Simulated Tempering Method in the Infinite Switch Limit with Adaptive Weight Learning

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Molecular Dynamics Sampling





• Canonical distribution for *q* (positions) and *p* (momentum):

$$\rho_{\beta}(\boldsymbol{q}, \boldsymbol{p}) = Z^{-1}(\beta) \boldsymbol{e}^{-\beta \frac{1}{2} \boldsymbol{p}^{T} \boldsymbol{m}^{-1} \boldsymbol{p} - \beta V(\boldsymbol{q})}$$

where V(q) is potential and $Z(\beta)$ is the normalisation constant, $\beta > 0$ reciprocal temperature



• Ergodic Average of observable A(q),

$$\mathbb{E}_{\beta}\left[A\right] = \int A(q)\rho_{\beta}(q,p) \, \mathrm{d}p \, \mathrm{d}q = \lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} A(q(t)) \, \mathrm{d}t$$

 Standard sampling methods for ρ_β(q, p) such as e.g. Monte Carlo or Langevin Dynamics,

$$dq = m^{-1}p \, \mathrm{d}t$$
$$dp = -\nabla V(q) \, \mathrm{d}t - \gamma p \, \mathrm{d}t + \sqrt{2\gamma\beta^{-1}m} \, \mathrm{d}W$$

struggle with energetic and entropic barriers

 Accelerated sampling: Simulated Annealing, Replica Exchange Molecular Dynamics, Simulated Tempering, Wang-Landau, Adaptive Force Biasing, Temperature-accelerated Molecular Dynamics, Hamiltonian Replica Exchange, ...

Simulated Tempering



• Temperature "ladder" with $M = T_{j+1}$ steps, with spacing $\Delta T = T_{j}$

$$T_{\min} = T_1 < \ldots < T_M = T_{\max}$$



- Let $\beta_i = (k_B T_i)^{-1}$ with assigned weight $\omega(\beta_i)$
- Switch every τ steps from $\beta_i \rightarrow \beta_j$ with probability α_{ij} ,

$$\alpha_{ij} = \min\{1, \frac{\omega(\beta_i)}{\omega(\beta_j)} e^{-(\beta_i - \beta_j) V(q)}\}$$

• Invariant measure with density,

$$\rho(\boldsymbol{q},\boldsymbol{p},\beta_i) = \boldsymbol{C}^{-1}(\beta)\omega(\beta_i)\boldsymbol{e}^{-\frac{1}{2}\beta\boldsymbol{p}^T\boldsymbol{m}^{-1}\boldsymbol{p}-\beta_i\boldsymbol{V}(\boldsymbol{q})}$$

where
$$\mathcal{C}(eta) = \sum_{i=1}^{M} \int_{\mathcal{D} imes \mathbb{R}^d} \omega(eta_i) e^{-rac{1}{2}eta p^T m^{-1} p - eta_i V(q)} \, \mathrm{d}q \, \mathrm{d}p$$

Simulated Tempering Parameters



- Choice of switch period, τ ?
- **2** How do we justify $\omega(\beta_i) = Z_q^{-1}(\beta_i)$?

$$\mathbb{P}(\beta_i) = \frac{\omega(\beta_i) \ Z_q(\beta_i)}{\sum_{j=1}^M \omega(\beta_j) \ Z_q(\beta_j)}.$$

Solution Can we learn $\omega(\beta_i)$ weights on-the-fly?

Remarks:

- Grid Spacing, ΔT . Is there a way to motivate the choice?
- How do we calculate an average from ρ_{β_i} i.e $\mathbb{E}_{\beta_i}[A]$?

Infinite Switch Limit of Simulated Tempering, $\tau \rightarrow 0$.

 ${}^{\text{MI}}_{\text{GS}}AA$

- Follows same large deviation approach as for REMD by Dupuis et. al. ^{1 2}
- ST in τ → 0 limit for some continuous β_c ∈ [β_{min}, β_{max}] is equivalent to sampling the averaged potential ³,

$$ar{V}(q) = -eta^{-1} \log \int_{eta_{\min}}^{eta_{\max}} \omega(eta_{c}) e^{-eta_{c} V(q)} deta_{c}$$

for some prior known weights $\omega(\beta_c)$.

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<sup>1</sup>Dupuis et. al. 2012.
<sup>2</sup>Plattner et. al 2011.
<sup>3</sup>A.M. et. al. 2018.
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The rate functional P (ν_T ≈ μ) ≍ exp [-T⁻¹I_τ(μ)] of the ergodic dynamics is a monotonically decreasing function of τ, i.e if

$$au < au' \implies I_{ au}(\mu) \geq I_{ au'}(\mu)$$

For faster convergence to μ , let $\tau \rightarrow 0$.

• The dynamical equations in au
ightarrow 0 limit,

$$dq = m^{-1}p \, dt,$$

$$dp = -\beta^{-1}\bar{\beta}(V(q))\nabla V \, dt - \gamma p \, dt + \sqrt{2\gamma\beta^{-1}m^{-1}} \, dW_p$$

which implies that we have averaged potential,

$$ar{V}(q) = -eta^{-1} \log \int_{eta_{\min}}^{eta_{\max}} \omega(eta_c) e^{-eta_c V(q)} deta_c$$

Simulated Tempering Parameters



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3 Can we learn
$$\omega(\beta_i)$$
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Justification of $\omega(\beta) \propto Z_q^{-1}(\beta)$.



• The density function of V(q)

$$\bar{\rho}(\boldsymbol{E}) = \frac{\int_{\beta_{\min}}^{\beta_{\max}} \boldsymbol{e}^{-\beta_{c}\boldsymbol{E}}\omega(\beta_{c}) \, \mathrm{d}\beta_{c}}{\int_{\beta_{\min}}^{\beta_{\max}} Z_{q}(\beta_{c})\omega(\beta_{c}) \, \mathrm{d}\beta_{c}} \, \Omega(\boldsymbol{E}),$$

where
$$\Omega(E) = \int_{\mathcal{D}} \delta(V(q) - E) \, \mathrm{d}q$$
.

• In that large system size limit,

$$\bar{\rho}(E) \asymp 1$$

when $\omega(\beta) \propto Z_q^{-1}(\beta)$.

Simulated Tempering Parameters



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Adaptive $\omega(\beta_c)$ adjustment as we learn $Z_q(\beta_c)$.

Outline of $\omega(\beta_c)$ Adjustment Results: part 1



• For $\beta_{c} \in [\beta_{\min}, \beta_{\max}]$ we can construct

$$z(t,\beta_c) = \frac{1}{t} \int_0^t \frac{e^{-\beta_c V(q(s))}}{\int_{\beta_{\min}}^{\beta_{\max}} \omega(\beta'_c) e^{-\beta'_c V(q(s))} d\beta'_c} ds$$

which can be calculated for all t > 0.

• In the limit as $t \to \infty$,

$$\lim_{t\to\infty} z(t,\beta_c) = \frac{Z_q(\beta_c)}{\int_{\beta_{\min}}^{\beta_{\max}} Z_q(\beta_c')\omega(\beta_c') \,\mathrm{d}\beta_c'},$$

 This implies that we learn ratios of Z_q(β_c) regardless of knowledge of ω(β_c),

$$\lim_{t\to\infty}\frac{z(t,\beta_c)}{z(t,\beta_c')}=\frac{Z_q(\beta_c)}{Z_q(\beta_c')}$$



• Define $z(t, \beta_c)$ as,

$$z(t,\beta_c) = \frac{1}{t} \int_0^t \frac{e^{-\beta_c V(q(s))}}{\int_{\beta_{\min}}^{\beta_{\max}} \omega(\beta'_c) e^{-\beta'_c V(q(s))} d\beta'_c} ds$$

Adjusting the weights according to,

$$\kappa \dot{\omega}(t,\beta_c) = z^{-1}(t,\beta_c) - \lambda(t)\omega(t,\beta), \text{ with } \lambda(t) = \int_{\beta_{\min}}^{\beta_{\max}} z^{-1}(t,\beta_c) \, \mathrm{d}\beta_c$$

will ensure that $\omega(t,\beta_c) \propto Z_q^{-1}(\beta_c)$ as $t \to \infty$.

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$$\mathbb{P}(\beta_i) = \frac{\omega(\beta_i) \ Z_q(\beta_i)}{\sum_{j=1}^M \omega(\beta_j) \ Z_q(\beta_j)}.$$

3 Can we learn
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• The equations of motion are,

$$d\boldsymbol{q} = \boldsymbol{m}^{-1}\boldsymbol{\rho} \, dt,$$

$$d\boldsymbol{p} = -\beta^{-1}\hat{\beta}(t, V(\boldsymbol{q}))\nabla V \, dt - \gamma \boldsymbol{\rho} \, dt + \sqrt{2\gamma\beta^{-1}m} \, dW_{\boldsymbol{\rho}}$$

• We need to calculate the following force re-scaling

$$\hat{\beta}(t, V(q)) = \frac{\int_{\beta_{\min}}^{\beta_{\max}} \beta_c \,\omega(t, \beta_c) \, e^{-\beta_c \, V(q)} \, \mathrm{d}\beta_c}{\int_{\beta_{\min}}^{\beta_{\max}} \omega(t, \beta_c) \, e^{-\beta_c \, V(q)} \, \mathrm{d}\beta_c}$$

• We therefore discretise $[\beta_{\min}, \beta_{\max}]$ with the aim of calculating $\hat{\beta}(t, V(q))$



In standard Simulated Tempering

$$\mathbb{E}_{\beta_c}\left[A\right] = \lim_{T \to \infty} \frac{1}{T} \int_0^T A(q(t)) \mathbb{1}_{\beta_c} \, \mathrm{d}t$$

• We instead use a reweighting of the entire trajectory (importance sampling),

$$\mathbb{E}_{\beta_c}\left[A\right] = \lim_{T \to \infty} \frac{1}{T} \int_0^T A(q(t)) W_{\beta_c}(t, q(t)) \, \mathrm{d}t$$

where,

$$W_{eta_c}(t,q) = rac{z^{-1}(t,eta_c)}{\int_{eta_{\min}}^{eta_{\max}} \omega(t,eta_c') e^{-(eta_c'-eta_c)V(q)} deta_c'}$$

where $z(t, \beta_c)$ is the estimate of $Z_q(\beta_c)$ at time *t*.

Numerical Experiments : Part 1



Curie Weiss Magnet - mean field Isings model



Curie Weiss Magnet







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- Molecular Integration Simulation Toolkit (MIST) ⁴ integrates with Amber 14, GROMACS 5.0.2, NAMD-Lite 2.0.3, LAMMPS
- In vacuum, using Gromacs with MIST⁵
- Measure RMSD and radius of gyration, *r_g*, from initial helix state ⁴Bethune et. al. *MIST: A Simple and Efficient Molecular Dynamics Abstraction Library for Integrator Development*, **Computer Physics Communications**, 2018 ⁵https://bitbucket.org/extasy-project/mist/wiki/Home

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Alanine-12: LD vs ST vs ISST





⁶Bethune et. al., 2018

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Alanine-12: LD vs ISST





⁷Bethune et. al., 2018

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Infinite Switch ST

Oaxaca 27 / 28



- Operate ST in the Infinite Switch limit, with adaptive weight learning – without temperature being a dynamical variable ⁸
- We have presented work on MD, future work is looking into applying the method in data science and ML
- We have implemented the method in MIST and it is available to download at https://bitbucket.org/extasy-project/mist/wiki/Home

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⁸Anton Martinsson, Jianfeng Lu, Ben Leimkuhler, Eric Vanden-Eijnden, Simulated Tempering Method in the Infinite Switch Limit with Adaptive Weight Learning, to appear in JSTAT, 2018

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