# On Poisson approximation for local sequence alignments

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based on the

joint work with Hrvoje Planinić

#### **Scoring alignments**

Let  $A_1, \ldots, A_n$  and  $B_1, \ldots, B_m$  be two independent iid sequences of letters (words) in finite alphabet  $\mathcal{A}$  e.g.  $\{A, C, T, G\}$  with distributions  $\mu_A$  and  $\mu_B$  respectively. For purpose of this lecture assume m = n.

**Score function**  $s : \mathcal{A} \times \mathcal{A} \rightarrow \mathbb{R}$  measures similarity of letters:

positive  $s \leftrightarrow \text{similar letters}$ .

For independent sequences we assume

$$\mathbb{E}s(A,B) < 0 \quad \text{and} \quad \mathbb{P}(s(A,B) > 0) > 0.$$
(1)

#### ...GTAACTGAATCGCTTATG... ...CACGGGCTGATTCGCTCG...



...GTAACTGAATCGCTTATG... ...CGGGGCTGATTCGCTCGAA... For any  $i, j \in \mathbb{Z}_+$  one compares sequences A and B up to these two positions by calculating

$$S_{i,j} = \left(\sup_{m < i,j} \sum_{0}^{m} s(A_{i-k}, B_{j-k}))\right)_{+}$$

It turns out one can ignore the edge effects and index the sequences over  $\mathbb{Z}$ , i.e. set

$$S_{i,j} = \left(\sup_{m} \sum_{0}^{m} s(A_{i-k}, B_{j-k}))\right)_{+}$$

Clearly array  $(S_{i,j})$  is stationary and for  $Z_{i,j} = s(A_i, B_j)$  on the **diagonal** Lindley recursion applies

$$S_{i,j} = (S_{i-1,j-1} + Z_{i,j})_+ .$$
<sup>(2)</sup>

It is easy to show that under (1) there exists a unique  $\alpha^* > 0$  such that

$$\mathbb{E}e^{\alpha^* Z} = \mathbb{E}e^{\alpha^* s(A,B)} = 1$$

Thus if Z = s(A, B) has **nonarithmetic distribution**, Cramér's arguments show that scores  $(S_{i,j})$  form a stationary array with asymptotically **exponential tail**, i.e. as  $u \to \infty$ 

$$\mathbb{P}(S > u) \sim C e^{-\alpha^* u} \,.$$

In particular as  $n \rightarrow \infty$  for any x

$$n^2 \mathbb{P}(S > \log n^{2/\alpha^*} + x) \to C e^{-\alpha^* x}$$

thus one may expect that  $M_n = \sup_{i,j \le n} S_{i,j}$  under some conditions satisfies

$$M_n - \log n^{2/\alpha^*} \stackrel{d}{\to} G$$
, (3)

where

$$G(x) = e^{-\vartheta C e^{-\alpha^* x}},$$

for some  $\vartheta \in [0,1]$ .

Actually, under conditions on s and  $\mu_A, \mu_B$  above, Dembo, Karlin and Zeitouni showed

$$M_n / \log n^{2/\alpha^*} \stackrel{\text{a.s.}}{\to} \gamma \le 1$$
.

Under (3)  $\gamma = 1$ , but this is not always the case — dependence is the key.

Dependence in such an array is indeed typically weak and one can often show that (3) holds i.e. the distribution of its maxima  $M_n$  over finite rectangle  $\{1, \ldots, n\} \times \{1, \ldots, n\}$  after centering tends to the **Gumbel distribution** (cf. Karlin & Altschul, Dembo et al., Arratia et al., Neuhauser, Siegmund & Yakir, Hansen,...). Thus extreme value theory is used to test unrelatedness in evolutionary biology  $\longrightarrow$  still, biologist use more than just the maximum.



cf.A.Coghlan

dot plot, cf. Metzler et al.

#### ....GTAACTGAATCGCTTATG.... ....CGGGGCTGATTCGCTCGAA....



...GTAACTGAATCGCTTATG... ...GGGCTGATTCGCTCGAAG...







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Recall Kulback-Leibler **divergence** between probability measures  $\nu$  and  $\mu$  on finite set  $A_0$  is defined by

$$H(\nu \mid \mu) = \sum_{a' \in \mathcal{A}'} \log \nu(a') \frac{\nu(a')}{\mu(a')}.$$

On  $A_0 = A \times A$  if  $\mu$  is the law of the pair (A, B) with marginals  $\mu_A$  and  $\mu_B$ , the quantity

 $H(\mu \mid \mu_A \times \mu_B) \ge 0$ 

is called mutual information, it equals 0 iff  $\mu = \mu_A imes \mu_B$  .

Probability measure  $\mu = \mu_A imes \mu_B$  can be tilted to

$$\mu^*(a,b) = e^{\alpha^* s(a,b)} \mu(a,b) = e^{\alpha^* s(a,b)} \mu_A(a) \mu_B(b) \,.$$

Under measure  $\mu^*$ 

▶ pairs  $(A_i, B_i)$  are still iid, but with possible mutual dependence, thus in general  $\mu^* \neq \mu^*_A \times \mu^*_B$ .

tilting gives positive drift to diagonal random walk in (2).

The case  $\mu^* = \mu_A^* \times \mu_B^*$  is degenerate

$$H(\mu^* \mid \mu) = H(\mu_A^* \mid \mu_A) + H(\mu_B^* \mid \mu_B)$$

which further equals  $2 \max\{H(\mu_A^* \mid \mu_A), H(\mu_B^* \mid \mu_B)\}$  when everything symmetric.

It turns out that we need the following (cf. Dembo et al. 1994) assumption

$$H(\mu^* \mid \mu) > 2 \max\{H(\mu_A^* \mid \mu_A), H(\mu_B^* \mid \mu_B)\}.$$
(4)

This excludes scoring functions of the form

$$s(a,b) = s_1(a) + s_2(b)$$
.

and degenerate distributions for A or B.

## planinić, b. (2018) **Theorem** Under assumptions above on $\mu_A, \mu_B$ and s on $[0, 1]^2 \times \mathbb{R}$ $N_n = \sum_{i,j} \delta_{\underline{i,j}, S_{i,j} - \log n^{2/\alpha^*}} \stackrel{d}{\to} \sum_{i} \sum_{j} \delta_{(T_i, \hat{P}_i + \hat{Q}_{i,j})}.$ Where $\triangleright \quad \sum_i \delta_{(T_i,\hat{P}_i)} \text{ is } \mathsf{PRM}(\mathsf{Leb} imes u) \text{ where } u(x,\infty) = artheta C e^{-lpha^* x} \text{ and }$ $\triangleright$ $((\hat{Q}_{i,j}))$ is a sequence of iid random elements in $\mathbb{R}^{\mathbb{Z}}$ such that $\sup_{j} \hat{Q}_{i,j} = 0$ a.s.

## **Poisson** approximation

Assume that an array of independent rv's  $X_{n,i}$ ,  $i \in I_n$  is such that for all (i.e. "bounded") sets of interest K,

$$\lim_{n} \max_{i} \mathbb{P}(X_{n,i} \in K) = 0 \quad \text{and} \quad \sum_{i} \mathbb{P}(X_{n,i} \in \cdot) \stackrel{v}{\to} \nu.$$

Then

$$\sum_{I_n} \delta_{X_{n,i}} \stackrel{d}{\to} N \sim \mathsf{PRM}(\nu).$$

In special cases, Chen–Stein method gives a rate of convergence as well, and handles dependence even for point process convergence on compact spaces (cf. Arratia et al. and Barbour and Brown).

Recall the convergence of point processes in distribution (wrt vague topology) is equivalent to convergence of Laplace functionals, i.e.

$$N_n = \sum_{I_n} \delta_{X_{n,i}} \stackrel{d}{
ightarrow} N$$

iff

$$\mathbb{E}\exp(-N_n f) = \mathbb{E}\exp\left(-\sum_{I_n} f(X_{n,i})\right) \to \mathbb{E}\exp(-Nf)$$

for all nonneg. continuous f with support in some bounded set K.

#### Arrays and neighbourhoods

$$\begin{split} I_n = & \text{sequence of index sets, e.g. } I_n = \{1, \ldots, k_n\}, k_n \to \infty \\ X_{n,i} = & \text{sequence of random elements in a Polish space } \mathbb{X}' \\ B_i = B_{n,i} = & \text{predetermined neighbourhoods of each } i, i \in B_i \\ \sigma(I_n \setminus B_i) = \sigma - & \text{algebra generated by } X_{n,i} \not\in B_i \end{split}$$

Consider bounded  $K \subseteq \mathbb{X} \subseteq \mathbb{X}'$  and

**Measures of clustering**: for fixed K and f nonneg. bounded continuous with support in K, i.e.  $\in C_K$ 

$$b_{1} = \sum_{i \in I_{n}} \sum_{j \in B_{i} \setminus \{i\}} \mathbb{P}(X_{n,i} \in K) \cdot \mathbb{P}(X_{n,j} \in K)$$
$$b_{2} = \sum_{i \in I_{n}} \sum_{j \in B_{i} \setminus \{i\}} \mathbb{P}(X_{n,i} \in K, X_{n,j} \in K)$$
$$b_{3} = \sum_{i \in I_{n}} \mathbb{E} \left| \mathbb{E} \left[ e^{-f(X_{n,i})} \mid \sigma(I_{n} \setminus B_{i}) \right] - \mathbb{E}[e^{-f(X_{n,i})}] \right|$$

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#### Theorem If

$$\lim_{n} \max_{i} P(X_{n,i} \in K) = 0 \quad \text{and} \quad \sum_{i \in I_n} \mathbb{P}(X_{n,i} \in \cdot) \xrightarrow{v} \lambda$$

and for all bounded K and  $f\in\mathcal{C}_K$ 

$$b_1, b_2, b_3 \longrightarrow 0.$$

Then

$$N_n = \sum_{I_n} \delta_{X_{n,i}} \stackrel{d}{\to} N ,$$

where N is  $PRM(\lambda)$ .

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**Corollary** Suppose  $I_n = \{1, \ldots, k_n\}^d$ , and  $X_{n,i}$  are identically distributed, if  $k_n^d \mathbb{P}(X_{n,1} \in \cdot) \xrightarrow{v} \nu$ 

and for all bounded K and  $f \in \mathcal{C}_R$ 

$$b_1, b_2, b_3 \longrightarrow 0.$$

Then

$$N_n = \sum_{I_n} \delta_{\frac{i}{k_n}, X_{n,i}} \stackrel{d}{\to} N ,$$

where N is  $\mathsf{PRM}(\mathsf{Leb} \times \nu)$ .

#### **Regularly varying arrays**

Consider a stationary array of random variables  $\boldsymbol{X} = (X_{\boldsymbol{i}} : \boldsymbol{i} \in \mathbb{Z}^d).$ 

We observe X over large (and increasing) section of  $\mathbb{Z}^d$ , for instance a square

$$\{1,\ldots,n\}\times\{1,\ldots,n\}$$

#### Independent observations indexed over $\mathbb{Z}$

cf. Leadbetter-Rootzén, Resnick

Take a sequence  $(a_n)$  s.t.

$$nP(X_0/a_n \in \cdot) \xrightarrow{v} \mu$$
,

for measure  $\mu$  s.t. for x > 0

 $\mu(-\infty,-x)=qx^{-\alpha} \quad \text{ and } \quad \mu(x,\infty)=px^{-\alpha}\,.$ 

**Theorem** For iid  $X_t$ , regular variation is equivalent to

$$N_n = \sum_1^n \delta_{rac{i}{n}, rac{X_i}{a_n}} \stackrel{d}{
ightarrow} N = \sum_i \delta_{T_i, P_i} \,,$$

where N is  $\mathsf{PRM}(\mathsf{Leb} \times \mu)$ .

Stationary array X is regularly varying with index  $\alpha > 0$  if all of its fidi's are multivariate regularly varying with index  $\alpha$ .

Or equivalently if there exists a tail process/array such that as  $x \to \infty$ 

$$\left(\frac{X_{t}}{x}\right)_{t\in\mathbb{Z}^{d}}\left|\left|X_{0}\right|>x\overset{d}{\to}(Y_{t})_{t\in\mathbb{Z}^{d}}\right|$$

Clearly

 $|Y_0| \sim \mathsf{Pareto}(\alpha)$ .

On  $\mathbb{Z}^d$  we will consider the **lexicographic order** 

e.g. for 
$$d = 2$$
 and  $\mathbf{i} = (i_1, i_2), \mathbf{j} = (j_1, j_2) \in \mathbb{Z}^2$   
 $\mathbf{i} \leq \mathbf{j} \iff i_1 < j_1 \text{ or } (i_1 = j_1 \text{ and } i_2 \leq j_2).$ 

For m = 1, 2, ... introduce **rectangular section** of the array

$$\boldsymbol{X}_m = \left(X_{\boldsymbol{k}} : \boldsymbol{k} = \left(k_1, \ldots, k_d\right), 1 \leq k_i \leq m\right).$$

#### **Restricting dependence**

Take  $a_n \rightarrow \infty$  such that

 $n^d \mathbb{P}(X_0/a_n \in \cdot) \xrightarrow{v} \mu.$ 

And assume for some  $r_n\!\rightarrow\infty$  and  $r_n/n\rightarrow 0$ 

$$\lim_{m \to \infty} \limsup_{n \to \infty} \mathbb{P}\left( \bigvee_{m \le \|\boldsymbol{i}\| \le r_n} |X_{\boldsymbol{i}}| > a_n u \middle| |X_{\boldsymbol{0}}| > a_n u \right) = 0, \quad u > 0.$$
 (AC)

(AC) implies

$$Y_{\boldsymbol{i}} \stackrel{\text{a.s.}}{\to} 0, \text{ as } \|\boldsymbol{i}\| \to \infty, \text{ and } \vartheta = \mathbb{P}(\sup_{\boldsymbol{j}<0} |Y_{\boldsymbol{j}}| \le 1) > 0.$$

#### Dependent observations indexed over $\ensuremath{\mathbb{Z}}$

Building on Davis & Resnick, Davis & Hsing, Davis & Mikosch,... Planinić, Soulier, B.(2018), Tafro, B.(2016) & Krizmanić, Segers, B. (2012) prove convergence of point processes.

#### **Blocks of data**

Consider a block

$$rac{oldsymbol{X}_{r_n}}{a_n}$$

as an element of

$$\tilde{l}_0 = \{ \boldsymbol{x} = (x_i)_{i \in \mathbb{Z}^d} : \lim_{|i| \to \infty} x_i = 0 \} / \sim$$

where we set  $x \sim y$  if they are equal up to a shift. With sup norm  $\tilde{l}_0$  is a separable complete metric space.

#### Limits of blocks



Note, conditionally on  $\sup_{j < 0} |Y_j| \le 1$ , random variable  $L_Y = \sup_{i \in \mathbb{Z}^d} |Y_i|$ and random cluster

$$\boldsymbol{Q} = (Q_{\boldsymbol{i}})_{\boldsymbol{i}} = (Y_{\boldsymbol{i}}/L_Y)_{\boldsymbol{i}}$$

are independent.

Then, for some homogeneous measure  $\nu = \nu_{\vartheta,\alpha,Q}$  on  $\tilde{l}_0$ , (AC) implies

$$k_n^d \mathbb{P}\left(\frac{\boldsymbol{X}_{r_n}}{a_n} \in \cdot\right) \stackrel{v}{\to} \nu$$

#### **Convergence theorem**

for blocks of data

Set  $k_n = \lfloor n/r_n \rfloor$  and for  $i \in K_n = \{1, \ldots, k_n\}^d$  introduce rectangular section of the array

$$\boldsymbol{X}_{n,\boldsymbol{i}} = (X_{\boldsymbol{k}} : \boldsymbol{k} \in ((\boldsymbol{i}-1)r_n, \boldsymbol{i}r_n]).$$

Consider the point process of clusters, on  $[0,1]^d imes \tilde{l}_0$  defined by

$$N_n'' = \sum_{\boldsymbol{i} \in K_n} \delta_{rac{\boldsymbol{i}}{k_n}, rac{\boldsymbol{x}_{n, \boldsymbol{i}}}{a_n}} \; .$$

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**Theorem** Suppose (AC) holds if for all bounded K and  $f \in C_R$   $b_1, b_2, b_3 \longrightarrow 0.$ Then  $N''_n \stackrel{d}{\to} N'' = \sum_i \delta_{(T_i, P_i \cdot Q_i)}.$ and N is PRM(Leb $\times \nu$ ).

In particular

$$\mathbb{P}\left(\frac{M_n}{a_n} \le x\right) \xrightarrow{d} e^{-\vartheta x^{-\alpha}}$$

#### Probabilistic model for the dot-plots

**Step 1** transformation  $S_{ij} \mapsto X_{ij} = e^{S_i j}$  gives a stationary regularly varying field.

**Step 2**  $(X_{ij})$  satisfies (AC) except in degenerate case  $s(a,b) = s_1(a) + s_2(b)$ .

**Step 3** Blocking observations  $(X_{ij})$  into  $r_n \times r_n$  squares is justified.

**Step 4** Under (4) one can show

$$b_1, b_2, b_3 \longrightarrow 0.$$

for all bounded K in space  $\tilde{l}_0$  and corresponding f's.

## ¡ Muchas gracias !

#### Approximation with m-dependent arrays

Assume there exists a sequence of  $m-{\rm dependent}$  regularly varying arrays  $(X_{\pmb{i}}^{(m)})$  such that

$$n^{d}\mathbb{P}(|X^{(m)}| > a_n) \to d^{(m)} > 0.$$

Then on  $\widetilde{l}_0 \setminus \{\mathbf{0}\}$ 

$$k_n^d \mathbb{P}\left(\frac{\boldsymbol{X}_{r_n}^{(m)}}{a_n} \in \cdot\right) \xrightarrow{v} \nu^{(m)}.$$

Assume further

(i) measures  $\nu^{(m)}$  converge in vague-topology to a nonzero measure  $\nu$ . (ii) for any u > 0

$$\lim_{m \to \infty} \limsup_{n \to \infty} \mathbb{P}(\max_{|\mathbf{i}| \le n} |X_{\mathbf{i}}^{(m)} - X_{\mathbf{i}}| > a_n u) = 0.$$

#### **Theorem** Under assumptions above, as $n \to \infty$ ,

$$N_n'' \stackrel{d}{\to} N'' = \sum_i \delta_{(T_i, P_i \cdot Q_i)}.$$

#### Example

Spatial moving average process, assume  $\xi_{i}$  are iid  $\mathrm{RegVar}(\alpha)$  and for some  $(c_{t})$ 

$$X_t = \sum_{\mathbb{Z}^d} c_i \xi_{t-i} \,,$$

e.g.

$$X_{t,s} = \sum_{i,j} c_{i,j} \xi_{t-i,s-j} \,.$$

is regularly varying if  $\sum_{j \in \mathbb{Z}^2} |c_j|^{\delta} < \infty$  for some  $\delta < \alpha \wedge 1$  (Davis and Resnick 1985). Appropriate approximation is of course

$$X_{t,s}^{(m)} = \sum_{|i|,|j| < m/2} c_{i,j} \xi_{t-i,s-j} \,.$$

### Thank you very much!