not* the Bochner inequality for  $g_{\nabla u}$ .

# **Applications under** $\operatorname{Ric}_N \ge K$

Let *M* be compact for simplicity.  $(u_t)_{t\geq 0}$ : sol. to heat eq.

Gradient estimates (O.–Sturm 2014) •  $L^2$ -gradient estimate ( $N = \infty$ ):  $F^2(\nabla u_t) \leq e^{-2Kt} P_t^{\nabla u}(F^2(\nabla u_0)) \quad \forall t > 0,$ where  $f_t = P_t^{\nabla u}(f)$  is the solution to  $\partial_t f_t = \Delta^{\nabla u_t} f_t$ ,  $f_0 = f$ . • Li–Yau gradient estimate ( $K \le 0, N \in [n, \infty)$ ):  $F^{2}(\nabla(\log u_{t})) - \theta \cdot \partial_{t}(\log u_{t}) \leq N\theta^{2}\left(\frac{1}{2t} - \frac{K}{4(\theta - 1)}\right) \quad \forall t > 0, \theta > 1.$  Poincaré–Lichnerowicz inequality (O. 2009, 2017)  $\mathfrak{m}(M) = 1, K > 0, N \in (-\infty, 0) \cup [n, \infty]: \text{ For } f \in H^1(M),$   $\int_M f^2 d\mathfrak{m} - \left(\int_M f d\mathfrak{m}\right)^2 \leq \frac{2(N-1)}{KN} \mathcal{E}(f).$ 

Logarithmic Sobolev inequality (O. 2009, 2017)  $\mathfrak{m}(M) = 1, K > 0, N \in [n, \infty]$ : For nonnegative  $f \in H^1(M)$  with  $\int_M f \, d\mathfrak{m} = 1$ ,  $\int_M f \log f \, d\mathfrak{m} \leq \frac{N-1}{2KN} \int_M \frac{F^2(\nabla f)}{f} \, d\mathfrak{m}$ . Sobolev inequality (O. 2017)

 $\mathfrak{m}(M) = 1, K > 0, N \in [n, \infty), p \in [2, 2(N + 1)/N]$  (or  $p \in [2, 2N/(N - 2)]$  if reversible F(-v) = F(v)): For  $f \in H^1(M)$ ,

$$\frac{\|f\|_{L^p}^2 - \|f\|_{L^2}^2}{p-2} \le \frac{N-1}{KN} \int_M F^2(\nabla f) \, d\mathfrak{m}.$$

Beckner inequality (O. 2021; cf. Gentil–Zugmeyer 2021)  $\mathfrak{m}(M) = 1, K > 0, N \in (-\infty, -2) \cup [n, \infty), p \in [1, 2]$  for  $N \in [n, \infty)$  and  $p \in \left[1, \frac{2N^2 + 1}{(N-1)^2}\right]$  for N < -2: For  $f \in H^1(M)$ , the same inequality as above holds.

## **Final remarks**

The proofs essentially follow the lines of the Riemanninan case up to some technical differences.

- One can also generalize Bakry–Ledoux's Gaussian isoperimetric inequality.
- In some results, the *noncompact case* is yet to be fully understood, due to the lack of *higher order regularity* and the *Wasserstein contraction*.
- The localization is useful in the noncompact case, however, it does not give sharp estimates in the *non-reversible* case (at present).

If you are interested  $\downarrow\downarrow$ 

Reference: "Comparison Finsler Geometry" (to appear in *Springer Monographs in Mathematics*).

# Thank you for your attention!