Threshold Selection Problem Asymptotics Simulations

### Threshold Selection by Distance Minimization

(work in progress)

Holger Drees

University of Hamburg

Workshop on Self-Similarity, Long-Range Dependence and Extremes June 2018

based on joint work with Anja Janßen (KTH Stockholm), and Sid Resnick and Tiandong Wang (Cornell) POT-analysis of heavy tails

 $X_i$ ,  $1 \leq i \leq n$ , iid observations with cdf  $F \in D(G_{1/\alpha})$ ,  $\alpha > 0$ , i.e. as  $t \to \infty$ 

$$\frac{1-F(tx)}{1-F(t)}\to x^{-\alpha},\qquad \forall x>0.$$

Hill estimator of  $\alpha$ :

$$\hat{lpha}_{n,k} := 1 \Big/ \left[ rac{1}{k-1} \sum_{i=1}^{k-1} \log rac{X_{n-i+1:n}}{X_{n-k+1:n}} 
ight]$$

where  $X_{j:n}$  denotes the *j*th smallest order statistic.

Hill estimator is essentially ML estimator if k largest observations behave like Pareto random variables.

Performance strongly depends on choice of k:

- k must be sufficiently small such that Pareto approximation is justified (→ small bias)
- *k* must be sufficiently large such that average is taken over many observations (→ small variance)

POT-analysis of heavy tails

 $X_i$ ,  $1 \leq i \leq n$ , iid observations with cdf  $F \in D(G_{1/\alpha})$ ,  $\alpha > 0$ , i.e. as  $t \to \infty$ 

$$\frac{1-F(tx)}{1-F(t)}\to x^{-\alpha},\qquad \forall x>0.$$

Hill estimator of  $\alpha$ :

$$\hat{lpha}_{n,k} := 1 \Big/ \left[ rac{1}{k-1} \sum_{i=1}^{k-1} \log rac{X_{n-i+1:n}}{X_{n-k+1:n}} 
ight]$$

where  $X_{j:n}$  denotes the *j*th smallest order statistic.

Hill estimator is essentially ML estimator if k largest observations behave like Pareto random variables.

Performance strongly depends on choice of k:

- k must be sufficiently small such that Pareto approximation is justified (→ small bias)
- k must be sufficiently large such that average is taken over many observations (→ small variance)

$$\hat{lpha}_{n,k} := 1 ig/ igg[ rac{1}{k-1} \sum_{i=1}^{k-1} \log rac{oldsymbol{X}_{n-i+1:n}}{oldsymbol{X}_{n-k+1:n}} igg]$$

Several procedures for data-dependent selection of k have been suggested, e.g. using

### • plug-in methods: Hall & Welsh ('85), ...

- resampling: Hall ('90), Danielsson et al. ('01), Gomes & Oliveira ('01), ...
- Lepskii method: D. & Kaufmann ('98), ...
- using log-spacings: Guillou & Hall ('01), Beirlant et al. ('04), ...
- distance minimization: Clauset, Shalizi & Newman (2009) (over 2700 citations)



$$\hat{lpha}_{n,k} := 1 ig/ igg[ rac{1}{k-1} \sum_{i=1}^{k-1} \log rac{X_{n-i+1:n}}{X_{n-k+1:n}} igg]$$

Several procedures for data-dependent selection of k have been suggested, e.g. using

- plug-in methods: Hall & Welsh ('85), ...
- resampling: Hall ('90), Danielsson et al. ('01), Gomes & Oliveira ('01), ...
- Lepskii method: D. & Kaufmann ('98), ...
- using log-spacings: Guillou & Hall ('01), Beirlant et al. ('04), ...
- distance minimization: Clauset, Shalizi & Newman (2009 (over 2700 citations)
- Idea: Choose k such that the Kolmogorov-Smirnov distance between empirical cdf of exceedances over  $X_{n-k+1:n}$  and fitted Pareto distribution is minimal. More precisely, minimize



$$\hat{\alpha}_{n,k} := 1 \Big/ \left[ \frac{1}{k-1} \sum_{i=1}^{k-1} \log \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right]$$

Several procedures for data-dependent selection of k have been suggested, e.g. using

- plug-in methods: Hall & Welsh ('85), ...
- resampling: Hall ('90), Danielsson et al. ('01), Gomes & Oliveira ('01), ...
- Lepskii method: D. & Kaufmann ('98), ...
- using log-spacings: Guillou & Hall ('01), Beirlant et al. ('04), ...
- distance minimization: Clauset, Shalizi & Newman (2009) (over 2700 citations)

Idea: Choose k such that the Kolmogorov-Smirnov distance between empirical cdf of exceedances over  $X_{n-k+1:n}$  and fitted Pareto distribution is minimal. More precisely, minimize

$$D_{n,k} := \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\hat{\alpha}_{n,k}} \right|$$

3/24

$$\hat{\alpha}_{n,k} := 1 \Big/ \left[ \frac{1}{k-1} \sum_{i=1}^{k-1} \log \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right]$$

Several procedures for data-dependent selection of k have been suggested, e.g. using

- plug-in methods: Hall & Welsh ('85), ...
- resampling: Hall ('90), Danielsson et al. ('01), Gomes & Oliveira ('01), ...
- Lepskii method: D. & Kaufmann ('98), ...
- using log-spacings: Guillou & Hall ('01), Beirlant et al. ('04), ...
- distance minimization: Clauset, Shalizi & Newman (2009) (over 2700 citations)

$$D_{n,k} := \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\hat{\alpha}_{n,k}} \right|$$

$$\hat{\alpha}_{n,k} := 1 \Big/ \left[ \frac{1}{k-1} \sum_{i=1}^{k-1} \log \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right]$$

Several procedures for data-dependent selection of k have been suggested, e.g. using

- plug-in methods: Hall & Welsh ('85), ...
- resampling: Hall ('90), Danielsson et al. ('01), Gomes & Oliveira ('01), ...
- Lepskii method: D. & Kaufmann ('98), ...
- using log-spacings: Guillou & Hall ('01), Beirlant et al. ('04), ...
- distance minimization: Clauset, Shalizi & Newman (2009) (over 2700 citations)

$$D_{n,k} := \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\hat{\alpha}_{n,k}} \right|$$

$$\hat{lpha}_{n,k} := 1 ig/ igg[ rac{1}{k-1} \sum_{i=1}^{k-1} \log rac{oldsymbol{X}_{n-i+1:n}}{oldsymbol{X}_{n-k+1:n}} igg]$$

Several procedures for data-dependent selection of k have been suggested, e.g. using

- plug-in methods: Hall & Welsh ('85), ...
- resampling: Hall ('90), Danielsson et al. ('01), Gomes & Oliveira ('01), ...
- Lepskii method: D. & Kaufmann ('98), ...
- using log-spacings: Guillou & Hall ('01), Beirlant et al. ('04), ...
- distance minimization: Clauset, Shalizi & Newman (2009) (over 2700 citations)

$$D_{n,k} := \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\hat{\alpha}_{n,k}} \right|$$

# Threshold selection by distance minimization

minimize 
$$D_{n,k} := \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\hat{\alpha}_{n,k}} \right|$$

Rationale:

- If Pareto approximation is accurate for top k order statistics, then  $D_{n,k}$  is of stochastic order  $k^{-1/2}$ , i.e. it shrinks with increasing k
- If below threshold u cdf is poorly approximated by Pareto cdf,  $D_{n,k}$  quickly increases as k increases such that  $X_{n-k:n}$  shrinks below u.

Indeed, it seems plausible that procedure yields k converging at the "optimal rate".

However, even if all observations are exact Pareto,  $D_{n,k}$  will be minimal for k much smaller than n due to random fluctuations.

# Threshold selection by distance minimization

minimize 
$$D_{n,k} := \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\hat{\alpha}_{n,k}} \right|$$

Rationale:

- If Pareto approximation is accurate for top k order statistics, then  $D_{n,k}$  is of stochastic order  $k^{-1/2}$ , i.e. it shrinks with increasing k
- If below threshold u cdf is poorly approximated by Pareto cdf,  $D_{n,k}$  quickly increases as k increases such that  $X_{n-k:n}$  shrinks below u.

Indeed, it seems plausible that procedure yields k converging at the "optimal rate".

However, even if all observations are exact Pareto,  $D_{n,k}$  will be minimal for k much smaller than n due to random fluctuations.

# Threshold selection by distance minimization

minimize 
$$D_{n,k} := \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\hat{\alpha}_{n,k}} \right|$$

Rationale:

- If Pareto approximation is accurate for top k order statistics, then  $D_{n,k}$  is of stochastic order  $k^{-1/2}$ , i.e. it shrinks with increasing k
- If below threshold u cdf is poorly approximated by Pareto cdf,  $D_{n,k}$  quickly increases as k increases such that  $X_{n-k:n}$  shrinks below u.

Indeed, it seems plausible that procedure yields k converging at the "optimal rate".

However, even if all observations are exact Pareto,  $D_{n,k}$  will be minimal for k much smaller than n due to random fluctuations.

### Gaussian approximation: $\alpha$ known

Assume  $F(x) = 1 - x^{-\alpha}$  (x > 1) with known  $\alpha > 0$ . Consider KS distance

$$\begin{split} \bar{D}_{n,k} &:= \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\alpha} \right| \\ &= \max_{1 \le i < k} \left| \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right)^{-\alpha} - \frac{i}{k} \right| + O(k^{-1}) \\ &= d \max_{1 \le i < k} \left| \frac{U_{i:n}}{U_{k:n}} - \frac{i}{k} \right| + O(k^{-1}) \end{split}$$

for iid uniform rv's  $U_j$ .

Approximation of uniform order statistics by Brownian motion yields

$$n^{1/2}\bar{D}_{n,\lceil nt\rceil} \to \sup_{0 < z \leq 1} z \Big| \frac{W(tz)}{tz} - \frac{W(t)}{t}\Big|$$

weakly in D(0,1].

医下子 医下

### Gaussian approximation: $\alpha$ known

Assume  $F(x) = 1 - x^{-\alpha}$  (x > 1) with known  $\alpha > 0$ . Consider KS distance

$$\begin{split} \bar{D}_{n,k} &:= \sup_{y \ge 1} \left| \frac{1}{k-1} \sum_{i=1}^{k-1} \mathbb{1}_{(y,\infty)} \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right) - y^{-\alpha} \right| \\ &= \max_{1 \le i < k} \left| \left( \frac{X_{n-i+1:n}}{X_{n-k+1:n}} \right)^{-\alpha} - \frac{i}{k} \right| + O(k^{-1}) \\ &= d \max_{1 \le i < k} \left| \frac{U_{i:n}}{U_{k:n}} - \frac{i}{k} \right| + O(k^{-1}) \end{split}$$

for iid uniform rv's  $U_i$ .

Approximation of uniform order statistics by Brownian motion yields

$$n^{1/2}\bar{D}_{n,\lceil nt\rceil} \to \sup_{0 < z \leq 1} z \Big| \frac{W(tz)}{tz} - \frac{W(t)}{t}\Big|$$

weakly in D(0,1].

医下颌 医下口

э

# "Early stopping"

$$n^{1/2}\bar{D}_{n,\lceil nt\rceil} \to \sup_{0 < z \leq 1} z \Big| \frac{W(tz)}{tz} - \frac{W(t)}{t} \Big|$$

One might thus expect that the value k for which  $\overline{D}_{n,k}$  is minimized behaves like  $nT^*$  with

$$T^* := \underset{0 < t \le 1}{\operatorname{arg\,min\,\,sup\,\,}} z \left| \frac{W(tz)}{tz} - \frac{W(t)}{t} \right|$$

Despite

$$\sup_{0 < z \le 1} z \Big| \frac{W(tz)}{tz} - \frac{W(t)}{t} \Big| =^{d} t^{-1/2} \sup_{0 < z \le 1} z \Big| \frac{W(z)}{z} - W(1) \Big|,$$

with non-negligible probability,  $t^*$  will be substantially smaller than 1, leading to too small a value for k.

< 4 P ►

ヨト・モヨト

э

# "Early stopping"

$$n^{1/2}\bar{D}_{n,\lceil nt\rceil} \to \sup_{0 < z \leq 1} z \Big| \frac{W(tz)}{tz} - \frac{W(t)}{t} \Big|$$

One might thus expect that the value k for which  $\overline{D}_{n,k}$  is minimized behaves like  $nT^*$  with

$$T^* := \underset{0 < t \leq 1}{\arg\min} \sup_{0 < z \leq 1} z \left| \frac{W(tz)}{tz} - \frac{W(t)}{t} \right|$$

Despite

$$\sup_{0 < z \le 1} z \Big| \frac{W(tz)}{tz} - \frac{W(t)}{t} \Big| =^d t^{-1/2} \sup_{0 < z \le 1} z \Big| \frac{W(z)}{z} - W(1) \Big|,$$

with non-negligible probability,  $t^*$  will be substantially smaller than 1, leading to too small a value for k.

Drees

A B A B A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

A E > A E >

### Gaussian approximation: $\alpha$ unknown

If  $\alpha$  is unknown and replaced with the Hill estimator, process convergence becomes more involved.

#### Theorem

Suppose 
$$F(x) = 1 - cx^{-\alpha}$$
  $(x > c^{1/\alpha})$ .  
• For all  $k = k_n = o(n)$   
 $2 \le j \le k$   
 $n^{1/2} D_{n, \lceil nt \rceil}$   
 $\rightarrow \sup_{\substack{0 < z \le 1}} \left| \left( \int_0^1 \frac{W(tx)}{tx} dx - \frac{W(t)}{t} \right) z \log z + \left( \frac{W(tz)}{tz} - \frac{W(t)}{t} \right) z \right|$   
 $=: \sup_{\substack{0 < z \le 1}} |Y(t, z)|$ 

weakly in D(0,1].

### Gaussian approximation: $\alpha$ unknown

If  $\alpha$  is unknown and replaced with the Hill estimator, process convergence becomes more involved.

#### Theorem

Suppose 
$$F(x) = 1 - cx^{-\alpha}$$
  $(x > c^{1/\alpha})$ .  
• For all  $k = k_n = o(n)$   
 $\lim_{2 \le j \le k} n^{1/2} D_{n,j} \xrightarrow{(P)} \infty$ .  
•  $\lim_{0 < z \le 1} |\int_{0}^{1} \frac{W(tx)}{tx} dx - \frac{W(t)}{t} z \log z + \left(\frac{W(tz)}{tz} - \frac{W(t)}{t}\right)$   
 $=: \sup_{0 < z \le 1} |Y(t, z)|$ 

weakly in D(0,1].

# Asymptotic behavior of selected threshold

Let  $k^* := \arg \min_{2 \le k \le n} D_{n,k}$ 

### Corollary

Suppose 
$$F(x) = 1 - cx^{-\alpha}$$
 ( $x > c^{1/\alpha}$ ). Then

$$\frac{k^*}{n} \rightarrow \argmin_{t \in (0,1]} \sup_{0 < z \le 1} |Y(t,z)| =: T^*,$$

provided the process  $(\sup_{0 \le z \le 1} |Y(t, z)|)_{t \in [0,1]}$  has a unique point of minimum a.s.

In that case,

$$n^{1/2}(\hat{\alpha}_{n,k^*}-\alpha) o lpha \left(\int_0^1 \frac{W(T^*x)}{T^*x} \, dx - \frac{W(T^*)}{T^*}\right)$$
 weak

The limit rv is not normally distributed.

# Asymptotic behavior of selected threshold

Let  $k^* := \arg \min_{2 \le k \le n} D_{n,k}$ 

### Corollary

Suppose 
$$F(x) = 1 - cx^{-\alpha}$$
 ( $x > c^{1/\alpha}$ ). Then

$$\frac{k^*}{n} \to \underset{t \in (0,1]}{\operatorname{arg inf}} \sup_{0 < z \leq 1} |Y(t,z)| =: T^*,$$

provided the process  $(\sup_{0 \le z \le 1} |Y(t, z)|)_{t \in (0,1]}$  has a unique point of minimum a.s.

In that case,

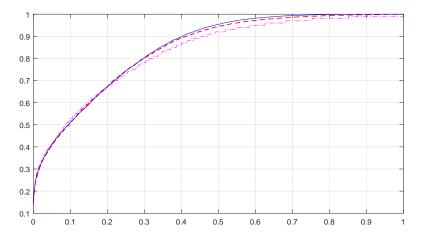
$$n^{1/2}(\hat{lpha}_{n,k^*}-lpha) 
ightarrow lpha \left( \int_0^1 rac{W(T^*x)}{T^*x} \, dx - rac{W(T^*)}{T^*} 
ight)$$
 weakly

The limit rv is not normally distributed.

Threshold Selection Problem Pareto case Asymptotics Pareto with str Simulations Under Second

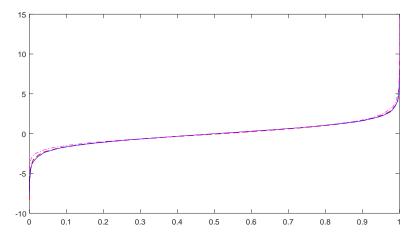
Pareto case Pareto with structural break Under Second Order Condition

# Distribution of $k^*/n$



Quantile function of  $T^*/n$  for sample sizes n = 100 (magenta dash-dotted), n = 1000 (red dashed), and limit (blue solid)

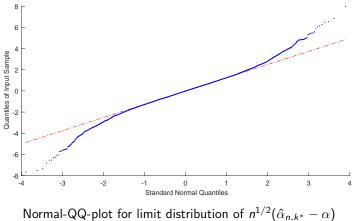
# Distribution of $\hat{\alpha}_{n,k^*}$



Quantile function of  $n^{1/2}(\hat{\alpha}_{n,k^*} - \alpha)$  for sample sizes n = 100 (magenta dash-dotted), n = 1000 (red dashed), and limit (blue solid)

Threshold Selection Problem Asymptotics Simulations Pareto case Pareto with structural break Under Second Order Condition

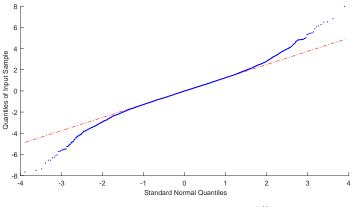
# Limit distribution of $\hat{\alpha}_{n,k^*}$



In the limit, the variance is about 1.95 times the variance of  $\hat{\alpha}_{n,n}$ 

Threshold Selection Problem Asymptotics Simulations Pareto case Pareto with structural break Under Second Order Condition

# Limit distribution of $\hat{\alpha}_{n,k^*}$



Normal-QQ-plot for limit distribution of  $n^{1/2}(\hat{\alpha}_{n,k^*} - \alpha)$ 

In the limit, the variance is about 1.95 times the variance of  $\hat{\alpha}_{n,n}$ 

# Structural breaks

In Clauset et al. (2009) (and similar papers) it is assumed that above some threshold  $u \ F$  equals a Pareto cdf, while below it has a different structure.

### Selection procedures should yield k such that $X_{n-k+1:n}$ is close to u.

There is no obvious asymptotic setting in which to embed such a situation.

However, simulations suggest that  $k^*/(n(1 - F(u)))$  roughly behaves like  $T^*$  if break is sufficiently clear and n is large.

Hence procedures often selects too small a k, i.e. too high a threshold.

# Structural breaks

In Clauset et al. (2009) (and similar papers) it is assumed that above some threshold  $u \ F$  equals a Pareto cdf, while below it has a different structure.

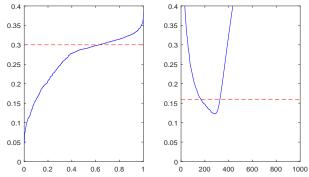
Selection procedures should yield k such that  $X_{n-k+1:n}$  is close to u.

There is no obvious asymptotic setting in which to embed such a situation.

However, simulations suggest that  $k^*/(n(1 - F(u)))$  roughly behaves like  $T^*$  if break is sufficiently clear and n is large.

Hence procedures often selects too small a k, i.e. too high a threshold.

Simulation  $1 - F(x) = \begin{cases} x^{-2}, & x > x_0, \\ cx^{-4}, & x_0 \ge x > c^{1/4} \end{cases}$ with  $x_0, c$  such that  $1 - F(x_0) = 0.3$ , *F* continuous.



Left: qf of  $k^*/n$  for n = 1000; red line indicates break point Right: RMSE of Hill estimator as function of k; red line indicates RMSE of  $\hat{\alpha}_{n,k^*}$ increase of RMSE and of SD  $\approx 31\%$ 

Assume, as  $t \downarrow 0$ ,

$$rac{F^{\leftarrow}(1-tx)}{F^{\leftarrow}(1-t)} - x^{-1/lpha}}{A(t)} o \psi(x), \qquad orall x > 0,$$

with  $A(t) \downarrow 0$ , regularly varying at 0 with index  $\rho > 0$ ,  $\psi(x)$  not a multiple of  $x^{-1/\alpha}$ .

Then there exists sequence  $\tilde{k} = \tilde{k}_n \to \infty$ ,  $\tilde{k} = o(n)$  such that  $\tilde{k}^{1/2}A(\tilde{k}/n) \to 1$ .

SD, bias balanced iff  $k \simeq \tilde{k}$  and then  $\hat{\alpha}_{n,k}$  converges with the optimal rate  $\tilde{k}^{-1/2}$  (among all deterministic intermediate sequences k). Moreover, AMSE  $\hat{\alpha}_{n,k}$  is minimal iff  $k \sim c\tilde{k}$  for some constant c depending on  $\alpha, \rho, \psi$ .

Most threshold selection methods mentioned in the beginning yield random  $\bar{k}\sim c\tilde{k}$  under suitable conditions.

In this setting, minimizer of  $D_{n,j}$  can be analyzed only if minimization is restricted to  $j \le k$  for some intermediate sequence k.

Assume, as  $t \downarrow 0$ ,

$$\frac{\frac{F^{\leftarrow}(1-tx)}{F^{\leftarrow}(1-t)}-x^{-1/\alpha}}{A(t)} \to \psi(x), \qquad \forall x > 0,$$

with  $A(t) \downarrow 0$ , regularly varying at 0 with index  $\rho > 0$ ,  $\psi(x)$  not a multiple of  $x^{-1/\alpha}$ .

Then there exists sequence  $\tilde{k} = \tilde{k}_n \to \infty, \tilde{k} = o(n)$  such that  $\tilde{k}^{1/2}A(\tilde{k}/n) \to 1$ .

SD, bias balanced iff  $k \simeq \tilde{k}$  and then  $\hat{\alpha}_{n,k}$  converges with the optimal rate  $\tilde{k}^{-1/2}$  (among all deterministic intermediate sequences k). Moreover, AMSE  $\hat{\alpha}_{n,k}$  is minimal iff  $k \sim c\tilde{k}$  for some constant c depending on  $\alpha, \rho, \psi$ .

Most threshold selection methods mentioned in the beginning yield random  $\bar{k} \sim c \tilde{k}$  under suitable conditions.

In this setting, minimizer of  $D_{n,j}$  can be analyzed only if minimization is restricted to  $j \leq k$  for some intermediate sequence k.

Assume, as  $t \downarrow 0$ ,

$$\frac{\frac{F^{\leftarrow}(1-tx)}{F^{\leftarrow}(1-t)}-x^{-1/\alpha}}{A(t)} \to \psi(x), \qquad \forall x > 0,$$

with  $A(t) \downarrow 0$ , regularly varying at 0 with index  $\rho > 0$ ,  $\psi(x)$  not a multiple of  $x^{-1/\alpha}$ .

Then there exists sequence  $\tilde{k} = \tilde{k}_n \to \infty, \tilde{k} = o(n)$  such that  $\tilde{k}^{1/2}A(\tilde{k}/n) \to 1$ .

SD, bias balanced iff  $k \simeq \tilde{k}$  and then  $\hat{\alpha}_{n,k}$  converges with the optimal rate  $\tilde{k}^{-1/2}$  (among all deterministic intermediate sequences k). Moreover, AMSE  $\hat{\alpha}_{n,k}$  is minimal iff  $k \sim c\tilde{k}$  for some constant c depending on  $\alpha, \rho, \psi$ .

Most threshold selection methods mentioned in the beginning yield random  $\bar{k} \sim c\tilde{k}$  under suitable conditions.

Drees

In this setting, minimizer of  $D_{n,j}$  can be analyzed only if minimization is restricted to  $j \le k$  for some intermediate sequence k.

14/24

Assume, as  $t \downarrow 0$ ,

$$\frac{\frac{F^{\leftarrow}(1-tx)}{F^{\leftarrow}(1-t)}-x^{-1/\alpha}}{A(t)} \to \psi(x), \qquad \forall x > 0,$$

with  $A(t) \downarrow 0$ , regularly varying at 0 with index  $\rho > 0$ ,  $\psi(x)$  not a multiple of  $x^{-1/\alpha}$ .

Then there exists sequence  $\tilde{k} = \tilde{k}_n \to \infty, \tilde{k} = o(n)$  such that  $\tilde{k}^{1/2}A(\tilde{k}/n) \to 1$ .

SD, bias balanced iff  $k \simeq \tilde{k}$  and then  $\hat{\alpha}_{n,k}$  converges with the optimal rate  $\tilde{k}^{-1/2}$  (among all deterministic intermediate sequences k). Moreover, AMSE  $\hat{\alpha}_{n,k}$  is minimal iff  $k \sim c\tilde{k}$  for some constant c depending on  $\alpha, \rho, \psi$ .

Most threshold selection methods mentioned in the beginning yield random  $\bar{k} \sim c\tilde{k}$  under suitable conditions.

In this setting, minimizer of  $D_{n,j}$  can be analyzed only if minimization is restricted to  $j \le k$  for some intermediate sequence k.

14/24

# Asymptotics under second order condition

### Theorem

Inf<sub>2≤j≤k</sub> 
$$\tilde{k}^{1/2} D_{n,j} \to \infty$$
 for all intermediate sequences  $k = o(\tilde{k})$ 

$$\tilde{k}^{1/2} D_{n, \lceil \tilde{k}t \rceil} \to \sup_{0 < z \le 1} |Y(t, z) - \left(\int_{0}^{1} x^{1/\alpha} \psi(x) \, dx \cdot z \log z + \alpha z^{1/\alpha} \psi(z)\right) t^{\rho}$$
weakly in  $D(0, \infty)$ .
If  $\tilde{k} = o(k), k = o(n)$  then, for all  $0 < t_0 < t_1 < \infty$ 

$$\inf_{t \in [t_0, t_1]} \tilde{k}^{1/2} D_{n, \lceil kt \rceil} \to \infty.$$

This suggests (but doesn't prove) that

 $k^*/\tilde{k} \to \underset{0 < t < \infty}{\operatorname{arg inf}} \sup_{0 < t < \infty} \left| Y(t, z) - \left( \int_0^{-\infty} x^{1/\alpha} \psi(x) \, dx \cdot z \log z + \alpha z^{1/\alpha} \psi(z) \right) t^{\rho} \right|.$ 

# Asymptotics under second order condition

#### Theorem

• 
$$\inf_{2 \le j \le k} \tilde{k}^{1/2} D_{n,j} \to \infty$$
 for all intermediate sequences  $k = o(\tilde{k})$   
•

$$\tilde{k}^{1/2} D_{n, \lceil \tilde{k}t \rceil} \to \sup_{0 < z \le 1} \left| Y(t, z) - \left( \int_0^1 x^{1/\alpha} \psi(x) \, dx \cdot z \log z + \alpha z^{1/\alpha} \psi(z) \right) t^{\rho} \right|$$

weakly in  $D(0,\infty)$ . If  $\tilde{k} = o(k)$ , k = o(n) then, for all  $0 < t_0 < t_1 < \infty$ 

$$\inf_{t\in[t_0,t_1]}\tilde{k}^{1/2}D_{n,\lceil kt\rceil}\to\infty.$$

This suggests (but doesn't prove) that

 $k^*/\tilde{k} \to \underset{0 < t < \infty}{\operatorname{arg inf}} \sup_{0 < t < \infty} \Big| Y(t,z) - \Big( \int_0^{-1} x^{1/\alpha} \psi(x) \, dx \cdot z \log z + \alpha z^{1/\alpha} \psi(z) \Big) t^{\rho} \Big|.$ 

Drees

# Asymptotics under second order condition

### Theorem

• 
$$\inf_{2 \le j \le k} \tilde{k}^{1/2} D_{n,j} \to \infty$$
 for all intermediate sequences  $k = o(\tilde{k})$   
•

$$\tilde{k}^{1/2}D_{n,\lceil \tilde{k}t\rceil} \to \sup_{0 < z \le 1} \left| Y(t,z) - \left( \int_0^1 x^{1/\alpha} \psi(x) \, dx \cdot z \log z + \alpha z^{1/\alpha} \psi(z) \right) t^{\rho} \right|$$

weakly in 
$$D(0,\infty)$$
.  
If  $\tilde{k} = o(k)$ ,  $k = o(n)$  then, for all  $0 < t_0 < t_1 < \infty$ 

$$\inf_{t\in[t_0,t_1]}\tilde{k}^{1/2}D_{n,\lceil kt\rceil}\to\infty.$$

This suggests (but doesn't prove) that

$$k^*/\tilde{k} \to \underset{0 < t < \infty}{\arg \inf} \sup_{0 < z \le 1} \Big| Y(t,z) - \Big( \int_0^1 x^{1/\alpha} \psi(x) \, dx \cdot z \log z + \alpha z^{1/\alpha} \psi(z) \Big) t^p \Big|.$$

15/24

# Asymptotics under second order condition

### Theorem

• 
$$\inf_{2 \le j \le k} \tilde{k}^{1/2} D_{n,j} \to \infty$$
 for all intermediate sequences  $k = o(\tilde{k})$   
•

$$\tilde{k}^{1/2}D_{n,\lceil \tilde{k}t\rceil} \to \sup_{0 < z \leq 1} \left| Y(t,z) - \left( \int_0^1 x^{1/\alpha} \psi(x) \, dx \cdot z \log z + \alpha z^{1/\alpha} \psi(z) \right) t^{\rho} \right|$$

weakly in 
$$D(0,\infty)$$
.  
If  $\tilde{k} = o(k)$ ,  $k = o(n)$  then, for all  $0 < t_0 < t_1 < \infty$ 

$$\inf_{t\in[t_0,t_1]}\tilde{k}^{1/2}D_{n,\lceil kt\rceil}\to\infty.$$

This suggests (but doesn't prove) that

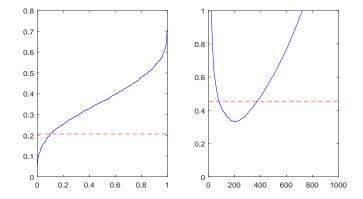
$$k^*/\tilde{k} \to \underset{0 < t < \infty}{\operatorname{arg inf }} \sup_{0 < t < \infty} \Big| Y(t, z) - \Big( \int_0^1 x^{1/\alpha} \psi(x) \, dx \cdot z \log z + \alpha z^{1/\alpha} \psi(z) \Big) t^{\rho} \Big|.$$

Threshold Selection Problem Asymptotics Simulations

Under Second Order Condition LPAN

# Simulations: Fréchet distribution

 $F(x) = \exp(-x^{-4}), \quad x > 0$ 



Left: qf of  $k^*/n$  for n = 1000; red line indicates RMSE minimizing value Right: RMSE of Hill estimator as function of k; red line indicates RMSE of  $\hat{\alpha}_{n,k^*}$ 

Drees

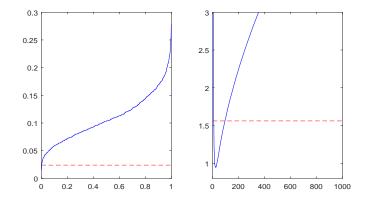
16/24

Threshold Selection Problem Asymptotics Simulations

Under Second Order Condition LPAN

#### Simulations: Student's *t*-distribution

F Student's t cdf with 4 degrees of freedom



Left: qf of  $k^*/n$  for n = 1000; red line indicates RMSE minimizing value Right: RMSE of Hill estimator as function of k; red line indicates RMSE of  $\hat{\alpha}_{n,k^*}$ 

#### Loss of efficiency

Increase of RMSE and standard deviation relative to Hill estimator with deterministic k minimizing the RMSE; sample size n = 1000

		distance minimization		Lepskii's method
F	α	RMSE	SD	RMSE
Frechet	1	41%	22%	12%
	5	37%	14%	12%
t	1	32%	30%	15%
	4	63%	-28%	14%
	10	49%	-62%	30%
Stable	1/2	37%	13%	30%
log-gamma	3	35%	-32%	9%

医下子 医下

э

# LPAN are oriented graphs successively built starting from a core network; in each step one of the following randomly chosen procedures is applied

- (a) add new node and edge from this node to an existing node w;
   latter is chosen with probability proportional to number of existing incoming edges of w plus a constant δ<sub>in</sub>;
- (b) add new edge from existing node v to existing node w;
   pair is chosen with probability proportional to (number of existing outgoing edges of v plus a constant δ<sub>out</sub>) × (number of existing incoming edges of w plus a constant δ<sub>in</sub>);
- (c) add new node and edge from an existing node v this node; v is chosen with probability proportional to number of existing outgoing edges of v plus a constant  $\delta_{out}$

E >

LPAN are oriented graphs successively built starting from a core network; in each step one of the following randomly chosen procedures is applied

- (a) add new node and edge from this node to an existing node w; latter is chosen with probability proportional to number of existing incoming edges of w plus a constant  $\delta_{in}$ ;
- (b) add new edge from existing node v to existing node w;
   pair is chosen with probability proportional to (number of existing outgoing edges of v plus a constant δ<sub>out</sub>) × (number of existing incoming edges of w plus a constant δ<sub>in</sub>);
- (c) add new node and edge from an existing node v this node; v is chosen with probability proportional to number of existing outgoing edges of v plus a constant  $\delta_{out}$

LPAN are oriented graphs successively built starting from a core network; in each step one of the following randomly chosen procedures is applied

- (a) add new node and edge from this node to an existing node w; latter is chosen with probability proportional to number of existing incoming edges of w plus a constant  $\delta_{in}$ ;
- (b) add new edge from existing node v to existing node w;
   pair is chosen with probability proportional to (number of existing outgoing edges of v plus a constant δ<sub>out</sub>) × (number of existing incoming edges of w plus a constant δ<sub>in</sub>);

(c) add new node and edge from an existing node v this node; v is chosen with probability proportional to number of existing outgoing edges of v plus a constant  $\delta_{out}$ 

・ 同 ト ・ ヨ ト ・ ヨ ト

LPAN are oriented graphs successively built starting from a core network; in each step one of the following randomly chosen procedures is applied

- (a) add new node and edge from this node to an existing node w; latter is chosen with probability proportional to number of existing incoming edges of w plus a constant  $\delta_{in}$ ;
- (b) add new edge from existing node v to existing node w;
   pair is chosen with probability proportional to (number of existing outgoing edges of v plus a constant δ<sub>out</sub>) × (number of existing incoming edges of w plus a constant δ<sub>in</sub>);
- (c) add new node and edge from an existing node v this node; v is chosen with probability proportional to number of existing outgoing edges of v plus a constant  $\delta_{out}$

# Asymptotics of linear preferential attachment networks Let

n: total number of nodes

 $n_i^{(in)}$ : number of nodes with *i* incoming edges

 $n_i^{(out)}$ : number of nodes with *i* outgoing edges

#### Ballobás et al. (2003):

 $(n_i^{(in)}/n)_{i \in \mathbb{N}_0}$ ,  $(n_i^{(out)}/n)_{i \in \mathbb{N}_0}$  converge to pmf of distribution with Pareto type tail; exponents  $\alpha^{(in)}, \alpha^{(out)}$  can be calculated from probabilities of three procedures and  $\delta_{in}, \delta_{out}$ 

(see Samorodnitsky et al. (2016) and Wang & Resnick (2016) for results on joint multivariate regular variation)

In the following simulations, in-degrees are observed; note that observations are not iid.

э

Asymptotics of linear preferential attachment networks Let

n: total number of nodes

 $n_i^{(in)}$ : number of nodes with *i* incoming edges

 $n_i^{(out)}$ : number of nodes with *i* outgoing edges

Ballobás et al. (2003):

 $(n_i^{(in)}/n)_{i \in \mathbb{N}_0}, (n_i^{(out)}/n)_{i \in \mathbb{N}_0}$  converge to pmf of distribution with Pareto type tail; exponents  $\alpha^{(in)}, \alpha^{(out)}$  can be calculated from probabilities of three procedures and  $\delta_{in}, \delta_{out}$ 

(see Samorodnitsky et al. (2016) and Wang & Resnick (2016) for results on joint multivariate regular variation)

In the following simulations, in-degrees are observed; note that observations are not iid.

医下颌 医下颌

-

Asymptotics of linear preferential attachment networks Let

n: total number of nodes

 $n_i^{(in)}$ : number of nodes with *i* incoming edges

 $n_i^{(out)}$ : number of nodes with *i* outgoing edges

Ballobás et al. (2003):

 $(n_i^{(in)}/n)_{i \in \mathbb{N}_0}, (n_i^{(out)}/n)_{i \in \mathbb{N}_0}$  converge to pmf of distribution with Pareto type tail; exponents  $\alpha^{(in)}, \alpha^{(out)}$  can be calculated from probabilities of three procedures and  $\delta_{in}, \delta_{out}$ 

(see Samorodnitsky et al. (2016) and Wang & Resnick (2016) for results on joint multivariate regular variation)

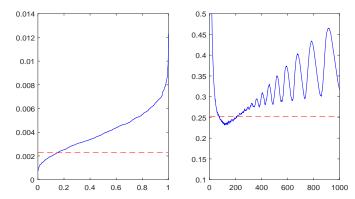
In the following simulations, in-degrees are observed; note that observations are not iid.

-

Threshold Selection Problem Asymptotics LPAN Simulations

#### Simulations: LPAN

Model: probability of procedures (a)/(b)/(c): 0.3 / 0.5 / 0.2  $\delta_{in} = 2, \quad \delta_{out} = 1 \qquad (\Rightarrow \alpha = 2.5)$ 



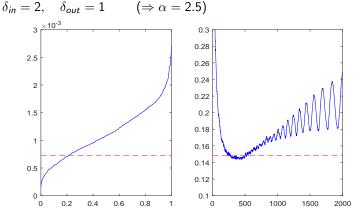
Left: qf of  $k^*/n$  for n = 50,000; red line indicates RMSE minimizing value Right: RMSE of Hill estimator as function of k; red line indicates RMSE of  $\hat{\alpha}_{n,k^*}$ increase of RMSE  $\approx 9\%$  (relative to optimal fixed k)

Threshold Selection Problem Asymptotics Simulations

Under Second Order Condition LPAN

#### Simulations: LPAN (cont.)

Model: probability of procedures (a)/(b)/(c): 0.3 / 0.5 / 0.2



Left: qf of  $k^*/n$  for n = 500,000; red line indicates RMSE minimizing value Right: RMSE of Hill estimator as function of k; red line indicates RMSE of  $\hat{\alpha}_{n,k^*}$ increase of RMSE  $\approx 4\%$  (relative to optimal fixed k)

Q.: Why does minimum distance selection perform so much better for LPAN data than for iid data under second order condition?

Possible answers: Because of

- large sample size,
- discrete data,
- dependence,

conceptual difference to lid setting:

< ∃⇒

Q.: Why does minimum distance selection perform so much better for LPAN data than for iid data under second order condition?

Possible answers: Because of

- large sample size,
- discrete data,
- dependence,
- conceptual difference to iid setting:

< ∃⇒

Q.: Why does minimum distance selection perform so much better for LPAN data than for iid data under second order condition?

Possible answers: Because of

- large sample size, but e.g. for iid Cauchy much worse behavior
- discrete data,
- dependence,
- conceptual difference to iid setting:

< ∃ →

Q.: Why does minimum distance selection perform so much better for LPAN data than for iid data under second order condition?

Possible answers: Because of

- large sample size, but e.g. for iid Cauchy much worse behavior
- discrete data, but e.g. for iid discretized Fréchet much worse behavior
- dependence,
- conceptual difference to iid setting:

in iid setting,  $\alpha$  has some clear meaning as exponent of regular variation of 1 - F for all  $\alpha$ 

in LPAN, for any fixed *n*, distribution of in-degrees does not have a power tail, i.e.  $\alpha$  is meaningful only for  $n \to \infty$ 

For fixed n, there is no true  $\alpha$ . Hence calculated RMSE has a completely different meaning that is an iid setting

Thus, here the RMSE may be mainly caused by difference between cdf of

Q.: Why does minimum distance selection perform so much better for LPAN data than for iid data under second order condition?

Possible answers: Because of

- large sample size, but e.g. for iid Cauchy much worse behavior
- discrete data, but e.g. for iid discretized Fréchet much worse behavior
- dependence, maybe, but why?
- conceptual difference to iid setting:

in iid setting, lpha has same clear meaning as exponent of regular variation of 1-F for all n

in LPAN, for any fixed *n*, distribution of in-degrees does not have a power tail, i.e.  $\alpha$  is meaningful only for  $n \rightarrow \infty$ 

- For fixed n, there is no true  $\alpha$ . Hence calculated RMSE has a completely different meaning than in an iid setting.
- Thus, here the RMSE may be mainly caused by difference between cdf of indegrees and limit cdf not by a feature of the estimators

< ∃⇒

Q.: Why does minimum distance selection perform so much better for LPAN data than for iid data under second order condition?

Possible answers: Because of

- large sample size, but e.g. for iid Cauchy much worse behavior
- discrete data, but e.g. for iid discretized Fréchet much worse behavior
- dependence, maybe, but why?
- conceptual difference to iid setting:

in iid setting,  $\alpha$  has same clear meaning as exponent of regular variation of 1-F for all n

in LPAN, for any fixed *n*, distribution of in-degrees does not have a power tail, i.e.  $\alpha$  is meaningful only for  $n \to \infty$ ! For fixed *n*, there is no true  $\alpha$ . Hence calculated RMSE has a completely different meaning than in an iid setting. Thus, here the RMSE may be mainly caused by difference between cdf of in-degrees and limit cdf, not by a feature of the estimators.

Q.: Why does minimum distance selection perform so much better for LPAN data than for iid data under second order condition?

Possible answers: Because of

- large sample size, but e.g. for iid Cauchy much worse behavior
- discrete data, but e.g. for iid discretized Fréchet much worse behavior
- dependence, maybe, but why?
- conceptual difference to iid setting:

in iid setting,  $\alpha$  has same clear meaning as exponent of regular variation of 1-F for all n

in LPAN, for any fixed *n*, distribution of in-degrees does not have a power tail, i.e.  $\alpha$  is meaningful only for  $n \to \infty$ ! For fixed *n*, there is no true  $\alpha$ . Hence calculated RMSE has a completely different meaning than in an iid setting. Thus, here the RMSE may be mainly caused by difference between cdf of in-degrees and limit cdf, not by a feature of the estimators.

23/24

Q.: Why does minimum distance selection perform so much better for LPAN data than for iid data under second order condition?

Possible answers: Because of

- large sample size, but e.g. for iid Cauchy much worse behavior
- discrete data, but e.g. for iid discretized Fréchet much worse behavior
- dependence, maybe, but why?
- conceptual difference to iid setting:

in iid setting,  $\alpha$  has same clear meaning as exponent of regular variation of 1-F for all n

in LPAN, for any fixed *n*, distribution of in-degrees does not have a power tail, i.e.  $\alpha$  is meaningful only for  $n \to \infty$ !

For fixed *n*, there is no true  $\alpha$ . Hence calculated RMSE has a completely different meaning than in an iid setting.

Thus, here the RMSE may be mainly caused by difference between cdf of in-degrees and limit cdf, not by a feature of the estimators.

23/24

Threshold Selection Problem Asymptotics Simulations Under Second Order Condition LPAN

# Thank you for your attention!

프 🕨 🖉